

# Linear Algebra - Part 2 Linear systems, linear least-squares

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• Linear equation

$$a_1x_1 + a_2x_2 + \dots + a_nx_n = b$$
  

$$x_1, \dots, x_n : \text{variables}$$
  

$$b \text{ and } a_1, \dots, a_n : \text{ constant real (or complex) numbers}$$

• Linear system (a system of linear equations)

$$a_{11}x_1 + a_{12}x_2 + a_{13}x_3 + \dots = b_1$$
  

$$a_{21}x_1 + a_{22}x_2 + a_{23}x_3 + \dots = b_2$$
  

$$a_{31}x_1 + a_{32}x_2 + a_{33}x_3 + \dots = b_3$$
  
.



• Solution of a linear system

- A list of numbers satisfying each equation

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:



• Solution of a linear system

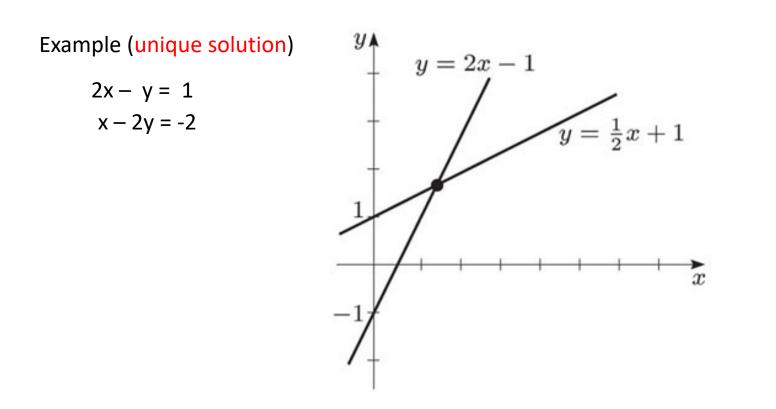
A list of numbers satisfying each equation

Example

2x - y = 1x - 2y = -2



- Solution of a linear system
  - A list of numbers satisfying each equation





- Solution of a linear system
  - A list of numbers satisfying each equation
- Solution set
  - The set of all possible solutions

Example

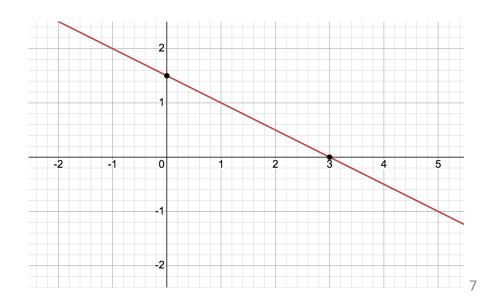
x + 2y = 3



- Solution of a linear system
  - A list of numbers satisfying each equation
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Example (infinite number of solutions)

x + 2y = 3





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Example

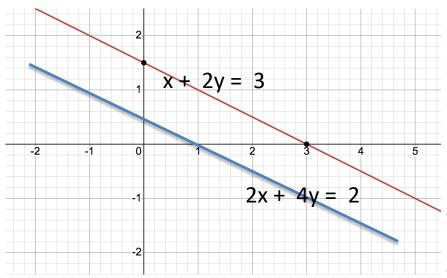
x + 2y = 32x + 4y = 2



- Solution of a linear system
  - A list of numbers satisfying each equation
- Solution set
  - The set of all possible solutions

Example (no solution)

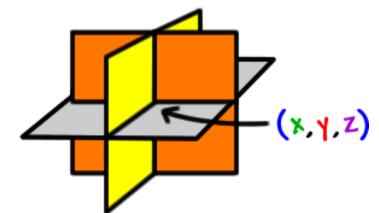
$$x + 2y = 3$$
  
 $2x + 4y = 2$ 





- A system of linear equations has
  - no solution, or
  - exactly one solution, or
  - infinitely many solutions.
- A system of linear equations is **consistent** 
  - One solution or infinitely many solutions
- A system of linear equations is **inconsistent** 
  - No solution

- Does a system of linear equations have
  - no solution, or
  - exactly one solution, or
  - infinitely many solutions ?
- If unique solution, what is it?









