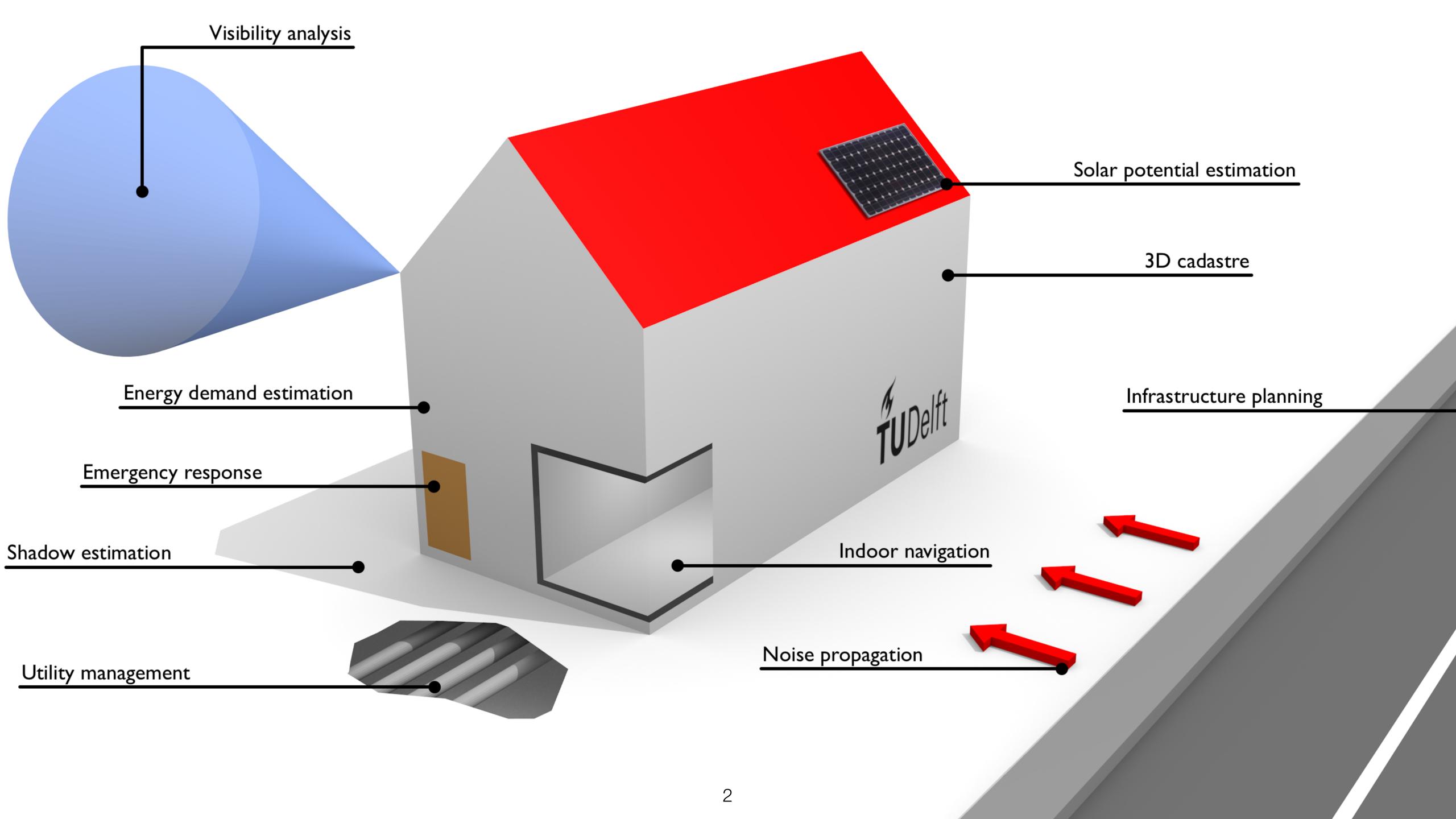
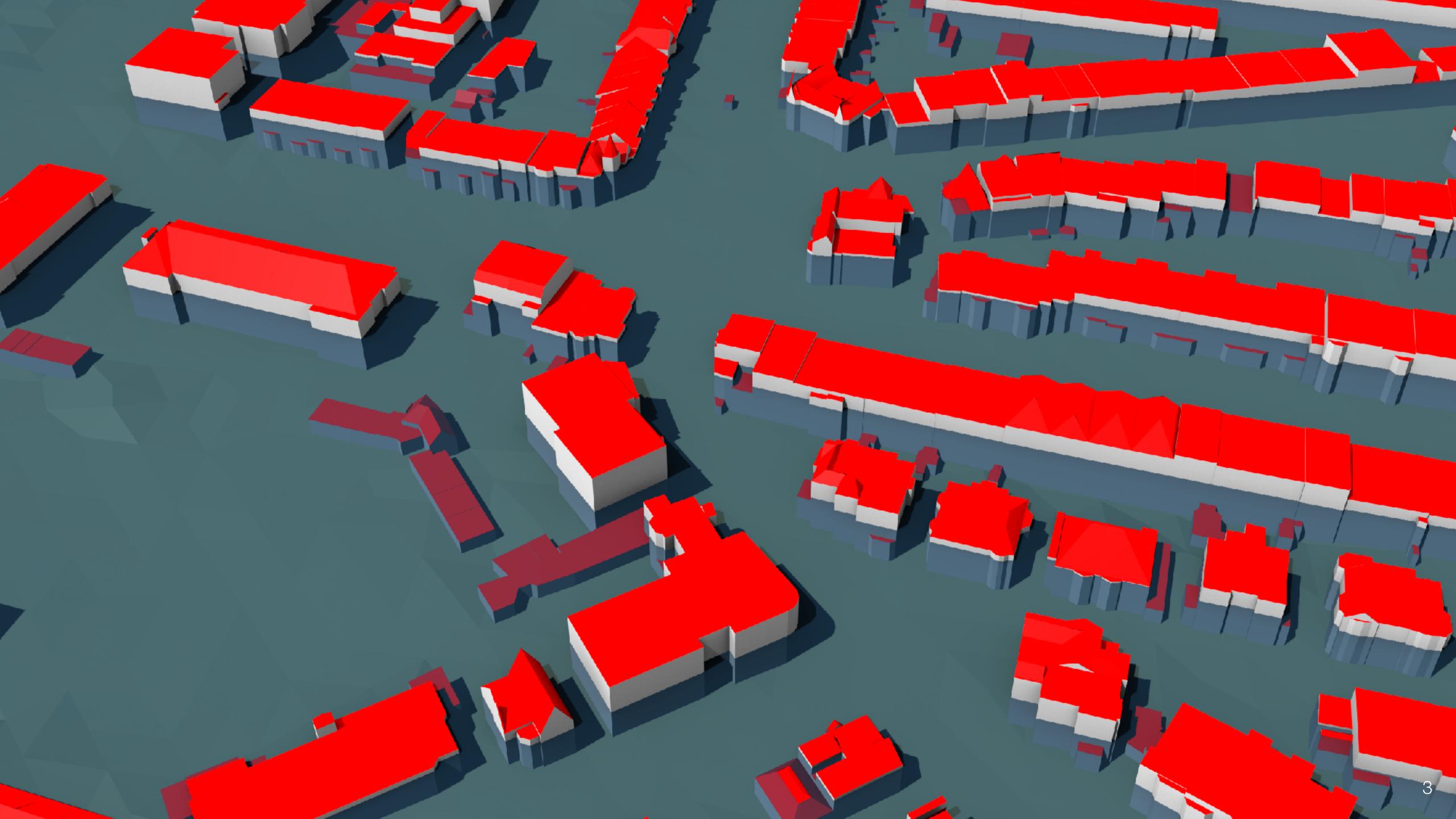
Applications of 3D modelling of the built environment

GEO1004:

