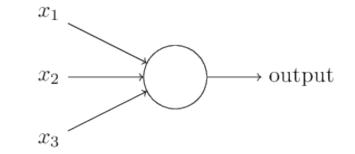
## Neural Networks

Nail Ibrahimli

Perceptron - a.k.a. single neuron

A perceptron takes multiple inputs (e.g.: x1, x2, x3) and produces a single binary output.



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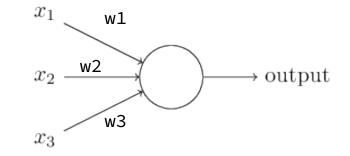
$$\begin{array}{c} x_1 & \texttt{w1} \\ x_2 & \underbrace{\texttt{w2}} \\ x_3 & \underbrace{\texttt{w3}} \end{array} \rightarrow \texttt{output}$$

$$ext{output} = egin{cases} 0 & ext{if } \sum_j w_j x_j \leq ext{ threshold} \ 1 & ext{if } \sum_j w_j x_j > ext{ threshold} \end{cases}$$

That's all there is to how a perceptron works!

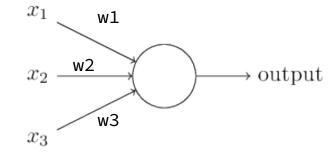
Perceptron - a.k.a. single neuron

X1: Is the weather good?X2: Am I going with friend?X3: Is the venue easy to commute?



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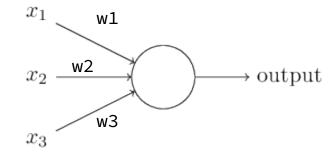


Let's say:

You don't mind that much going alone (X2), and since it is at the Weekend you don't mind that much to commute for longer(X3). But you hate bad weather and you would rather stay at home in bad weather(X1).

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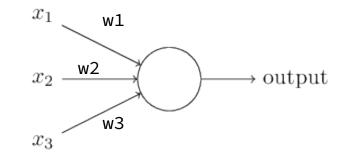
w1 = 6, w2 = w3 = 2

Perceptron - a.k.a. single neuron

X1: Is the weather good?X2: Am I going with friend?X3: Is the venue easy to commute?

w1 = 6, w2 = w3 = 2

What would happen if threshold = 5?



 $ext{output} = egin{cases} 0 & ext{if } \sum_j w_j x_j \leq ext{ threshold} \ 1 & ext{if } \sum_j w_j x_j > ext{ threshold} \end{cases}$ 

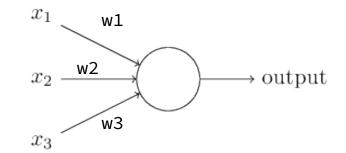
Perceptron - a.k.a. single neuron

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w1 = 6, w2 = w3 = 2

What would happen if threshold = 5?

What would happen if threshold = 3?

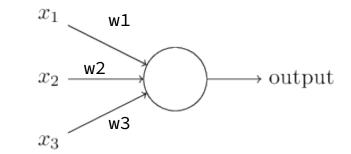


 $ext{output} = egin{cases} 0 & ext{if } \sum_j w_j x_j \leq ext{ threshold} \ 1 & ext{if } \sum_j w_j x_j > ext{ threshold} \end{cases}$ 

Perceptron - a.k.a. single neuron

We can rewrite weighted sum as an inner product of two vectors.

$$\sum_{j} w_{j} x_{j} = w \cdot x$$



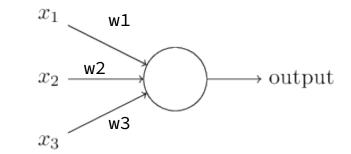
We can assume that b = -threshold.

$$ext{output} = egin{cases} 0 & ext{if } \sum_j w_j x_j \leq ext{ threshold} \ 1 & ext{if } \sum_j w_j x_j > ext{ threshold} \ \end{cases}$$

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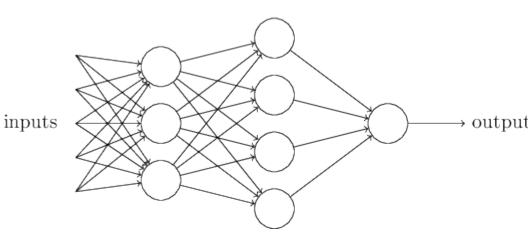
We can assume that b = -threshold.