• Without/With matrix notation



- Without matrix notation
  - Row transformation: elimination

$$x_{1} - 2x_{2} + x_{3} = 0 \quad ----(1)$$
$$2x_{2} - 8x_{3} = 8 \quad ----(2)$$
$$-4x_{1} + 5x_{2} + 9x_{3} = -9, \quad ----(3)$$



- Without matrix notation
  - Row transformation: elimination

$$x_{1} - 2x_{2} + x_{3} = 0 \quad ---(1) \qquad x_{1} - 2x_{2} + x_{3} = 0 \quad ---(1)$$
  

$$2x_{2} - 8x_{3} = 8 \quad ---(2) \qquad \implies \qquad 2x_{2} - 8x_{3} = 8 \quad ---(2)$$
  

$$-4x_{1} + 5x_{2} + 9x_{3} = -9, \quad ---(3) \qquad \qquad -3x_{2} + 13x_{3} = -9 \quad ---(3)$$
  

$$(1) * 4 + (3)$$



- Without matrix notation
  - Row transformation: elimination

$$x_{1} - 2x_{2} + x_{3} = 0 \quad \dots \quad (1) \qquad x_{1} - 2x_{2} + x_{3} = 0 \quad \dots \quad (1)$$

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$$(1) * 4 + (3)$$

$$x_{1} - 2x_{2} + x_{3} = 0 \quad ---(1)$$

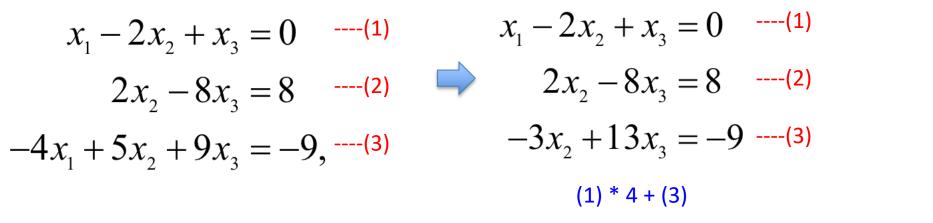
$$2x_{2} - 8x_{3} = 8 \quad ---(2)$$

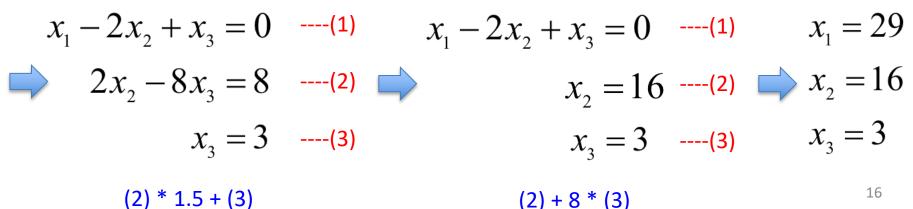
$$x_{3} = 3 \quad ---(3)$$

$$(2) * 1.5 + (3)$$



- Without matrix notation
  - Row transformation: elimination







• Matrix notation



- Matrix notation
  - Coefficient matrix

$$x_1 - 2x_2 + x_3 = 0$$
  
$$2x_2 - 8x_3 = 8$$
  
$$-4x_1 + 5x_2 + 9x_3 = -9,$$

$$A = \begin{bmatrix} 1 & -2 & 1 \\ 0 & 2 & -8 \\ -4 & 5 & 9 \end{bmatrix} \qquad \mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \qquad \mathbf{b} = \begin{bmatrix} 0 \\ 8 \\ -9 \end{bmatrix}$$

A **x=b** 



- Gaussian elimination
- Matrix inversion

$$A = \begin{bmatrix} 1 & -2 & 1 \\ 0 & 2 & -8 \\ -4 & 5 & 9 \end{bmatrix} \qquad \mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \qquad \mathbf{b} = \begin{bmatrix} 0 \\ 8 \\ -9 \end{bmatrix}$$

A **x=b** 



- Gaussian elimination
  - Strategy: find an equivalent system easier to solve





• Augmented matrix

A **x**=**b**, where 
$$A = \begin{bmatrix} 1 & -2 & 1 \\ 0 & 2 & -8 \\ -4 & 5 & 9 \end{bmatrix} \mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \mathbf{b} = \begin{bmatrix} 0 \\ 8 \\ -9 \end{bmatrix}$$
$$\begin{bmatrix} 1 & -2 & 1 & 0 \\ 0 & 2 & -8 & 8 \\ -4 & 5 & 9 & -9 \end{bmatrix}$$



- Gaussian elimination
  - Elementary row operations
    - **Replacement:** Replace one row by the sum of itself and a multiple of another row.
    - Interchange: Interchange two rows.
    - **Scaling:** Multiply all entries in a row by a nonzero constant.