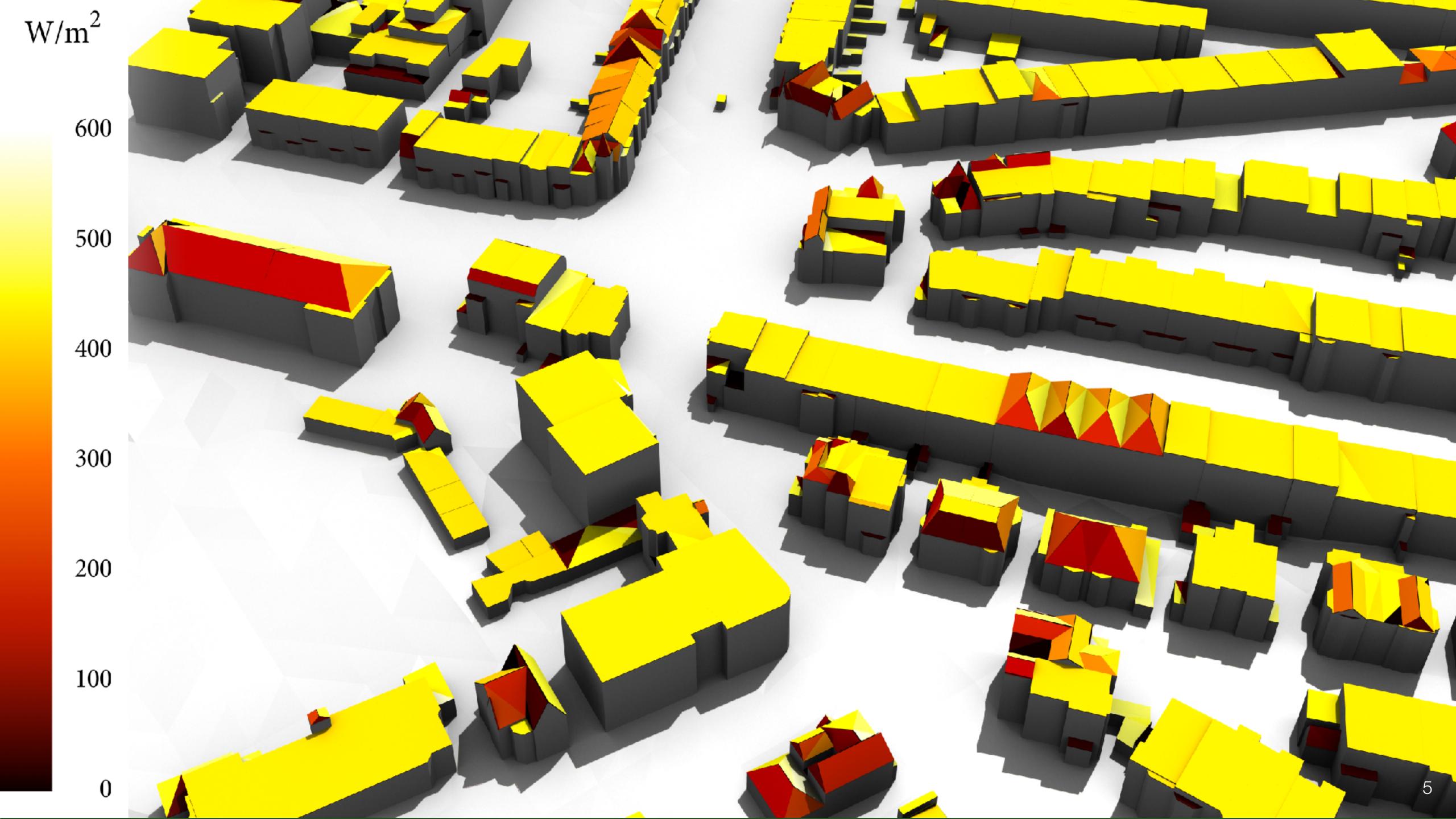
3D modelling of the built environment

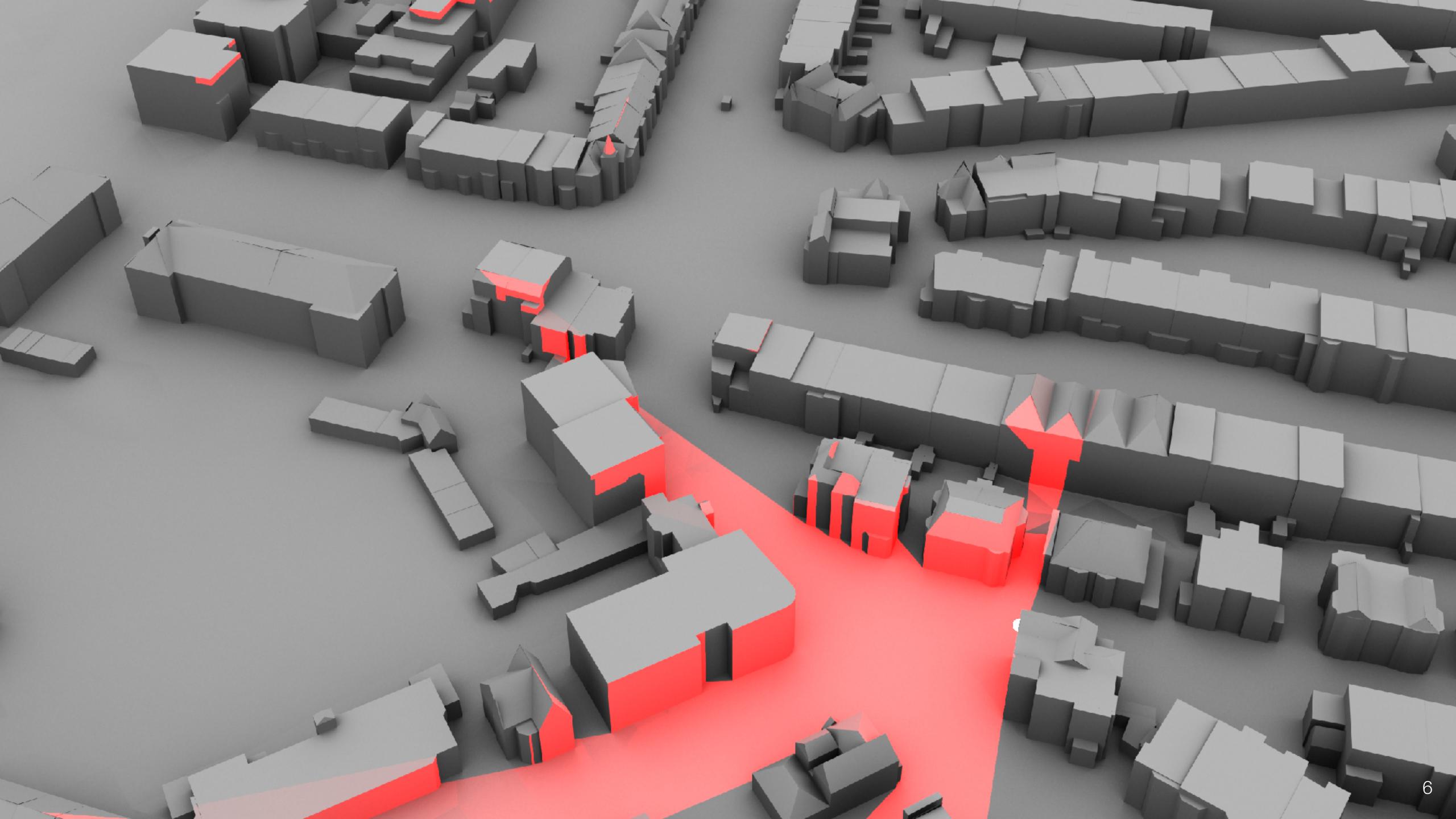












Other applications

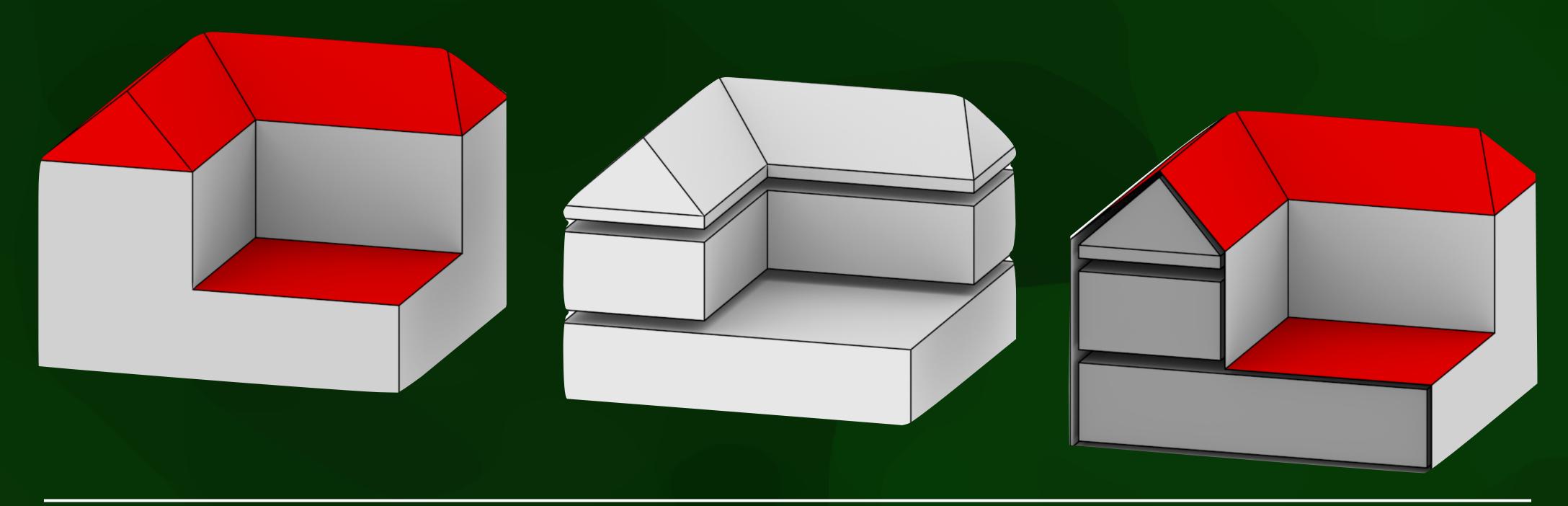
- Visualisation (eg for gaming, tourism, navigation, etc)
- Energy demand estimation (and potential for retrofitting)
- Computational fluid dynamics (eg for wind speeds, air quality, effects on buildings, etc)
- Shadow casting (eg for building permits, visibility analysis, improving energy demand/solar potential calculations, etc)

Some MSc Geomatics theses

- Motivation: create (rough) indoor geometry from widely available outdoor geometry
- Definition of a CityGML LOD2 with interiors (LOD2+)
- Compute interior geometry from exterior geometry + number of storeys
- Compute net internal area