$$ext{output} = egin{cases} 0 & ext{if } w \cdot x + b \leq 0 \ 1 & ext{if } w \cdot x + b > 0 \end{cases}$$

Layers of Perceptrons

First layer:

Making simple three decisions by weighing inputs



Second layer:

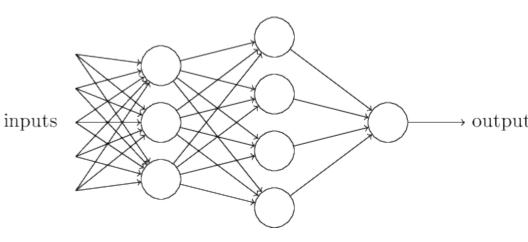
Making four decisions by weighing up the results from first layer decisions making

Using multiple layers of perceptrons, neural networks can make more sophisticated decisions

Layers of Perceptrons

First layer:

Making simple three decisions by weighing inputs



Second layer:

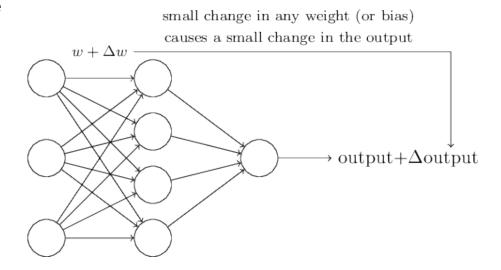
Making four decisions by weighing up the results from first layer decisions making

Using multiple layers of perceptrons, neural networks can make more sophisticated decisions.

But how we set the weights (and biases)?

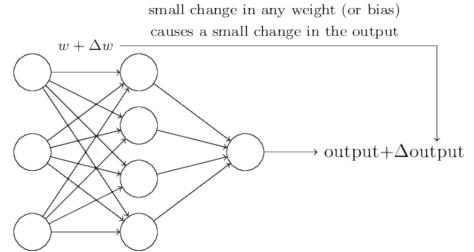
Neural Networks

1. Suppose that we know how small change in weights changes the output.



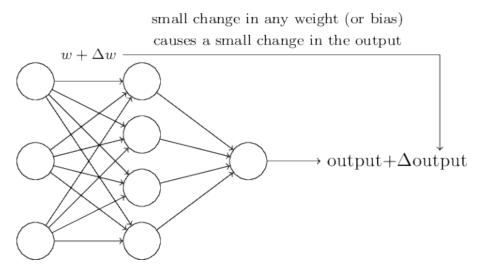
Neural Networks

- 1. Suppose that we know how small change in weights changes the output.
- 2. Starting with random initialization we can iteratively update (supervise) the weights with small changes to bring the output to expected value.

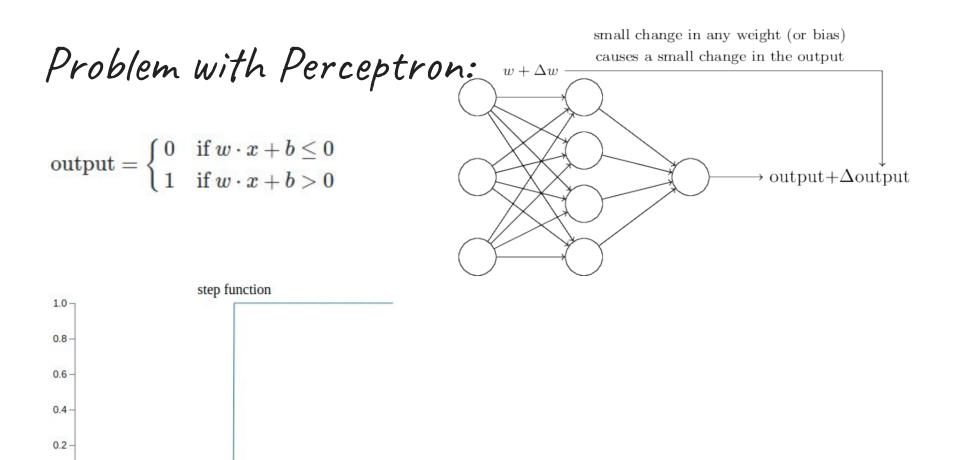


Neural Networks

- 1. Suppose that we know how small change in weights changes the output.
- 2. Starting with random initialization we can iteratively update (supervise) the weights with small changes to bring the output to expected value.
- 3. We control the learning process, by testing and validating it with data that were not used while weight optimization.



