GEO5017 Machine Learning for the Built Environment



Department of Urbanism Faculty of Architecture and the Built Environment Delft University of Technology

Lecture Support Vector Machine

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Today's Agenda



• Previous Lecture: Classification

- Support Vector Machine
 - Standard SVM
 - Soft Margin SVM

• SVM Applications

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• We usually have a set of input data represented as feature vectors:

$$\boldsymbol{x} = (x_1, x_2, x_3 \dots x_p)^T$$

 Classification aims to specify which category/class y some input data x belong to



• An example of point cloud semantic classification



 $x = (x, y, z, r, g, b, intensity ...)^T$ y: High vegetation Low vegetation Building Road Grass land



- Two classification approaches:
 - Generative approach: model the probability distribution of feature \boldsymbol{x} and label \boldsymbol{y}
 - Bayes classifier
 - Gaussian mixture model
 - Discriminative approach: model a function that directly map from feature x to label y
 - Linear classifier (Fisher, Logistic regression, SVM)
 - Non-linear classifier (Decision tree, Neural networks)



- Many classification or regression problems can be specified as:
 - Find a suitable model / hypothesis
 - Define a loss function (i.e., least squares, maximum likelihood ...)
 - Feed the data samples into the model and search for the model parameters that cause the least loss



- Standard linear (Fisher) classifier:
 - Hypothesis: the decision boundary is a linear model of the input vector x:

$$w^T x + b = 0$$

- Loss Function: least squares
- Logistic regression:
 - Hypothesis: the posterior probability is a logistic sigmoid of a linear function of \pmb{x}

$$P(y|\mathbf{x}) = \sigma(\mathbf{w}^T\mathbf{x} + b)$$

• Loss Function: maximum likelihood

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SVM Applications

• We consider two-class (+1, -1) linearly separable task

• Constrain the weights so that the output is always larger than 1 or smaller than -1

$$\begin{cases} \mathbf{w}^T \mathbf{x}_i + b \ge +1 & if \quad y_i = +1 \\ \mathbf{w}^T \mathbf{x}_i + b \le -1 & if \quad y_i = -1 \end{cases}$$



 Given a set of data samples, we aim to find a decision boundary for the input vector space:

$$g(\mathbf{x}) = \mathbf{w}^T \mathbf{x} + b = 0$$





Negative class



Such a decision boundary is not unique





- The goal of SVM is to find a decision boundary that gives the maximum possible margin ρ



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• What is the margin ρ ?



• w is orthogonal to the line

$$w^T(x_2 - x_1) = 0$$

ρ/2 is the projection of (x1, x3) over w

$$\rho/2 = \frac{w^T(x_3 - x_1)}{\|w\|} = \frac{1}{\|w\|}$$







• What is optimization

- Discrete options
 - Choose a brand of milk
 - Choose where to rent
 - Choose to study or to browse facebook this afternoon

• Continuous space

- What is optimization?
 - A goal (i.e., maximization, minimization)
 - Some constraints
 - Sometimes constraints might be compromised to achieve the goal

• SVM optimization problem:

$$\min \frac{1}{2} \| \boldsymbol{w} \|^{2}$$

s.t. $y_{i} (\boldsymbol{w}^{T} \boldsymbol{x}_{i} + b) - 1 \ge 0, \forall i = 1, 2, 3, ..., n$

• A constrained optimization problem can often be solved with Lagrangian (this will not be asked in the exam)

$$L(\boldsymbol{w}, \lambda) = \frac{1}{2} \|\boldsymbol{w}\|^2 - \sum_{i=1}^n \lambda_i (y_i (\boldsymbol{w}^T \boldsymbol{x}_i + b) - 1)$$

• Computing the derivative and making it to 0 we get:

$$\frac{\partial L(\boldsymbol{w}, \lambda)}{\partial \boldsymbol{w}} = \boldsymbol{w} - \sum_{i=1}^{n} \lambda_i y_i \boldsymbol{x}_i = \boldsymbol{0}$$
$$\boldsymbol{w} = \sum_{i=1}^{n} \lambda_i y_i \boldsymbol{x}_i$$