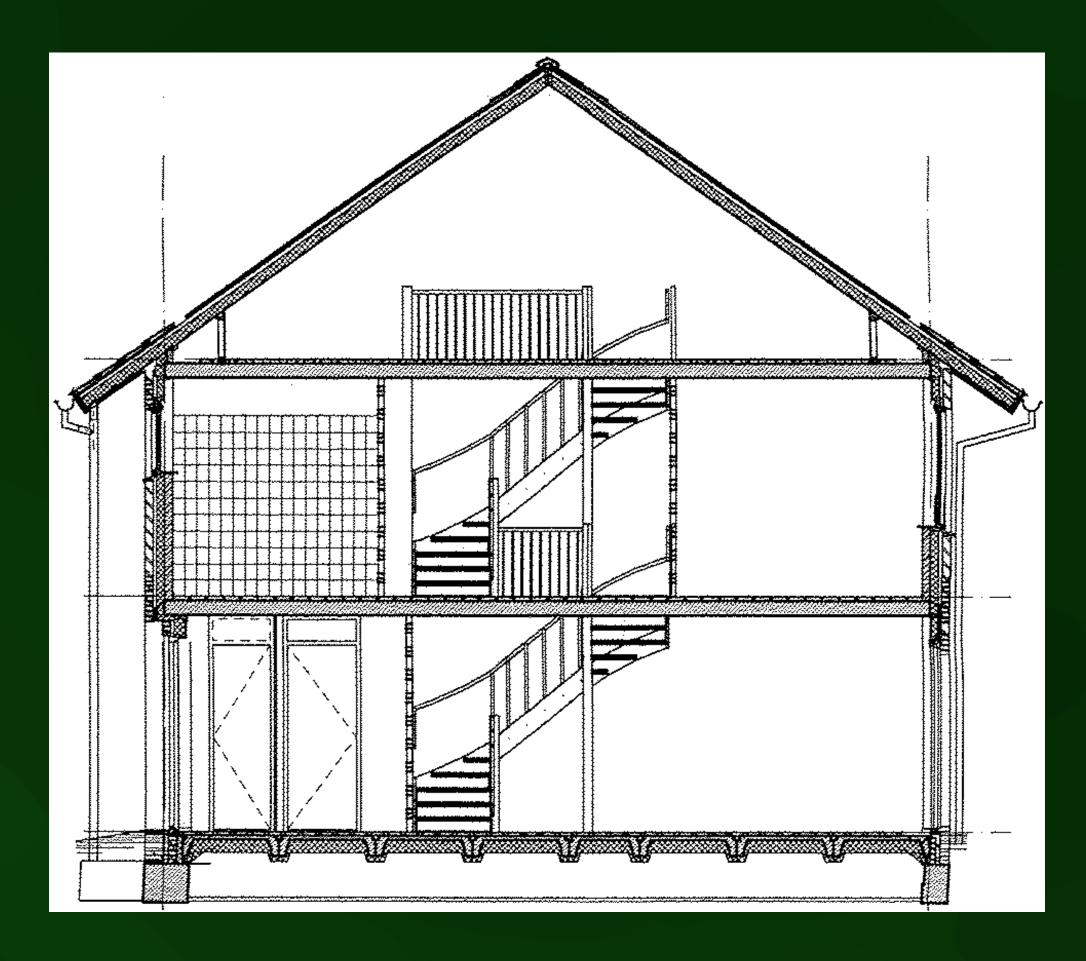


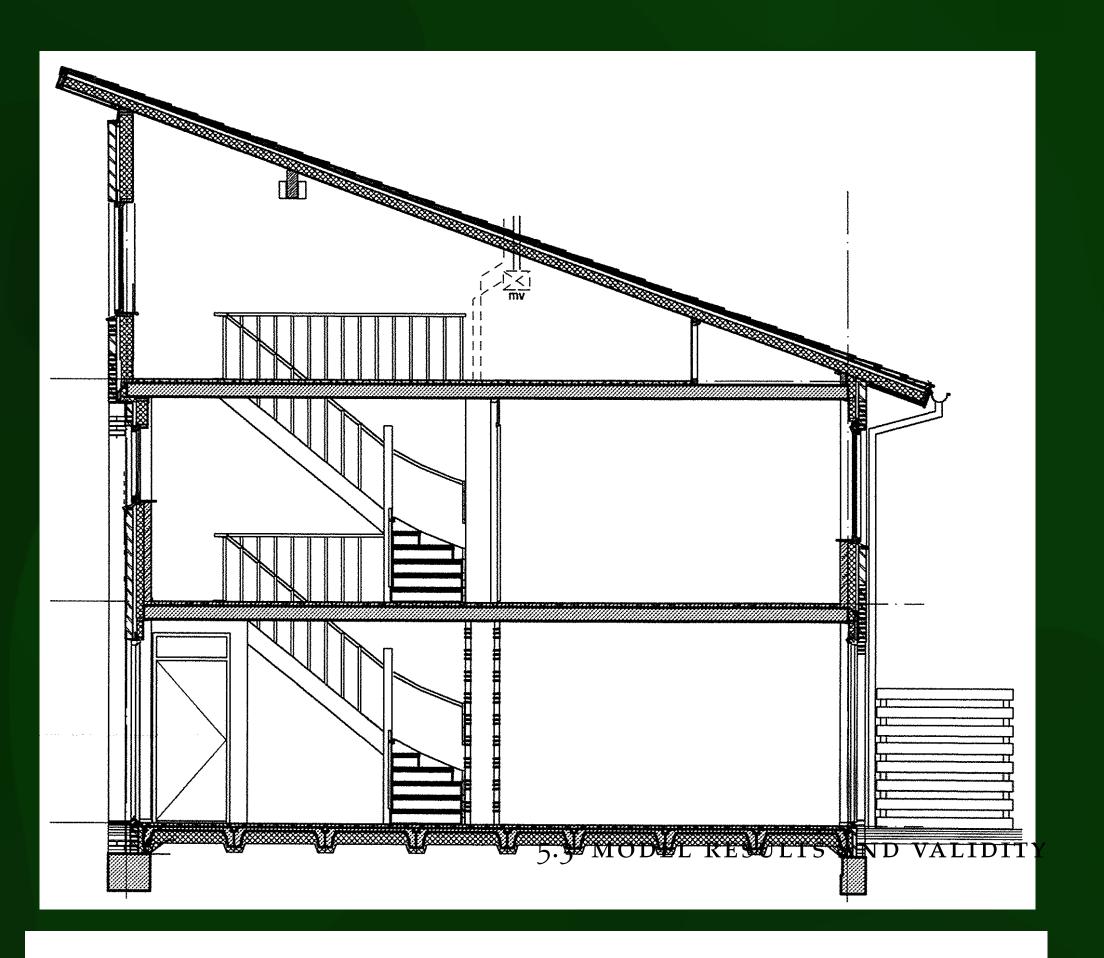
LOD2+



Exterior in LOD2	Interior in LOD2+
Buildings bodies are prisms Simple roof shapes Thematically classified boundary surfaces No openings in the exterior geometry	Storeys within building bodies are prisms Attic storey shapes corresponding to roof shapes Thematically classified boundary surfaces No openings in the indoor geometry

Indication of storeys

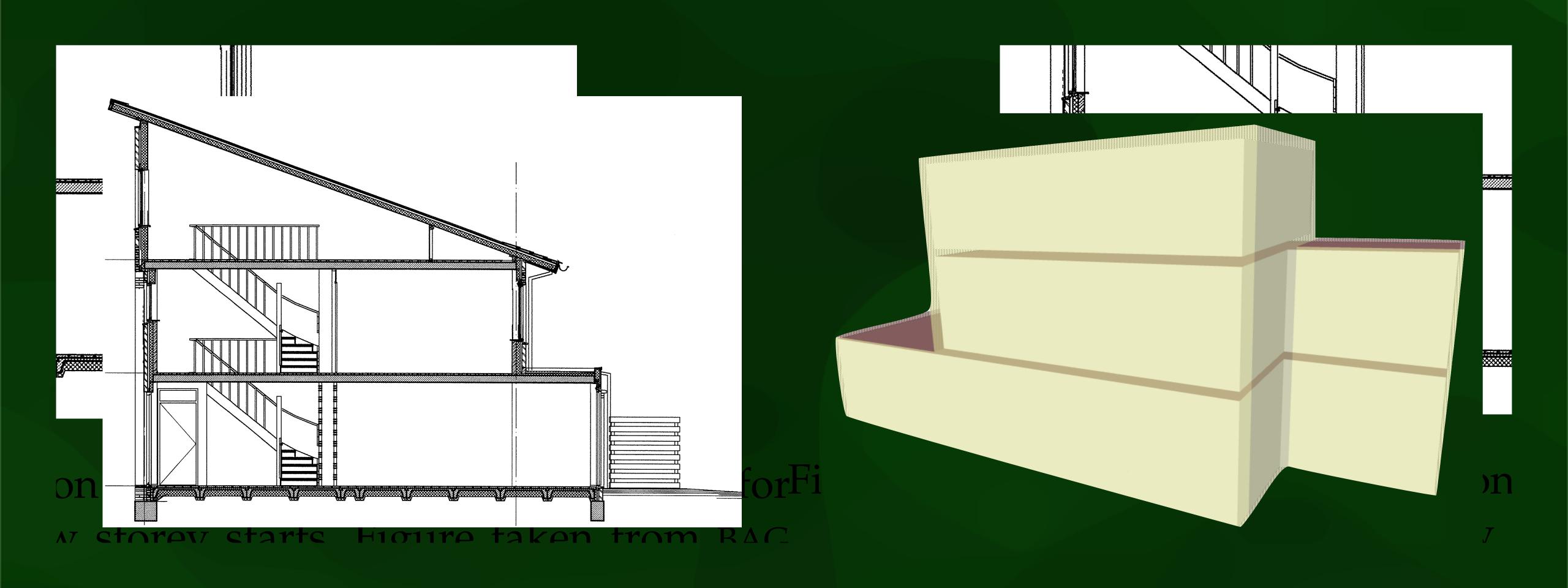




5.2 GENERATION RULES AND DATA IN

77

Indication of storeys



Wall thickness

Туре	year y	storeys x	$t_{ m ext}$ [cm]	$t_{ m shared} \ [m cm]$
Non-stacked	y < 1970	$x \leq 2$	27	11
		$x \ge 3$	27	12
	$1970 \le y \le 1985$	x = 2	27	10
		x = 3	28	12
		x = 4	27	9
	y > 1985	x = 2	28	13
		x = 3	30	12
		x = 4	25	12
Stacked	y < 1970	$x \leq 5$	29	12
		$5 < x \le 10$	38	11
		x > 10	25	9
	$1970 \le y \le 1985$	$x \leq 5$	28	11
		$5 < x \le 10$	26	11
		x > 10	29	12
	y > 1985	$x \leq 5$	30	12
		$5 < x \le 10$	38	13
		x > 10	35	15
Other types	y < 1970	x = 1	14	14
		$x \geq 2$	31	11
	$1970 \le y \le 1985$	x = 1	14	14
		$x \geq 2$	30	10
	y > 1985	x = 1	14	14
		$x \ge 2$	36	13

This robot can have different shapes. If an exact buffer is required in all directed the all directed the shapes are shaped to the shapes and the shapes are shaped in the shapes. If an exact buffer is required in all directed to the shapes are shaped in the shapes. If an exact buffer is required in all directed to the shapes are shaped in the shapes. If an exact buffer is required in all directed to the shapes are shaped in the shapes are shaped in the shaped sive operation and runs in $O(n^3m^3)$ where n and m are the sum of vertices, halfedges and shalfedges of polyhedron 1 and polyhedron 2 res<mark>pectively (H</mark>achenberger, 2007). A quick performance test shows that Minkowski sum of a triangular face with an approximated sphere (with 80 triangular facets and 42 vertices) takes about 2-3 times longer than Minkowski sum with a cube whereas the accuracy in the perpendicular offset is then still limited. Therefore a cube is chosen as robot, which is expected to be good enough as the walls of most buildings are perpendicular to each other.