Problem with Perceptron: 
$$w + \Delta w$$
  
output = 
$$\begin{cases} 0 & \text{if } w \cdot x + b \leq 0 \\ 1 & \text{if } w \cdot x + b > 0 \end{cases}$$
small change in any weight (or bias)  
causes a small change in the output  
 $w + \Delta w$   
 $w + \Delta w$ 



0.0

-4

-3

-2

-1

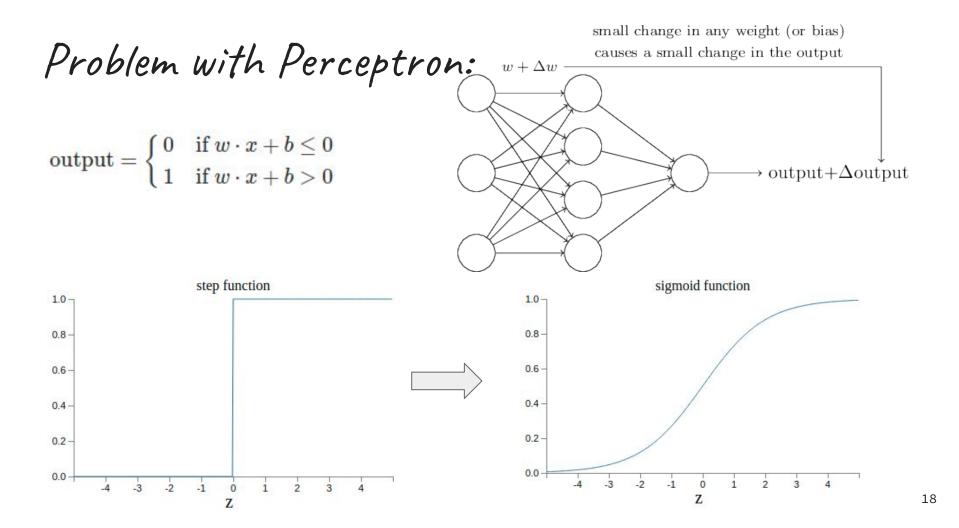
0

Z

1

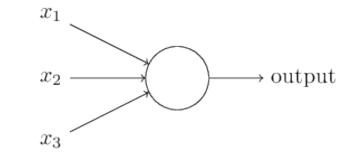
2

3



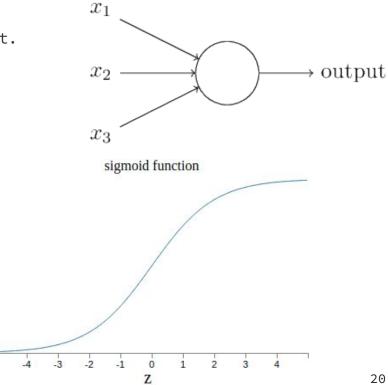
Sigmoid Neuron

A perceptron sigmoid neuron takes multiple inputs (e.g.: x1, x2, x3) and produces a single <del>binary</del> output.



Sigmoid Neuron

A perceptron sigmoid neuron takes multiple inputs (e.g.: x1, x2, x3) and produces a single <del>binary</del> output.