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$$\begin{bmatrix} 1 & -2 & 1 & 0 \\ 0 & 2 & -8 & 8 \\ -4 & 5 & 9 & -9 \end{bmatrix} \xrightarrow{\text{----(1)}}$$



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$$\begin{bmatrix} 1 & -2 & 1 & 0 \\ 0 & 2 & -8 & 8 \\ -4 & 5 & 9 & -9 \end{bmatrix} \xrightarrow{\text{---(1)}} (1)^{*} (4+(3) -> (3)) \begin{bmatrix} 1 & -2 & 1 & 0 \\ 0 & 2 & -8 & 8 \\ 0 & -3 & 13 & -9 \end{bmatrix}$$



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$$(2)^{*3+(3)} \rightarrow (3) \begin{bmatrix} 1 & -2 & 1 & 0 \\ 0 & 1 & -4 & 4 \\ 0 & 0 & 1 & 3 \end{bmatrix}$$



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    - **Replacement:** Replace one row by the sum of itself and a multiple of another row.
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$$\begin{bmatrix} 1 & -2 & 1 & 0 \\ 0 & 2 & -8 & 8 \\ -4 & 5 & 9 & -9 \end{bmatrix} \xrightarrow{--.(1)} = \begin{bmatrix} 1 & -2 & 1 & 0 \\ 0 & 2 & -8 & 8 \\ 0 & -3 & 13 & -9 \end{bmatrix} \xrightarrow{(2)*1/2 \to (2)} \begin{bmatrix} 1 & -2 & 1 & 0 \\ 0 & 1 & -4 & 4 \\ 0 & -3 & 13 & -9 \end{bmatrix}$$

$$(2)*3+(3) \to (3) \begin{bmatrix} 1 & -2 & 1 & 0 \\ 0 & 1 & -4 & 4 \\ 0 & 0 & 1 & 3 \end{bmatrix} \xrightarrow{(1)-(3) \to (1)} \begin{bmatrix} 1 & -2 & 0 & -3 \\ (2)+4^*(3) \to (2) \\ \hline & & & & & & \\ 0 & 0 & 1 & 3 \end{bmatrix} \xrightarrow{(1)-(3) \to (2)} \begin{bmatrix} 1 & -2 & 0 & -3 \\ 0 & 1 & 0 & 16 \\ 0 & 0 & 1 & 3 \end{bmatrix}$$



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• Gaussian elimination



• Gaussian elimination

 $\begin{bmatrix} 1 & 0 & 0 & 29 \\ 0 & 1 & 0 & 16 \\ 0 & 0 & 1 & 3 \end{bmatrix} \qquad \mathbf{I} \mathbf{X} = \begin{bmatrix} 29 \\ 16 \\ 3 \end{bmatrix}$ 

<b>x</b> =		$x_1 = 29$
<b>x</b> =	<i>x</i> <sub>2</sub>	$x_2 = 16$
	[ <i>x</i> <sub>3</sub> ]	$x_{3} = 3$

 $x_{1} - 2x_{2} + x_{3} = 0$   $2x_{2} - 8x_{3} = 8$   $-4x_{1} + 5x_{2} + 9x_{3} = -9,$  (29) - 2(16) + (3) = 29 - 32 + 3 = 0 2(16) - 8(3) = 32 - 24 = 8 -4(29) + 5(16) + 9(3) = -116 + 80 + 27 = -9



Gaussian elimination

$$\begin{bmatrix} 1 & -2 & 1 & 0 \\ 0 & 2 & -8 & 8 \\ -4 & 5 & 9 & -9 \end{bmatrix}$$