The Minkowski-sum is the vector sum of the point sets of both polyhedra. Therefore when using a cube for applying the offset, a rotation should be applied. This is illustrated for a 2-dimensional case in Figure 39. The offset to the line is not the same for both cases. A rotation thus needs to be applied, such that the square is aligned with

ouffered face from the original solid (set difperation)

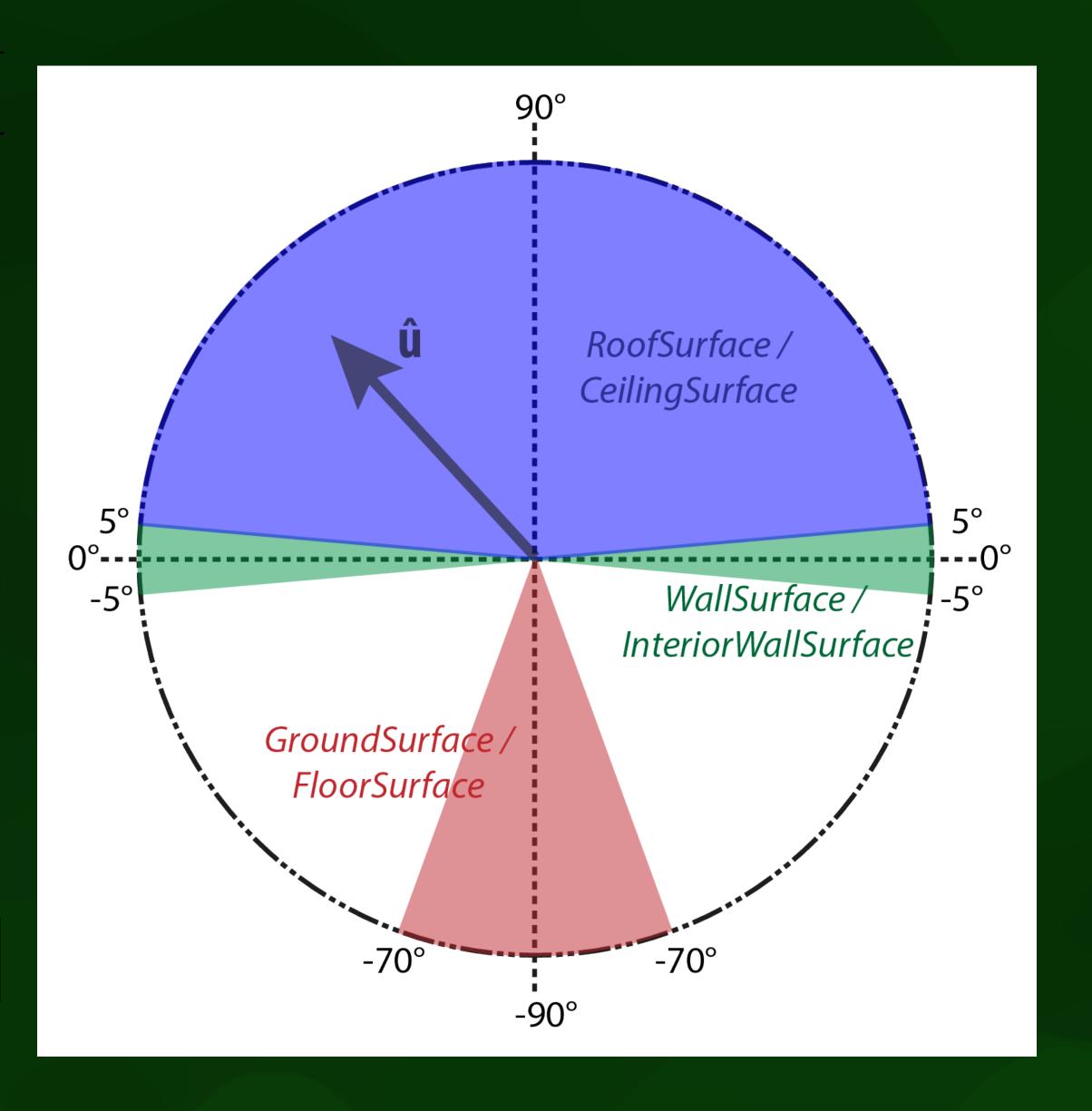
erent shapes. If an exact buffer is required in should be a sphere where the radius equals ortunately the Minkowski sum is an expension of the sum of the sum of the sum of a triangular face with an approximated ar facets and 42 vertices) takes about 2-3 times sum with a cube whereas the accuracy in the then still limited. Therefore a cube is chosen cted to be good enough as the walls of most cular to each other.

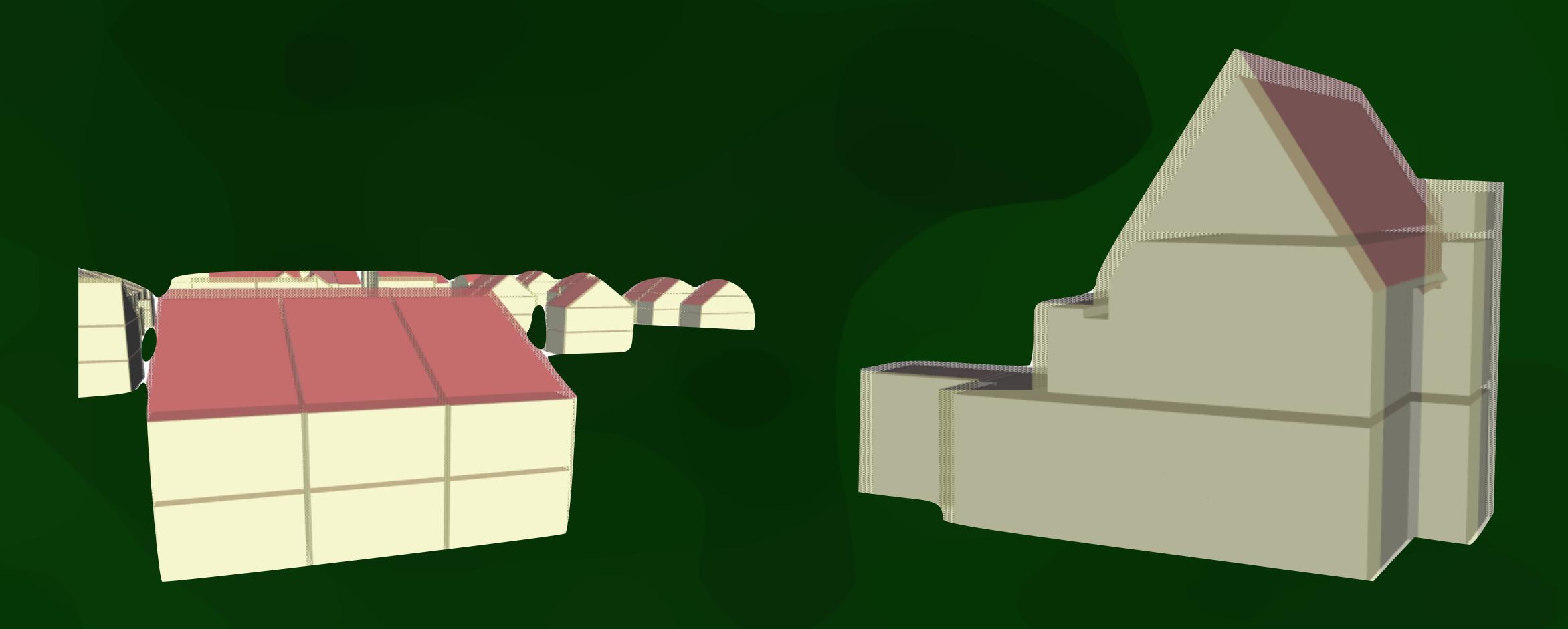
is the vector sum of the point sets of both when using a cube for applying the offset, a ed. This is illustrated for a 2-dimensional case to the line is not the same for both cases. A e applied, such that the square is aligned with the robot must be scaled, such that the radius is need to be handled separately so that in the out-squals the desired of the square is aligned with the robot must be scaled, such that the radius is need to be handled separately so that in the out-squals the desired of the square is aligned with the radius and the desired of the square is aligned.

of which the normal vectory ger than 100°, thereby exclude heights are extracted by containing height. What this height is marked as characteristic

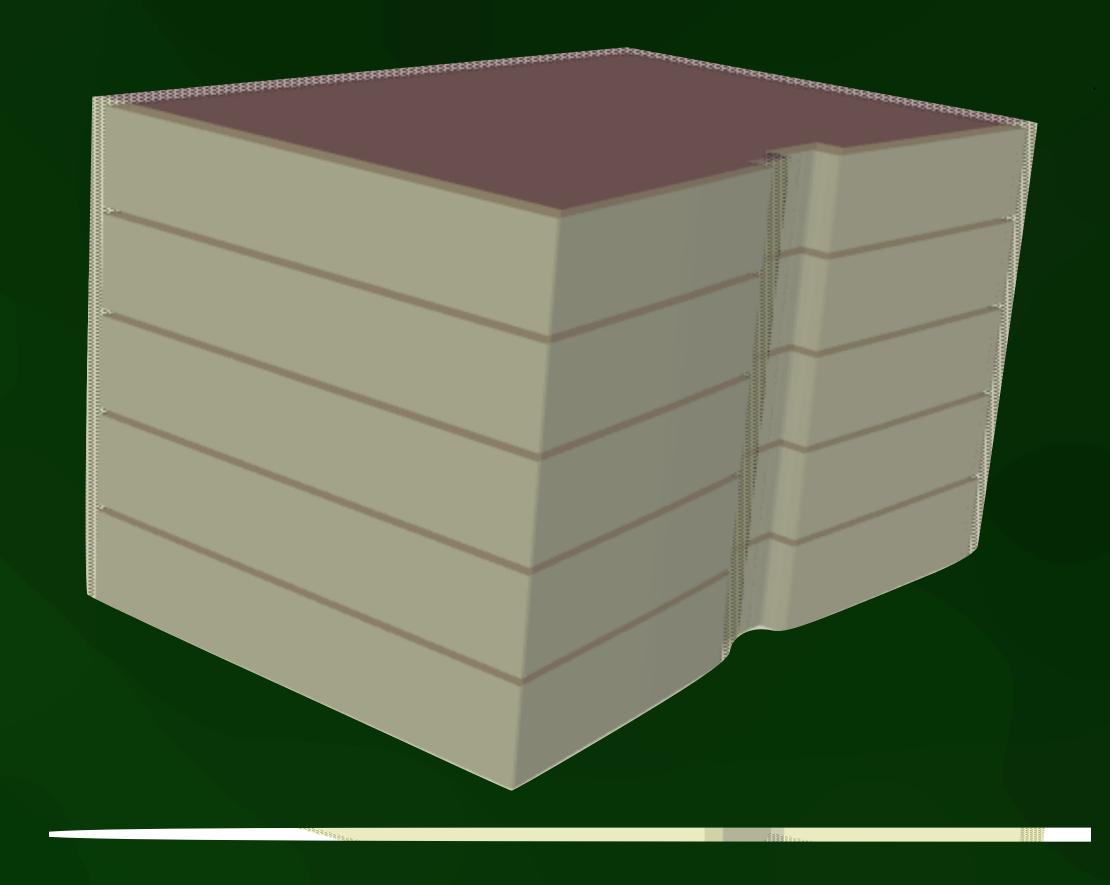
mption is that each storey has the same height, substrated fromestalts in the eight of the line. total height can be divided by the amount of heights at which the built a must be split.