1.0 -

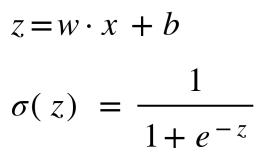
0.8

0.6

0.4 -

0.2

0.0 -

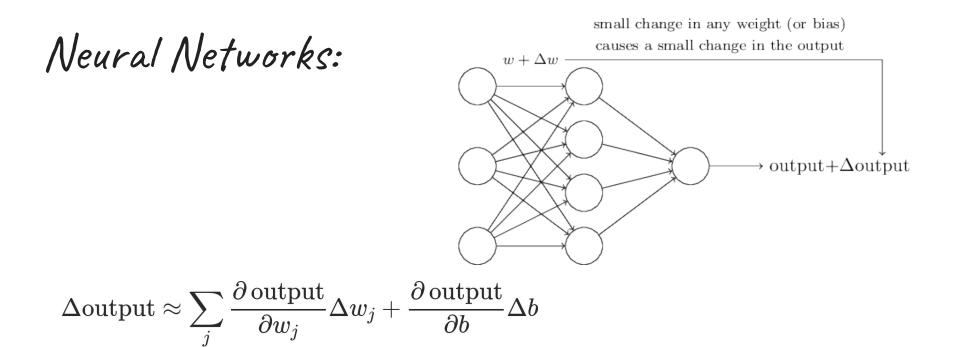


First order Taylor approximation (Quick Lookup)

Let's say we have function f, and value c, for which function output value of f(c) is known.

For x in neighborhood of c, output value f(x) can be approximated as:

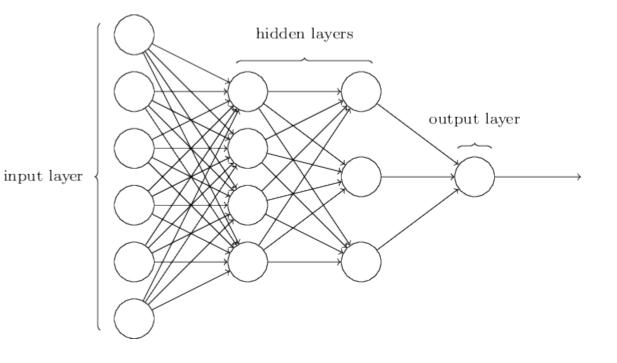
```
f(x) \approx f'(c)(x-c)+f(c)f(x) - f(c) \approx f'(c)(x-c)\Delta f \approx f'(c) \Delta x
```



## Feedforward Network architecture

3 layers: Input Hidden

Output



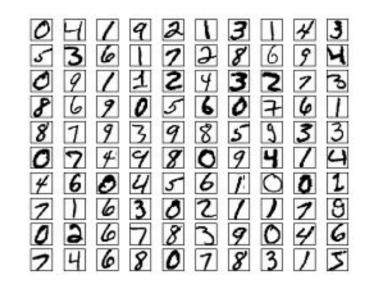
Recognizing Digits with Neural Nets.

MNIST Data:

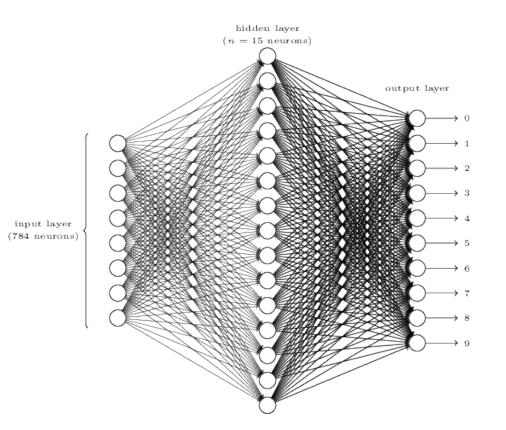
28x28 images

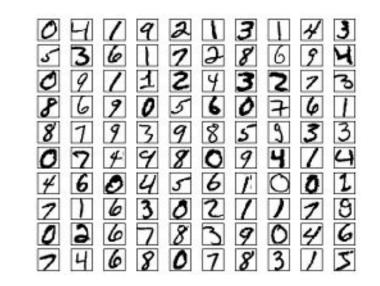
Greyscale (single channel)

Goal: classifying/recognizing images.

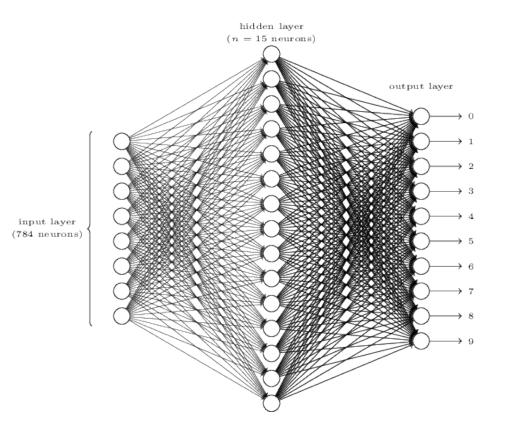


Recognizing Digits with Neural Nets.