• Solving λ_i requires Quadratic programming and thus is not covered in this lecture

$$\boldsymbol{w} = \sum_{i=1}^n \lambda_i y_i \boldsymbol{x_i}$$

- After solving the problem, a lot of λ_i becomes 0
- Only the objects x_i with non-zero λ_i contribute to w
- These objects are called the "support vector"

 Support vectors usually lie near the boundary

 Objects far away from boundary will have little influence on the model

- Overview:
 - Hypothesis: the decision boundary is a linear model of the input vector *x*:

$$\boldsymbol{w}^T\boldsymbol{x}+b=0$$

• Loss Function:

$$\min \frac{1}{2} \| \boldsymbol{w} \|^{2}$$

s.t. $y_{i} (\boldsymbol{w}^{T} \boldsymbol{x}_{i} + b) - 1 \ge 0$

• Aim: find a decision boundary that gives the maximum margin

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SVM Applications

Soft Margin SVM

• When classes are not linearly separable

Soft Margin SVM

 Standard SVM will cause misclassifications

• For misclassified samples:

 $y_i(\boldsymbol{w}^T\boldsymbol{x_i} + b) \le 1$

Soft Margin SVM

• We introduce a new slack variable ξ_i , i=1,2,...,n, which refers to the soft margin

• Soft margin SVM aims to solve:

$$\min \frac{1}{2} \|\boldsymbol{w}\|^2 + C \sum_{i=1}^n \xi_i$$

s.t. $y_i (\boldsymbol{w}^T \boldsymbol{x}_i + b) \ge 1 - \xi_i$
 $\xi_i \ge 0$

Where C is a constant term

SVM Remarks

- Strengths:
 - It generalizes well in high-dimensional space with relatively low sample sizes
 - It is little affected by data distribution / density

- Weaknesses:
 - It is usually computational expensive
 - It performs bad when classes are highly overlapped (although the soft-margin tricks have been developed to cope with overlapping issue)

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• SVM Applications =

• [1] Eigen-feature analysis of weighted covariance matrices for LiDAR point cloud classification (Lin et al, 2014, ISPRS Journal)

Fig. 1. Results of PCA on point datasets with uniform sampling (top), incomplete surface sampling (middle), and different sampling densities (bottom).

• [1] Eigen-feature analysis of weighted covariance matrices for LiDAR point cloud classification (Lin et al, 2014, ISPRS Journal)

Top left: orthoimage; top right: point clouds; Bot left: classification results from standard eigen features Bot right: classification results from generated features

• [2] Feature relevance assessment for the semantic interpretation of 3D point cloud data. (Weinmann et al, 2013, ISPRS Annals)

	NN	k-NN	NB	SVM
all features	86.74	90.21	84.66	89.48
only 3D features	85.70	88.64	85.80	88.34
only 2D features	82.66	83.80	77.09	80.06
eigenvalue-based 3D features	80.36	82.42	83.92	84.81
$\{L_{\lambda}, P_{\lambda}, S_{\lambda}\}$	62.91	75.72	76.90	75.26
five best-ranked features	90.97	93.53	92.61	93.32

Table 3: Overall classification accuracies in % for different feature subsets and different classifiers.

- Steps to apply SVM and other classical classifiers:
 - Collect raw data
 - Design and compute features
 - Feed the data and features to train the model
 - Test and evaluate the model
- Most of the traditional machine learning works focus on feature engineering

Questions?

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Lab Session SVM Practice in Scikit Learn

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Scikit-Learn

scikit-learn

Machine Learning in Python

Getting Started

Release Highlights for 1.0 GitHub

Classification

Identifying which category an object belongs to.

Applications: Spam detection, image recognition. **Algorithms:** SVM, nearest neighbors, random forest, and more...

Regression

Predicting a continuous-valued attribute associated with an object.