Classifying surfaces

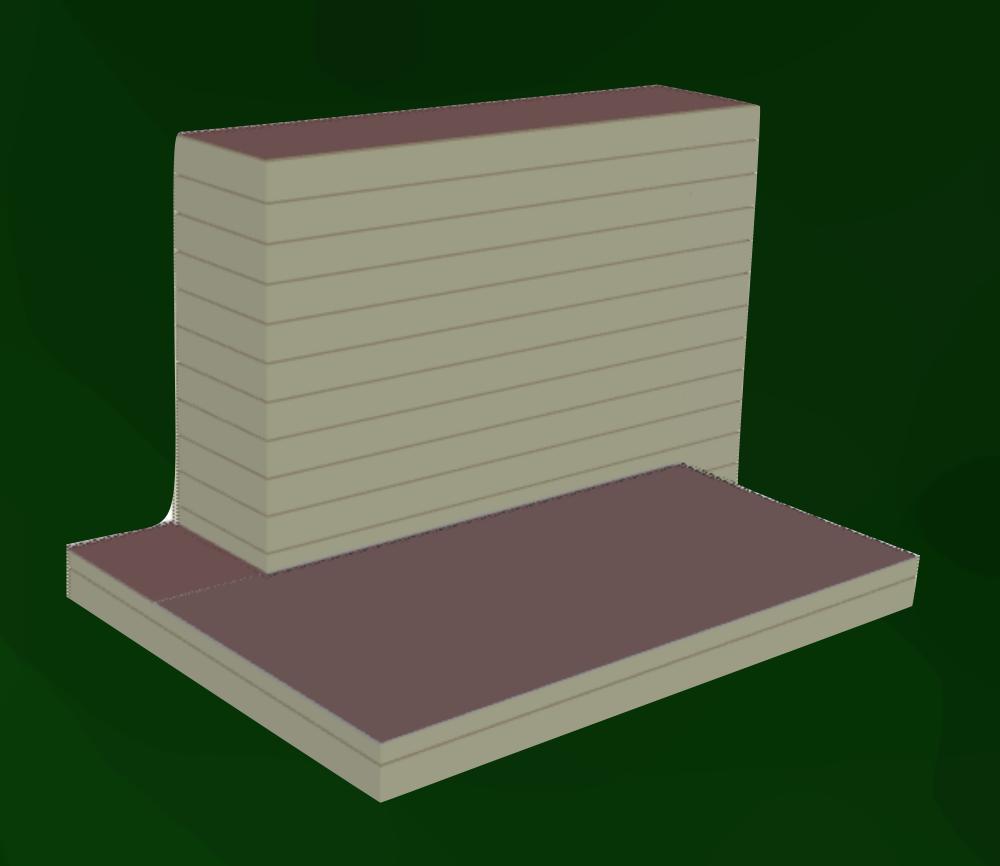




are not snapped to the eaves of the root, because the distance between

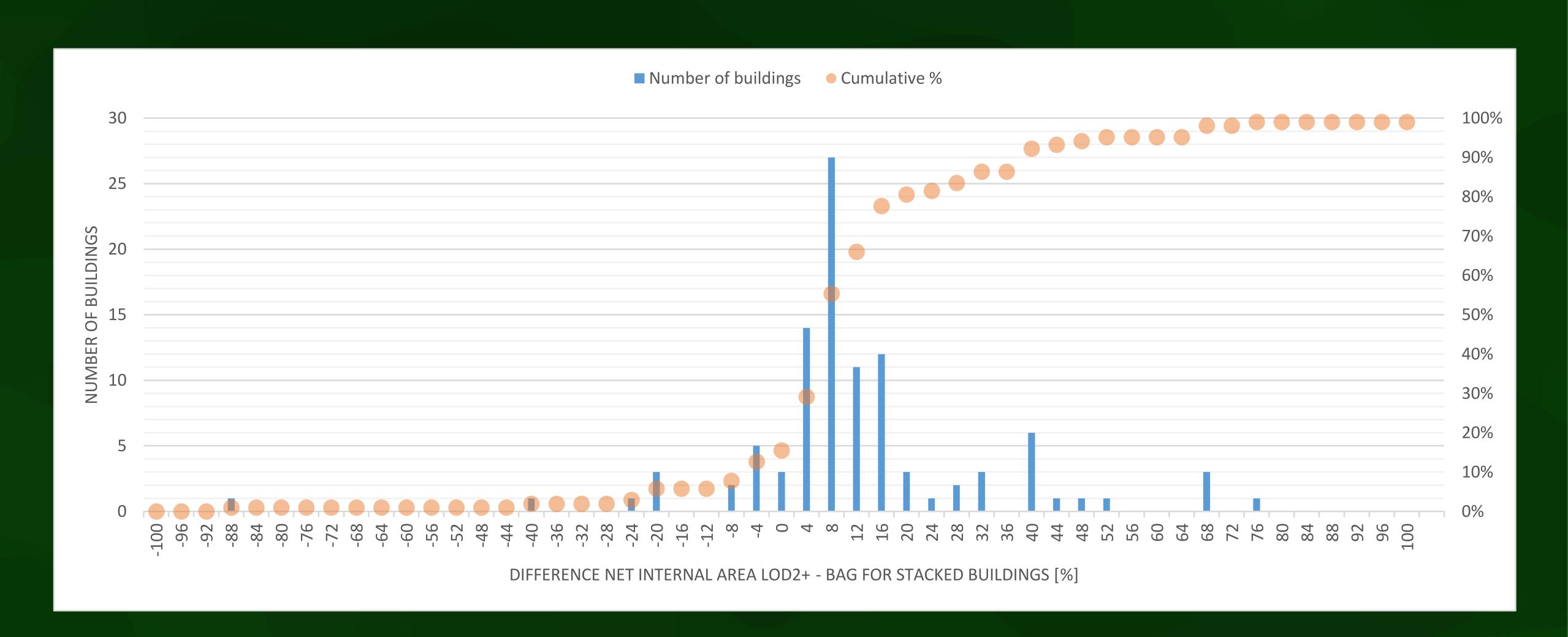




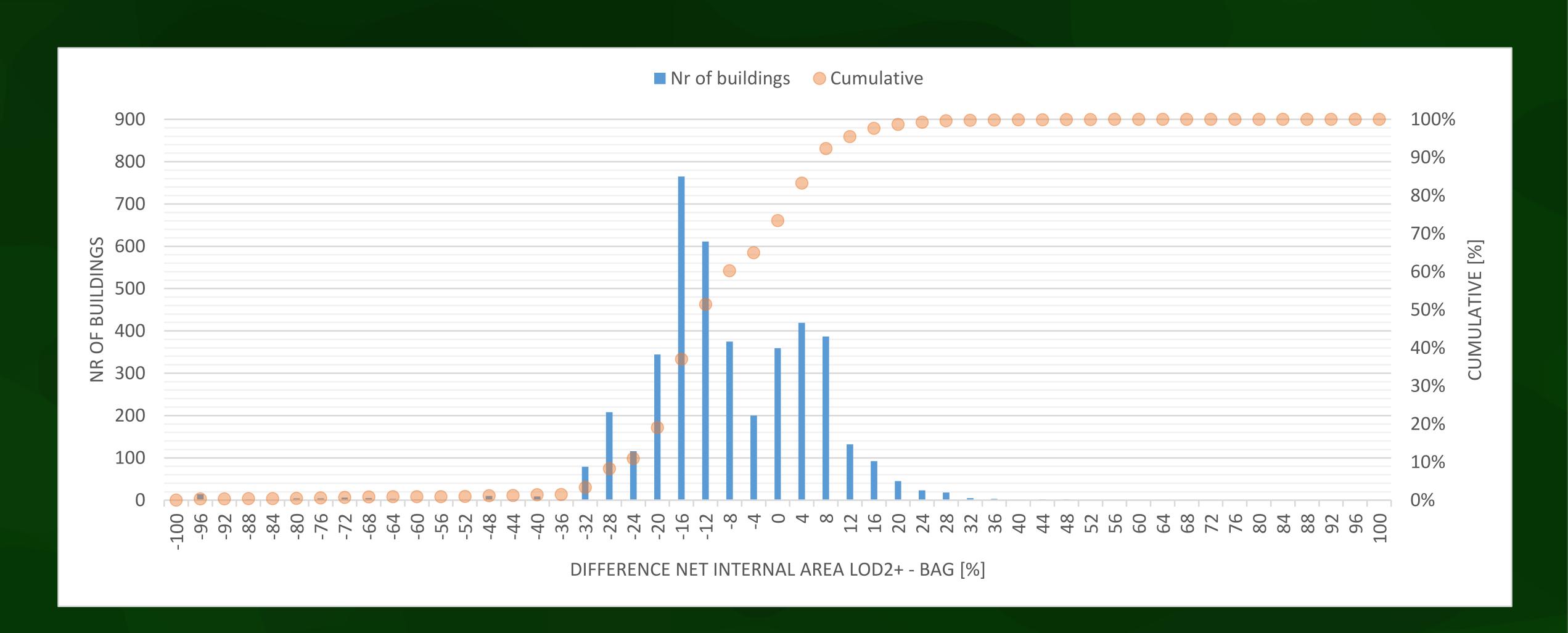




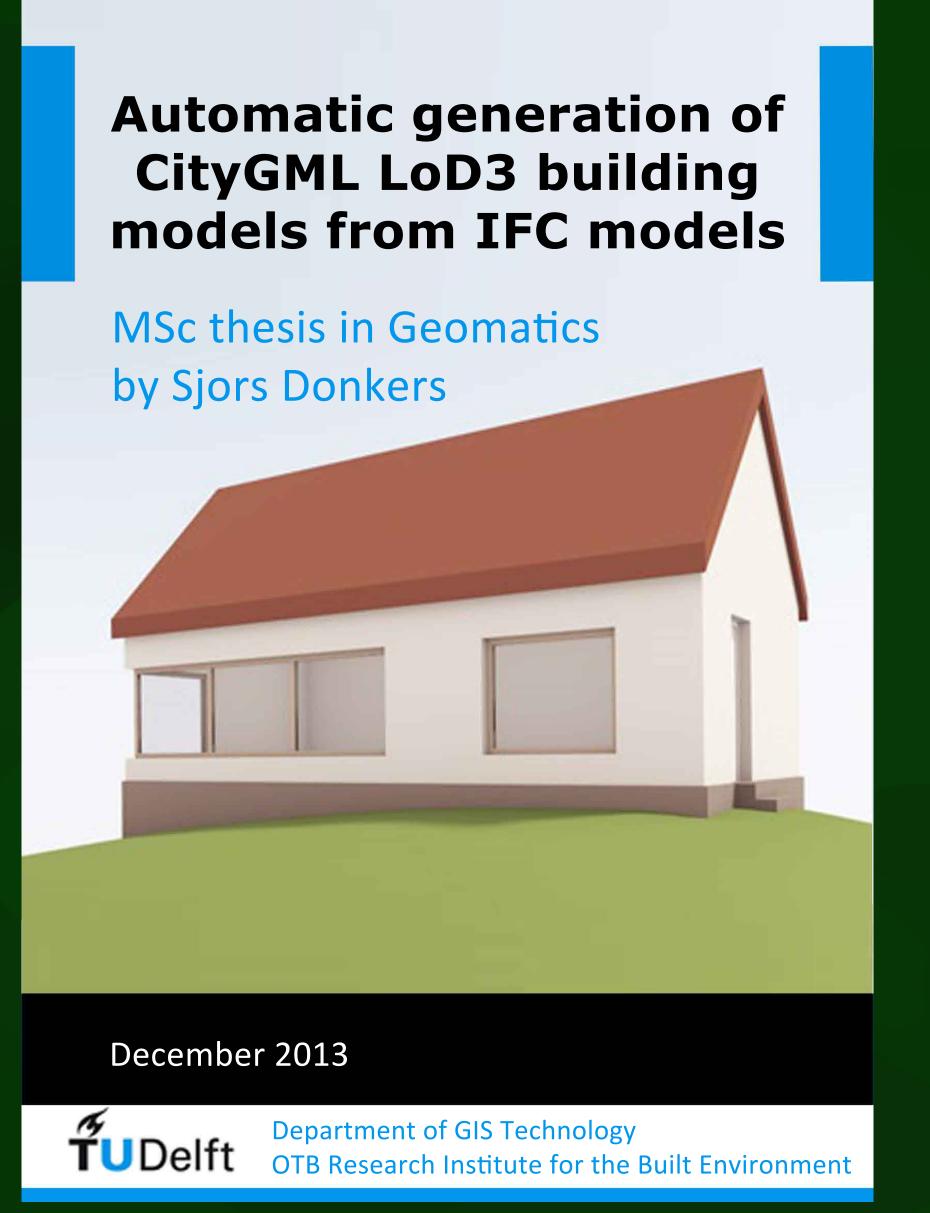
Net internal area (stacked)