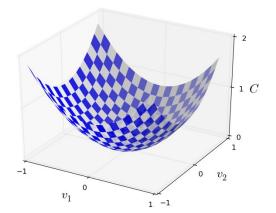
Recognizing Digits with Neural Nets.



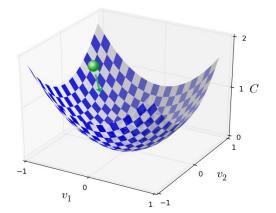
For x representing digit 6:  $y(x) = (0, 0, 0, 0, 0, 0, 1, 0, 0, 0)^T$ 

$$C(w,b) \equiv \frac{1}{2n} \sum_{x} \|y(x) - a\|^2$$

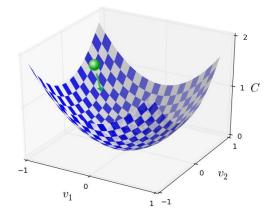
Learning with gradient descent



Learning with gradient descent

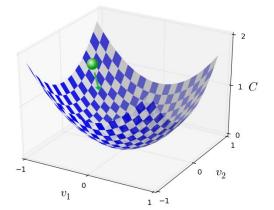


Learning with gradient descent



 $\Delta C pprox rac{\partial C}{\partial v_1} \Delta v_1 + rac{\partial C}{\partial v_2} \Delta v_2$ 

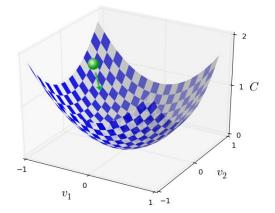
Learning with gradient descent



$$egin{aligned} \Delta C &pprox rac{\partial C}{\partial v_1} \Delta v_1 + rac{\partial C}{\partial v_2} \Delta v_2 \ &\Delta C &pprox 
abla C \cdot \Delta v \end{aligned}$$

$$abla C \equiv \left(rac{\partial C}{\partial v_1},rac{\partial C}{\partial v_2}
ight)^T$$

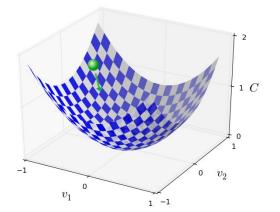
Learning with gradient descent



$$egin{aligned} \Delta C &pprox rac{\partial C}{\partial v_1} \Delta v_1 + rac{\partial C}{\partial v_2} \Delta v_2 \ &\Delta C &pprox 
abla C &pprox 
abla C & \cdot \Delta v \ &\Delta v &= -\eta 
abla C \ &v & o v' = v - \eta 
abla C \end{aligned}$$

$$abla C \equiv \left(rac{\partial C}{\partial v_1},rac{\partial C}{\partial v_2}
ight)^T$$

Learning with gradient descent

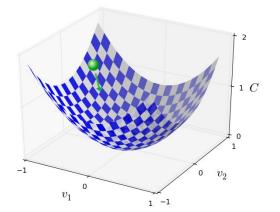


$$abla C \equiv \left(rac{\partial C}{\partial v_1}, \dots, rac{\partial C}{\partial v_m}
ight)^T$$

 $\Delta C \approx \nabla C \cdot \Delta v$ 

$$\Delta v = -\eta 
abla C$$
 $v o v' = v - \eta 
abla C$ 

Learning with gradient descent

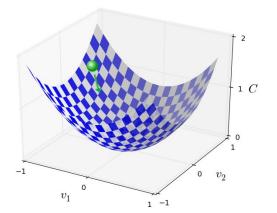


$$abla C \equiv \left(rac{\partial C}{\partial v_1}, \dots, rac{\partial C}{\partial v_m}
ight)^T$$