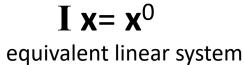
original augmented matrix

 $\begin{bmatrix} 1 & 0 & 0 & 29 \\ 0 & 1 & 0 & 16 \\ 0 & 0 & 1 & 3 \end{bmatrix}$ 

transformed augmented matrix

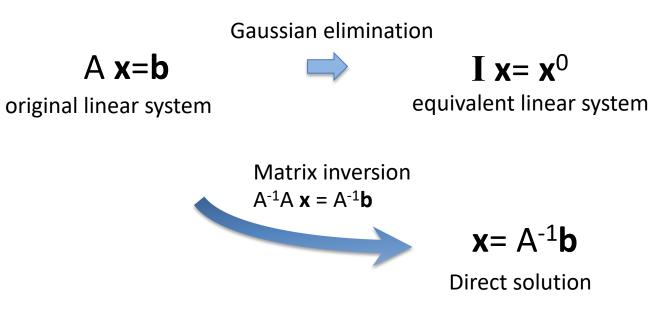
A **x=b** 

original linear system



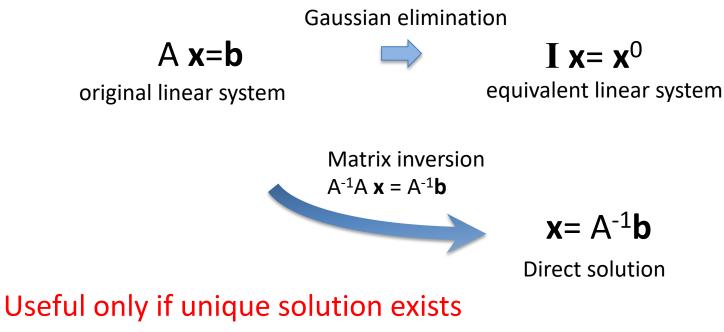


- Gaussian elimination
- Matrix inversion





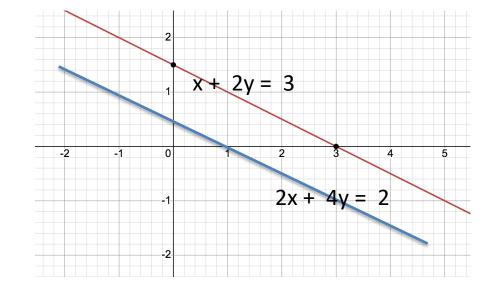
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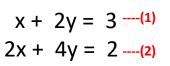


Gain insights before you solve



- Two fundamental questions
  - Existence: Is the system consistent (does at least one solution *exist*)?
  - Uniqueness: If a solution exists, is it the only one?







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x + 2y = 12x + 4y = 2



• Non-square systems

$$A_{m \times n} \mathbf{x} = \mathbf{b} \quad (\mathbf{m} \neq \mathbf{n})$$

- Underdetermined if m < n</li>
  - "more unknowns than equations"
  - If any two equations are not consistent: no solution
  - If all pairs of equations are consistent: infinite number of solutions

#### - Overdetermined if m>n

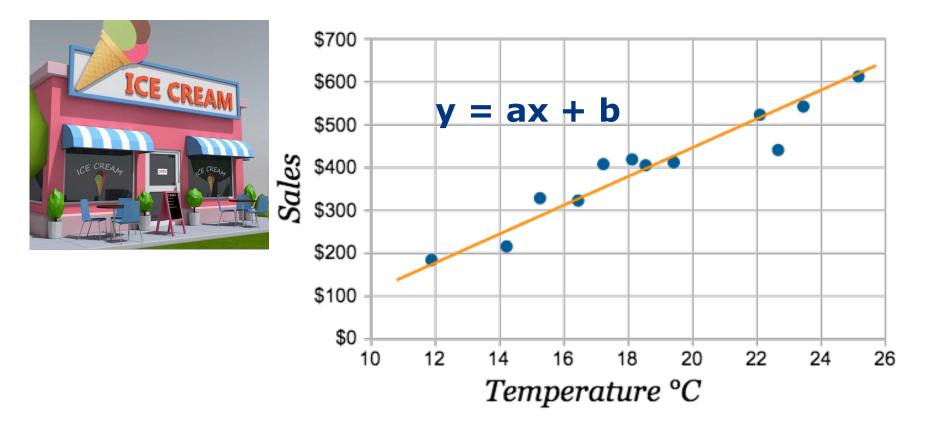
- "more equations than unknowns"
- Usually has no solution, but people may want the "best approximate solution"