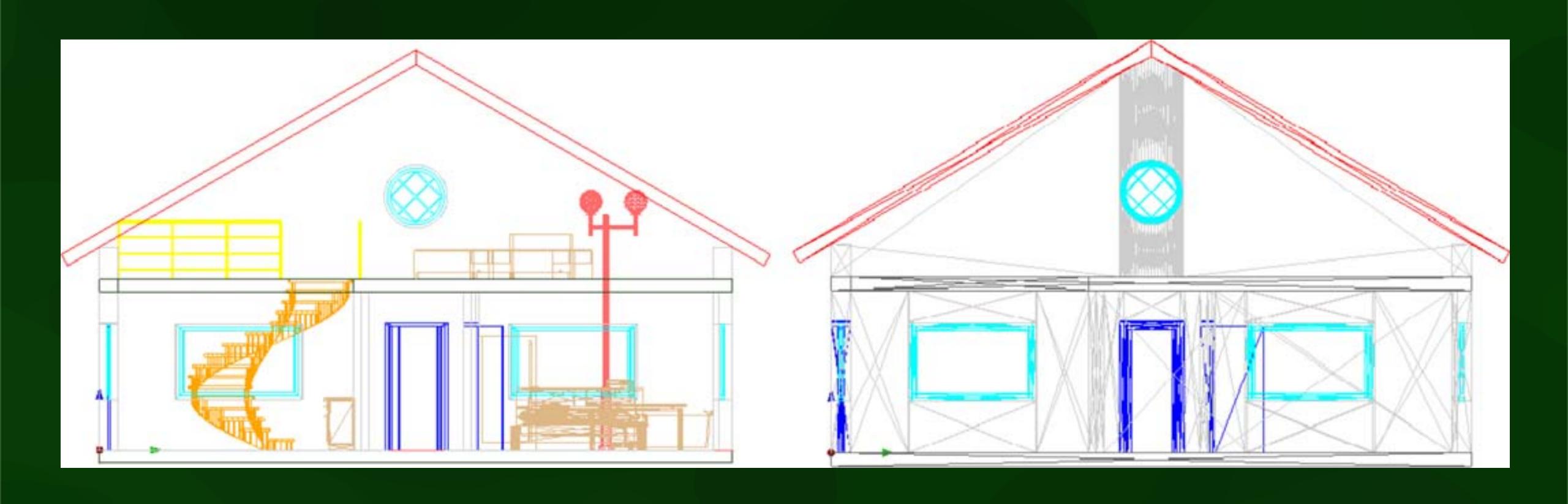
Net internal area (non-stacked)



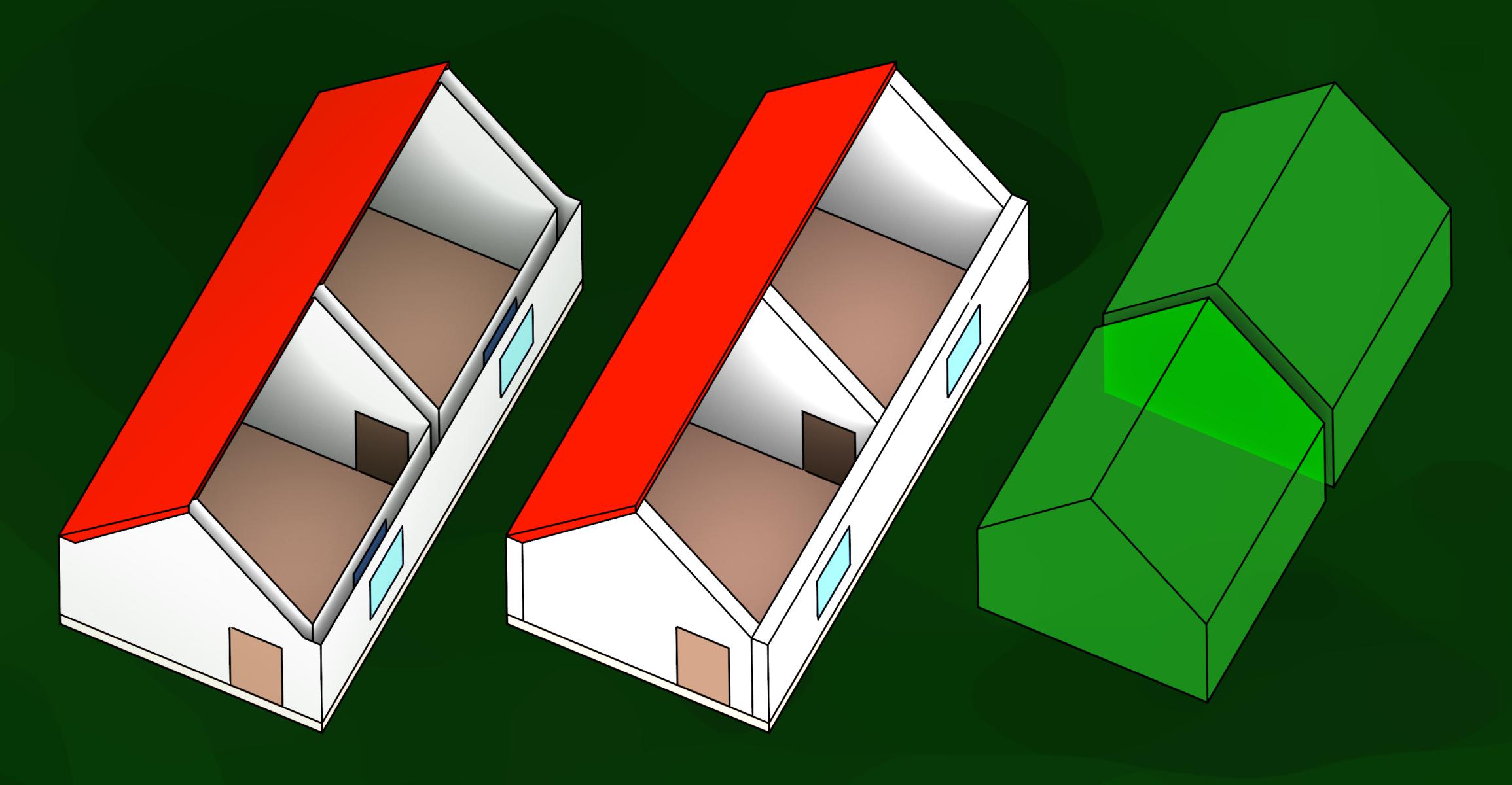
- Motivation: update 3D city models from designed BIM models (including potentially interiors)
- Fill gaps using Minkowski sum to increase size of elements
- Merge elements using Boolean set union
- Reclassify surfaces