 $\Delta C \approx \nabla C \cdot \Delta v$ 

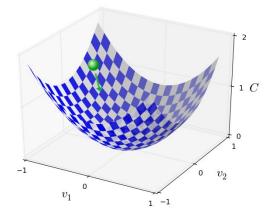
$$\Delta v = -\eta 
abla C$$
 $v o v' = v - \eta 
abla C$ 

NN with gradient descent



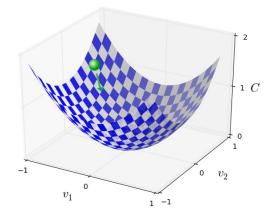
$$egin{aligned} w_k &
ightarrow w_k' = w_k - \eta rac{\partial C}{\partial w_k} \ b_l &
ightarrow b_l' = b_l - \eta rac{\partial C}{\partial b_l}. \end{aligned}$$

## Stochastic Gradient Descent



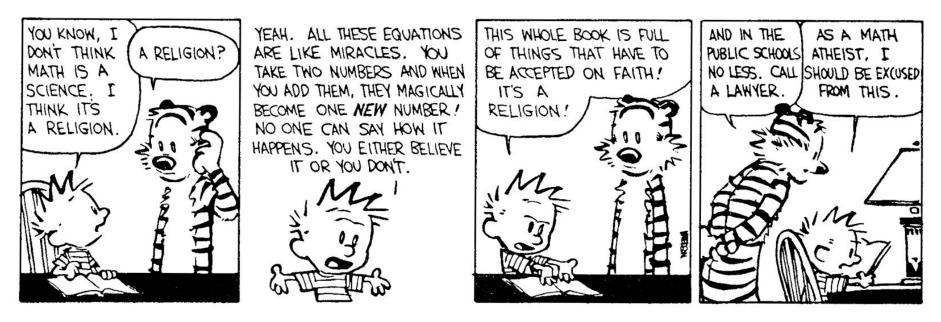
$$egin{aligned} C_x &\equiv rac{\|y(x)-a\|^2}{2} \ C &= rac{1}{n}\sum_x C_x \ 
abla C &= rac{1}{n}\sum_x 
abla C \ 
abla C \ 
abla C &= rac{1}{n}\sum_x 
abla C \ 
abla C \$$

## Stochastic Gradient Descent

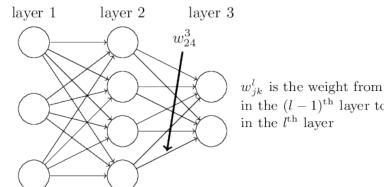


$$egin{aligned} C_x &\equiv rac{\|y(x)-a\|^2}{2} \ C &= rac{1}{n}\sum_x C_x \ 
abla C &= rac{1}{n}\sum_x \nabla C_x \ 
abla C &= rac{1}{n}\sum_x 
abla C_x \ rac{\sum_{j=1}^m 
abla C_{X_j}}{m} &pprox rac{\sum_x 
abla C_x}{n} = 
abla C \ w_k &
ightarrow w_k' = w_k - rac{\eta}{m}\sum_j rac{\partial C_{X_j}}{\partial w_k} \ b_l &
ightarrow b_l' = b_l - rac{\eta}{m}\sum_j rac{\partial C_{X_j}}{\partial b_l}, \end{aligned}$$

BackPropagation

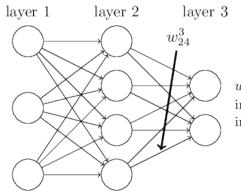


BackPropagation: Notation

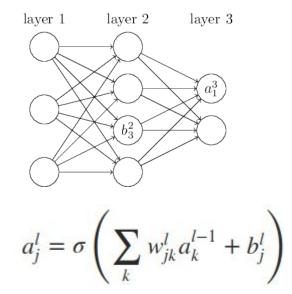


 $w_{ik}^{l}$  is the weight from the  $k^{\text{th}}$  neuron in the  $(l-1)^{\text{th}}$  layer to the  $j^{\text{th}}$  neuron