Applications: Drug response, Stock prices. Algorithms: SVR, nearest neighbors, random forest, and more...

Simple and efficient tools for predictive data analysis

- Accessible to everybody, and reusable in various contexts
- Built on NumPy, SciPy, and matplotlib
- Open source, commercially usable BSD license

Clustering

Automatic grouping of similar objects into sets.

Applications: Customer segmentation, Grouping experiment outcomes Algorithms: k-Means, spectral clustering, meanshift, and more...

Source: Scikit-Learn documentation

Scikit-Learn

• Installation with pip or conda

Installing the latest release							
Operating System Windows macOS	Linux						
Packager pip conda							
Use pip virtualenv							
Install the 64bit version of Python 3, for instance from https://www.python.org. Then run:							
\$ pip install -U scikit-learn							

SK-Learn for SVM

- SVM has three classifiers in the library
 - SVC: most commonly used in practice
 - NuSVC: similar to SVC, has slightly different yet equivalent mathematical formulations and parameter set
 - LinearSVC: faster implementation of SVM, but can only adopt linear kernels

SVC: Getting started


```
>>> from sklearn import svm
>>> X = [[0, 0], [1, 1]]
>>> y = [0, 1]
>>> clf = svm.SVC()
>>> clf.fit(X, y)
SVC()
```

After being fitted, the model can then be used to predict new values:

```
>>> clf.predict([[2., 2.]])
array([1])
```

- X is input samples with features, y is the labels
- Model.fit() gives the trained model
- Model.predict() gives the predictions on other unseen samples

SVC: Documentation

sklearn.svm.SVC

class sklearn.svm.SVC(*, C=1.0, kernel='rbf', degree=3, gamma='scale', coef0=0.0, shrinking=True, probability=False, tol=0.001, cache_size=200, class_weight=None, verbose=False, max_iter=-1, decision_function_shape='ovr', break_ties=False, random_state=None)

- The most important hyper-parameters:
 - C: the coefficient introduced in soft-margin SVM
 - Kernel: a trick you can use to transform input features

SVC: Documentation

sklearn.svm.SVC

class sklearn.svm.SVC(*, C=1.0, kernel='rbf', degree=3, gamma='scale', coef0=0.0, shrinking=True, probability=False, tol=0.001, cache_size=200, class_weight=None, verbose=False, max_iter=- 1, decision_function_shape='ovr', break_ties=False, random_state=None) [source]

- Other important hyper-parameters:
 - Class_weight: specify the weight per class. You either input a dictionary of pre-fixed weights, or use 'balanced'.
 - Max_iter: hard limit on iterations within solver, or -1 for no limit.
 - Decision_function_shape:
 - 'ovr': default, one versus the rest for multi-class
 - 'ovo': one versus one for multi-class

SVC: Interesting Attributes

- n_features_in: int
 - Number of features seen during fitting the model

- support_: ndarray of shape (n_SV)
 - Indices of support vectors.

- support_vectors_: ndarray of shape (n_SV, n_features)
 - Support vectors.

• An example: based on observations of dosage of a medicine, determine if a dosage is effective or not

• Transforming features to higher dimensions

- Recall the SVM solution for weights: $w = \sum_{i=1}^{n} \lambda_i y_i x_i$
- For an input x:

$$f(\mathbf{x}) = \mathbf{w}^T \mathbf{x} + b = \sum_{i=1}^n \lambda_i y_i \mathbf{x_i}^T \mathbf{x} + b$$

• Assume we transfer x to $\Phi(\mathbf{x})$, we have

$$f(\Phi(\mathbf{x})) = \sum_{i=1}^{n} \lambda_i y_i \Phi(\mathbf{x}_i)^T \Phi(\mathbf{x}) + b$$

Kernel, also can be written as $K(x_i, x)$

Polynomial Kernel (Optional)

• A simple polynomial kernel in 1D dimension:

Polynomial Kernel (Optional)

$$K(x_a, x_b) = (x_a x_b + \frac{1}{2})^2 = x_a x_b + x_a^2 x_b^2 + \frac{1}{4}$$
$$= \left\{ x_a, x_a^2, \frac{1}{2} \right\}^T \left\{ x_b, x_b^2, \frac{1}{2} \right\}$$

Polynomial Kernel (Optional)

• A general polynomial kernel in multi-feature dimension:

$$K(\boldsymbol{x_a}, \boldsymbol{x_b}) = (\boldsymbol{x_a}^T \boldsymbol{x_b} + r)^d$$

• A simple RBF kernel in 1D dimension:

• RBF naturally contains a polynomial kernel in infinite space

$$K(x_a, x_b) = e^{-\frac{1}{2}(x_a - x_b)^2} = e^{-\frac{1}{2}(x_a^2 + x_b^2) + x_a x_b}$$
$$= e^{-\frac{1}{2}(x_a^2 + x_b^2)} e^{x_a x_b}$$

• RBF naturally contains a polynomial kernel in infinite space $e^{x} = 1 + x + \frac{x^{2}}{2!} + \frac{x^{3}}{3!} + \dots + \frac{x^{\infty}}{\infty!}$

$$e^{x_a x_b} = 1 + x_a x_b + \frac{(x_a x_b)^2}{2!} + \frac{(x_a x_b)^3}{3!} + \dots + \frac{(x_a x_b)^\infty}{\infty!}$$

$$= \left\{1, x_{a}, \frac{x_{a}^{2}}{2!}, \frac{x_{a}^{3}}{3!}, \dots, \frac{x_{a}^{\infty}}{\infty!}\right\}^{T} \left\{1, x_{b}, \frac{x_{b}^{2}}{2!}, \frac{x_{b}^{3}}{3!}, \dots, \frac{x_{b}^{\infty}}{\infty!}\right\}$$

• RBF naturally contains a polynomial kernel in infinite space

$$K(x_a, x_b) = e^{-\frac{1}{2}(x_a^2 + x_b^2)} e^{x_a x_b}$$
$$= e^{-\frac{1}{2}(x_a^2 + x_b^2)} \left\{ 1, x_a, \frac{x_a^2}{2!}, \frac{x_a^3}{3!}, \dots, \frac{x_a^\infty}{\infty!} \right\}^T \left\{ 1, x_b, \frac{x_b^2}{2!}, \frac{x_b^3}{3!}, \dots, \frac{x_b^\infty}{\infty!} \right\}$$

• A general RBF kernel in multi-feature dimension:

$$K(x_a, x_b) = e^{-\frac{1}{\sigma^2}(||x_a - x_b||)^2}$$

• It measures the influence one sample has over another sample

• We don't actually conduct feature transformation, i.e., x to $\Phi(x)$

• Instead, we apply kernel trick to obtain the dot product of the transformed features in high dimensional space

 Kernel options provided by Scikit-Learn: 'linear', 'poly', 'rbf', 'sigmoid', 'precomputed'

Image source: https://www.eric-kim.net/eric-kim-net/posts/1/kernel_trick.html

Two SVC Demos

- (1) Maximum margin separating hyperplane
- (2) Plot different kernels using iris dataset

Sepal length

SVC with RBF kernel

Sepal length

SVC with polynomial (degree 3) kernel

Sepal length

A2: Point Cloud Classification

• You will use a classical ML model to perform point cloud classification (again, on object level)

• You are allowed to use libraries such as scikit learn

• You will need to evaluate the performance of the classifier

A2: Evaluation of the Model

- OA: overall accuracy
 - Out of 500 objects, how many are correctly classified?

- mAcc: mean per-class accuracy
 - How is the accuracy of each class? Average them.

A2: Evaluation of the Model

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Confusion Matrix:

• Row is the actual class, while column is the predicted class

Pred. classes →	Count	Building	Car	Fence	Pole	Tree	· ۲	True classes
	Building							
	Car							
	Fence							
	Pole							
	Tree							

Questions?