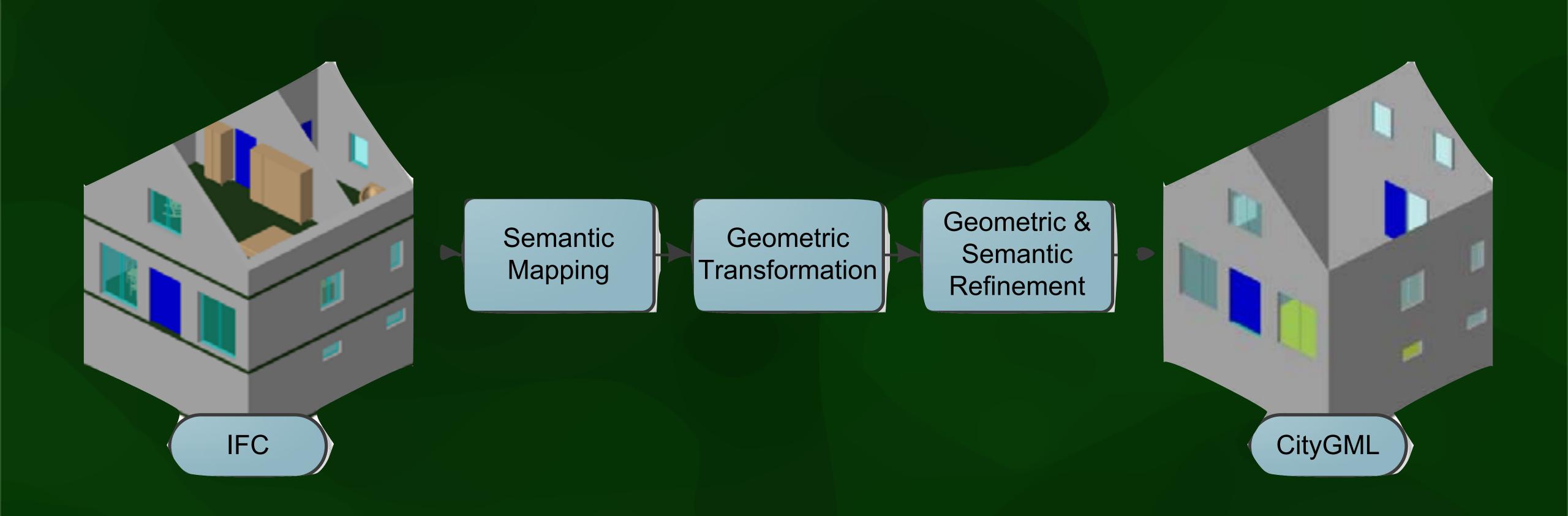
Goal



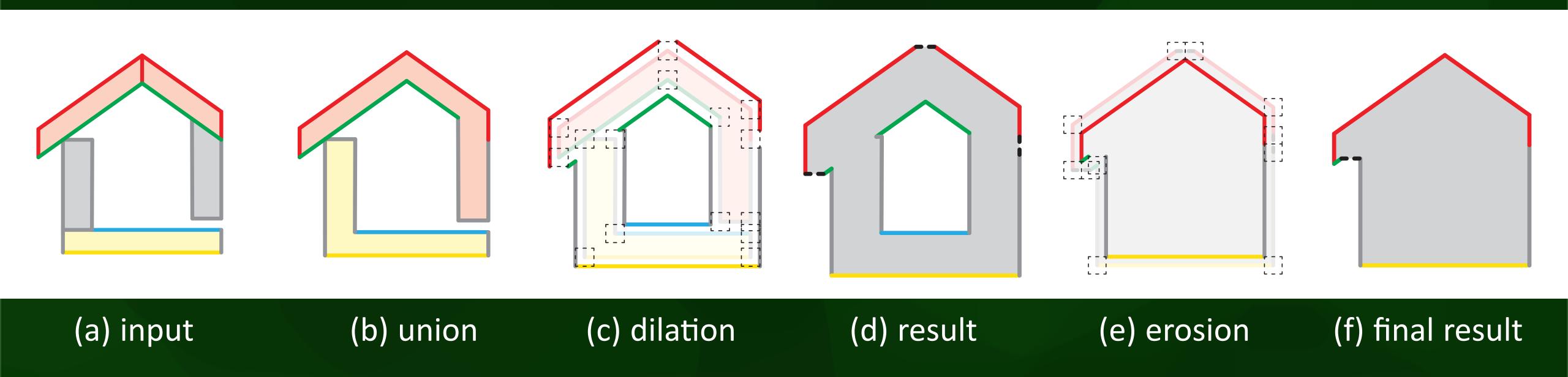
3DCM vs BIM

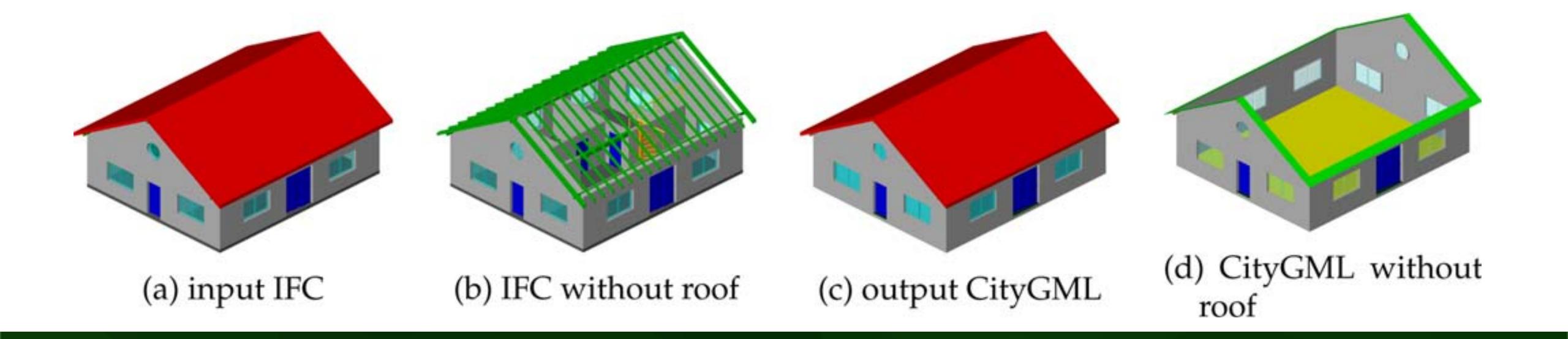


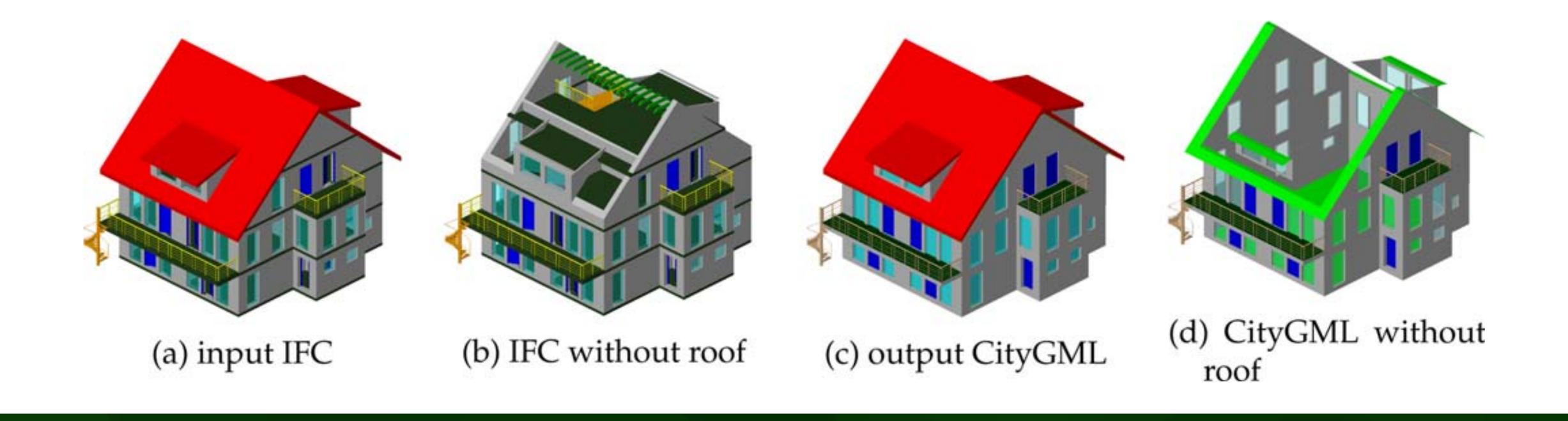
Methodology (semantics)

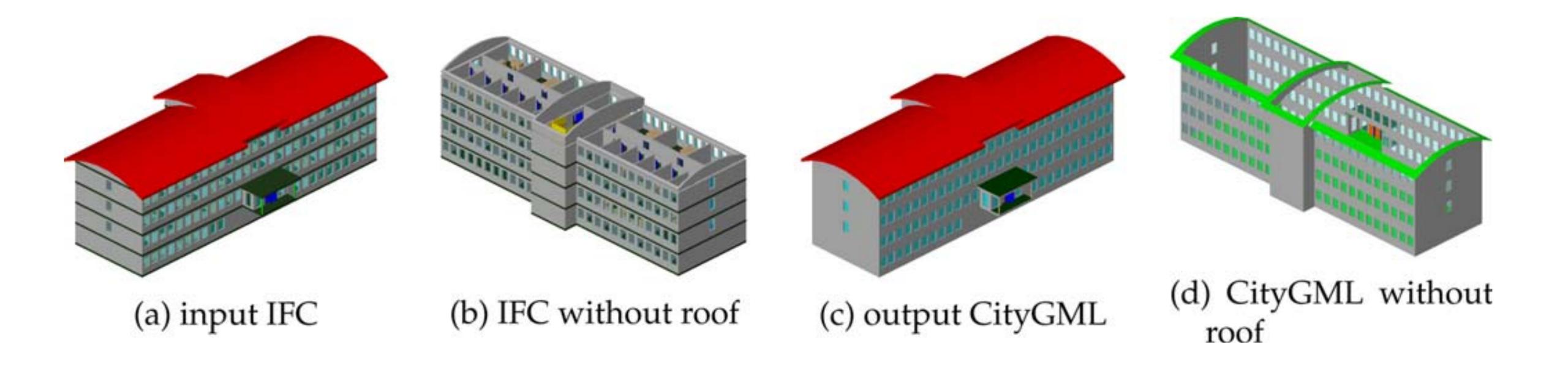


Methodology (geometry)