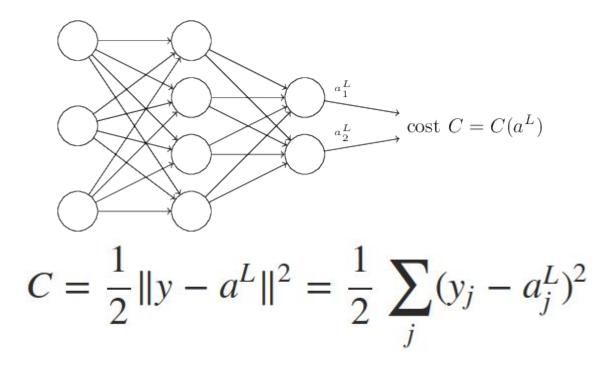
BackPropagation: Notation



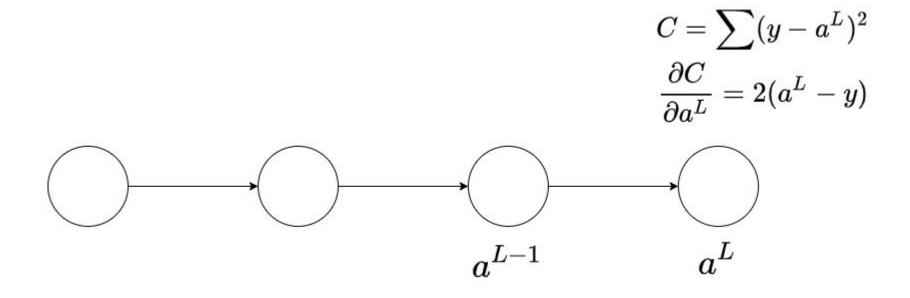
 $w_{jk}^{l}$  is the weight from the  $k^{\text{th}}$  neuron in the  $(l-1)^{\text{th}}$  layer to the  $j^{\text{th}}$  neuron in the  $l^{\text{th}}$  layer