- Fit a mathematical model to data
  - Idealized value of the model for any data is linearly in term of the unknown parameters
  - The fitted model summarizes data, can predict unobserved values

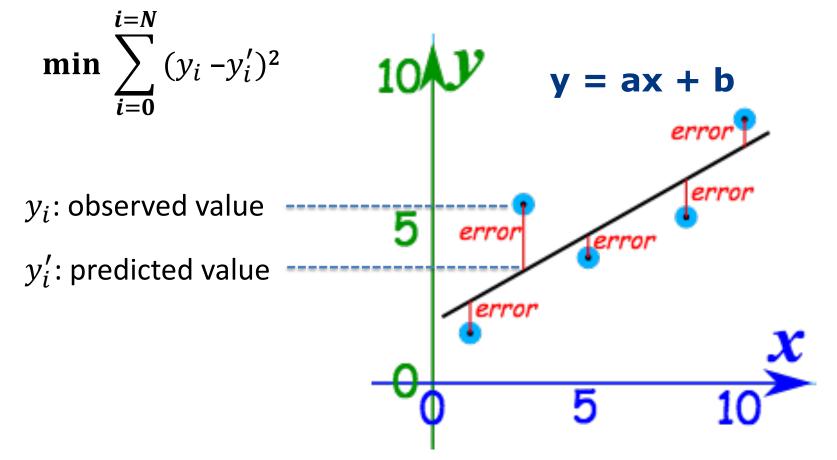


• Fit a mathematical model to data



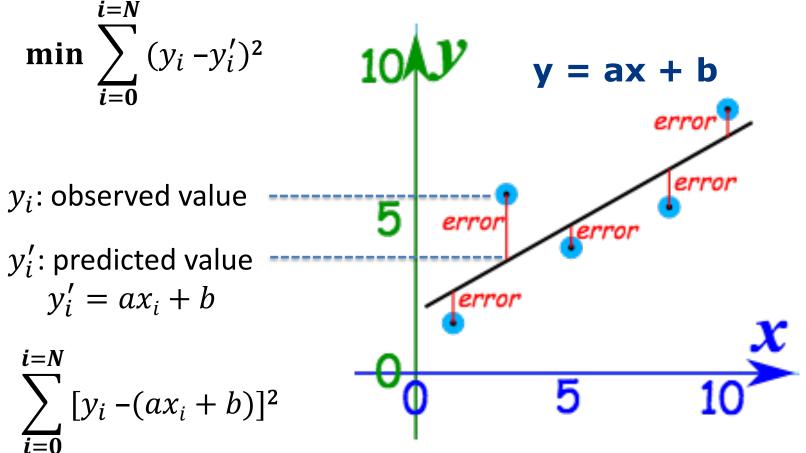


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...

• Equivalent to solving the overdetermined linear system

$$y_1 - (ax_1 + b) = 0$$
  

$$y_2 - (ax_2 + b) = 0$$
  

$$y_3 - (ax_3 + b) = 0$$
  
 $N \ge 2$ 



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 $N \ge 2$ 

• Solve it

 $A\mathbf{x} = \mathbf{b} \implies A^T A \mathbf{x} = A^T \mathbf{b} \implies \mathbf{x} = (A^T A)^{-1} A^T b$ 

# Other methods



- Row transformation w/o matrix notation
- Gaussian elimination
- Direct method  $\mathbf{x} = A^{-1} b$
- Many other methods
  - LU decomposition

 A00
 A01
 A02

 A10
 A11
 A12

 A20
 A21
 A22

- Cholesky decomposition

$$\mathbf{A} = \mathbf{L}\mathbf{L}^T = egin{pmatrix} L_{11} & 0 & 0 \ L_{21} & L_{22} & 0 \ L_{31} & L_{32} & L_{33} \end{pmatrix} egin{pmatrix} L_{11} & L_{21} & L_{31} \ 0 & L_{22} & L_{32} \ 0 & 0 & L_{33} \end{pmatrix}_{45}$$

# Assignment (part 2)



- System of linear equations
- Linear least squares
  - Use any programming language/tools
  - Use any third party libraries/software





# Part 3: Eigen values/vectors, singular value decomposition