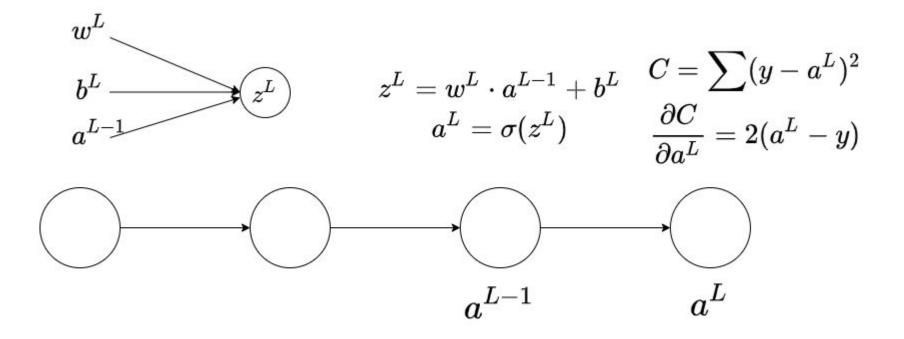
BackPropagation: Cost function



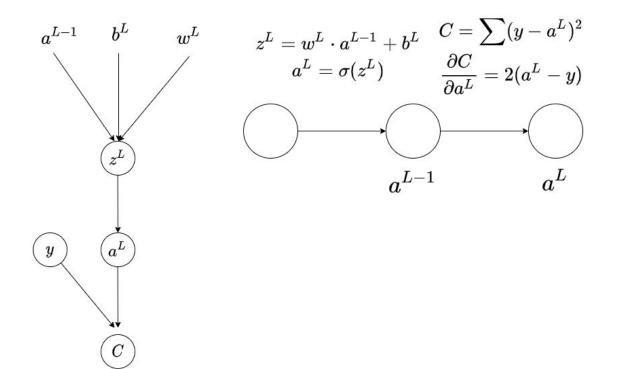
BackPropagation



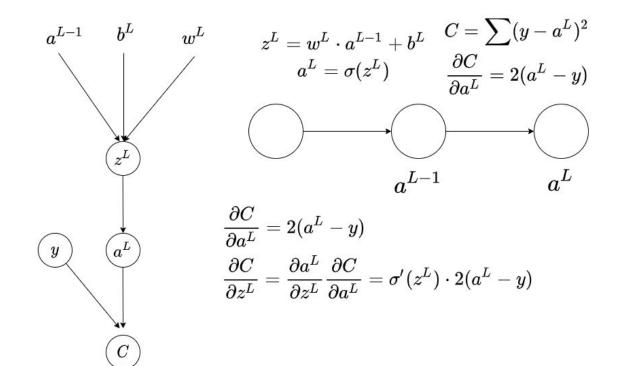
BackPropagation



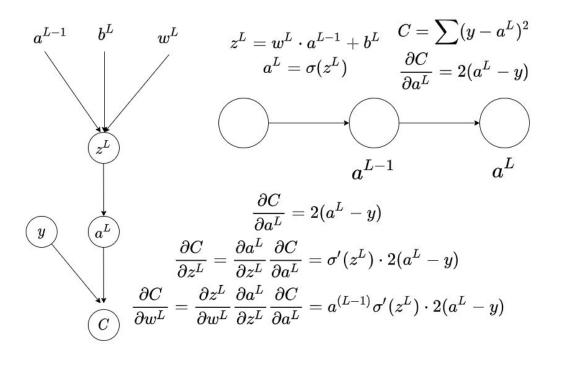
BackPropagation



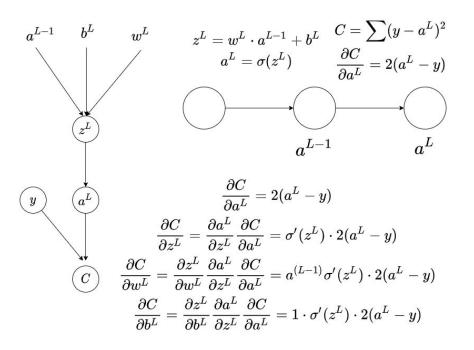
BackPropagation



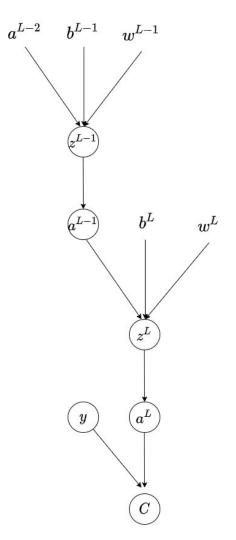
BackPropagation



BackPropagation



BackPropagation



BackPropagation

$$\begin{aligned} \frac{\partial C}{\partial a^{L}} &= 2(a^{L} - y) \\ \frac{\partial C}{\partial z^{L}} &= \frac{\partial a^{L}}{\partial z^{L}} \frac{\partial C}{\partial a^{L}} = \sigma'(z^{L}) \cdot 2(a^{L} - y) \\ \frac{\partial C}{\partial w^{L-1}} &= \frac{\partial z^{L-1}}{\partial w^{L-1}} \cdot \frac{\partial z^{L}}{\partial a^{L-1}} \cdot \frac{\partial C}{\partial z^{L}} = a^{L-2} \cdot \sigma'(z^{L-1}) \cdot w^{(L)} \cdot \frac{\partial C}{\partial z^{L}} \\ \frac{\partial C}{\partial b^{L-1}} &= \frac{\partial z^{L-1}}{\partial b^{L-1}} \cdot \frac{\partial a^{L-1}}{\partial z^{L-1}} \cdot \frac{\partial C}{\partial z^{L}} = \sigma'(z^{L-1}) \cdot w^{(L)} \cdot \frac{\partial C}{\partial z^{L}} \\ \frac{\partial C}{\partial b^{L-1}} &= \frac{\partial z^{L-1}}{\partial b^{L-1}} \cdot \frac{\partial z^{L}}{\partial a^{L-1}} \cdot \frac{\partial C}{\partial z^{L}} = \sigma'(z^{L-1}) \cdot w^{(L)} \cdot \frac{\partial C}{\partial z^{L}} \\ \frac{\partial C}{\partial b^{L-1}} &= \frac{\partial z^{L-1}}{\partial b^{L-1}} \cdot \frac{\partial z^{L}}{\partial a^{L-1}} \cdot \frac{\partial C}{\partial z^{L}} = \sigma'(z^{L-1}) \cdot w^{(L)} \cdot \frac{\partial C}{\partial z^{L}} \\ \end{array}$$