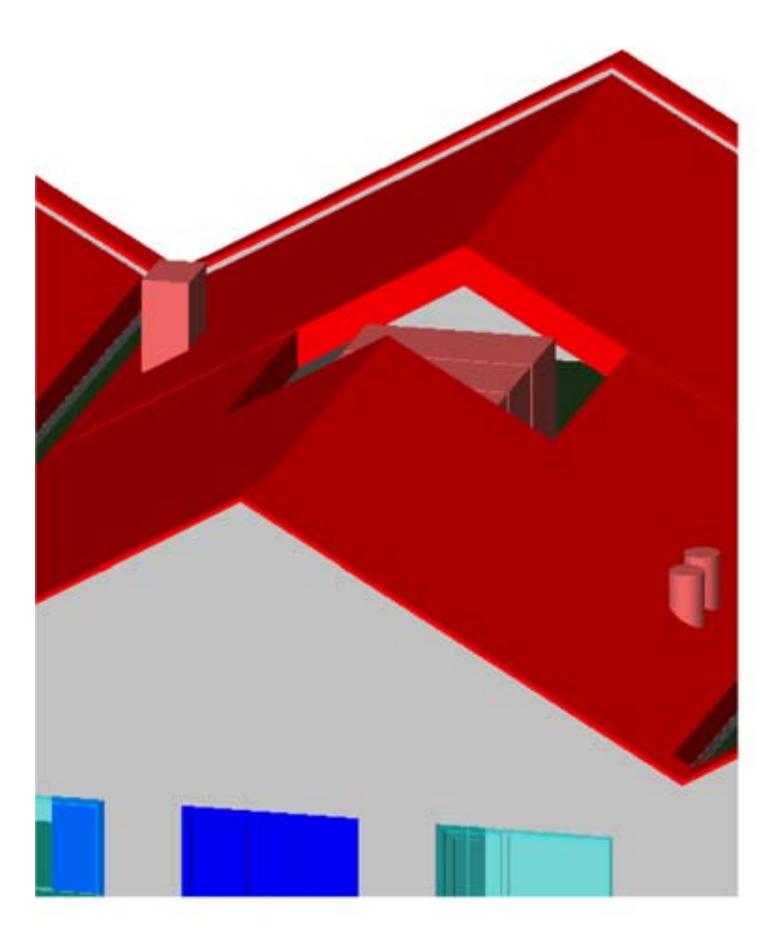




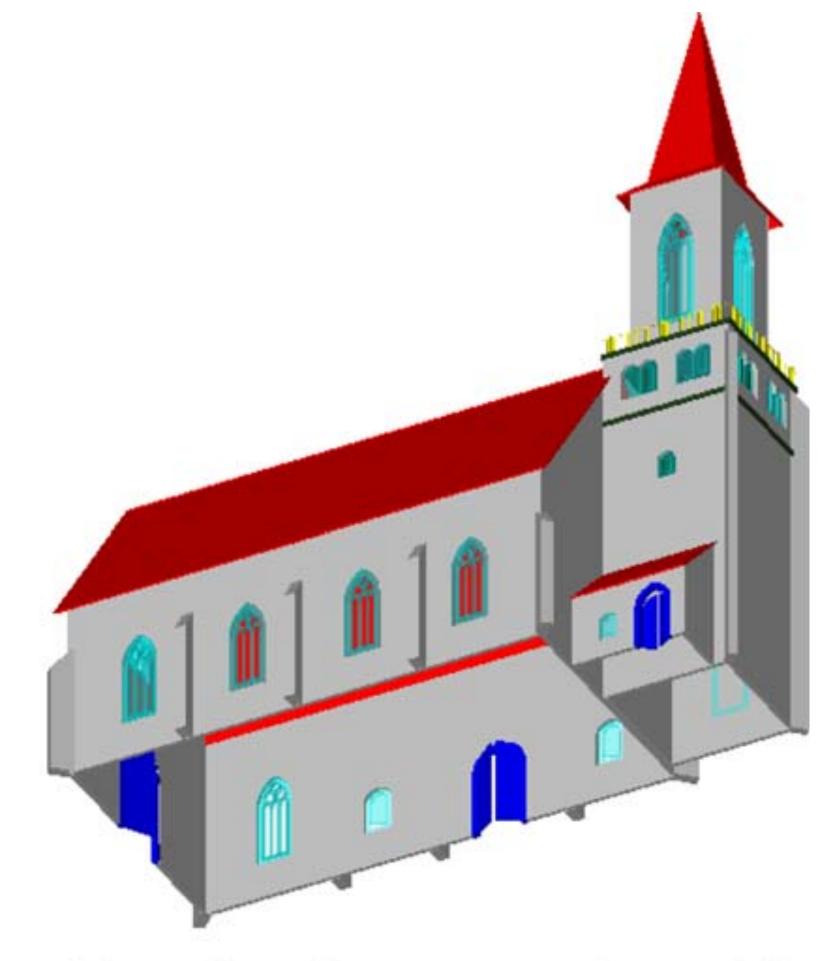




Issues



(a) Building where part of the roof is missing

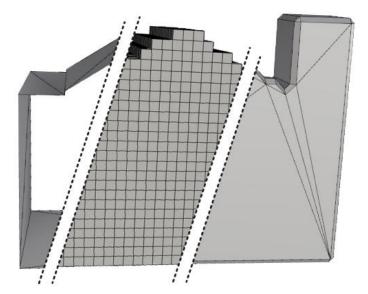


(b) A church missing a base slab

Motivation: repair 3D models so that they can be used in applications

- Voxelisation
- Reconstruction of mesh
- Obtain semantics and export

AUTOMATIC REPAIR OF 3D CITY BUILDING MODELS USING A VOXEL-BASED REPAIR METHOD



A thesis submitted to the Delft University of Technology in partial fulfillment of the requirements for the degree of

Master of Science in Geomatics

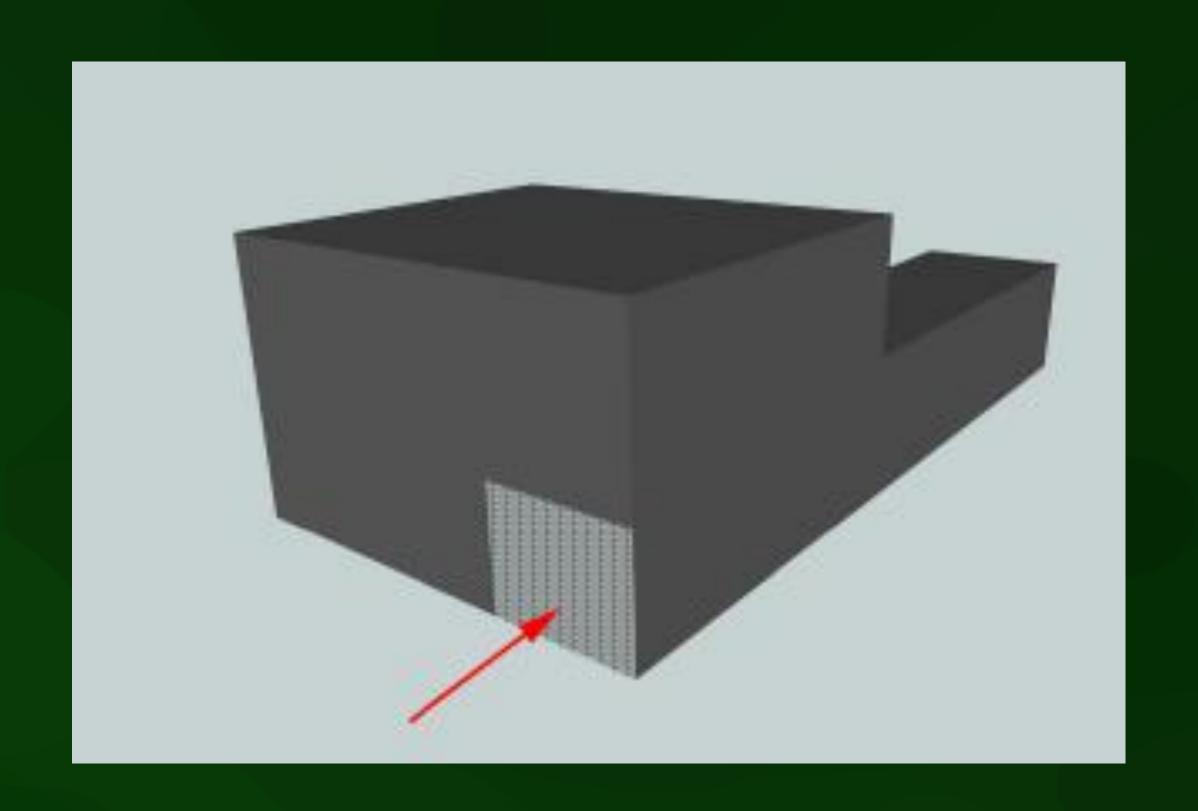
bv

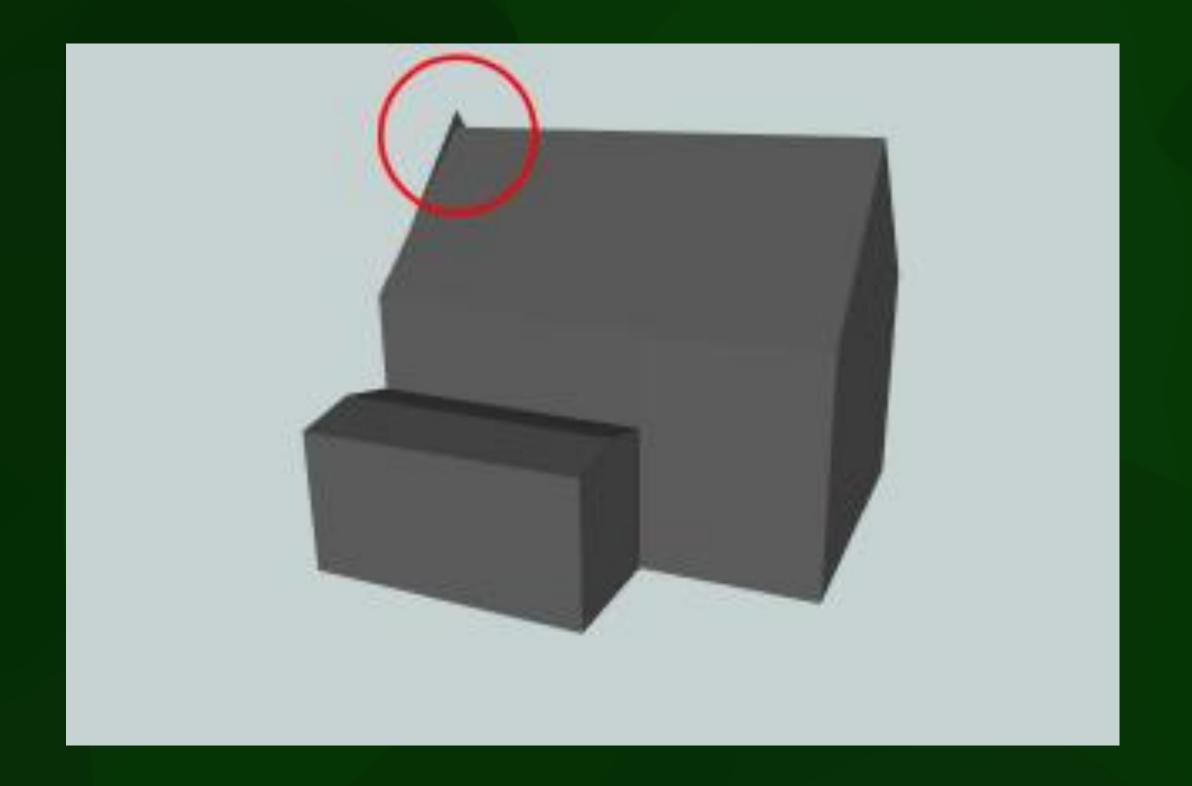
Damien Mulder

M.Sc Geomatics Thesis

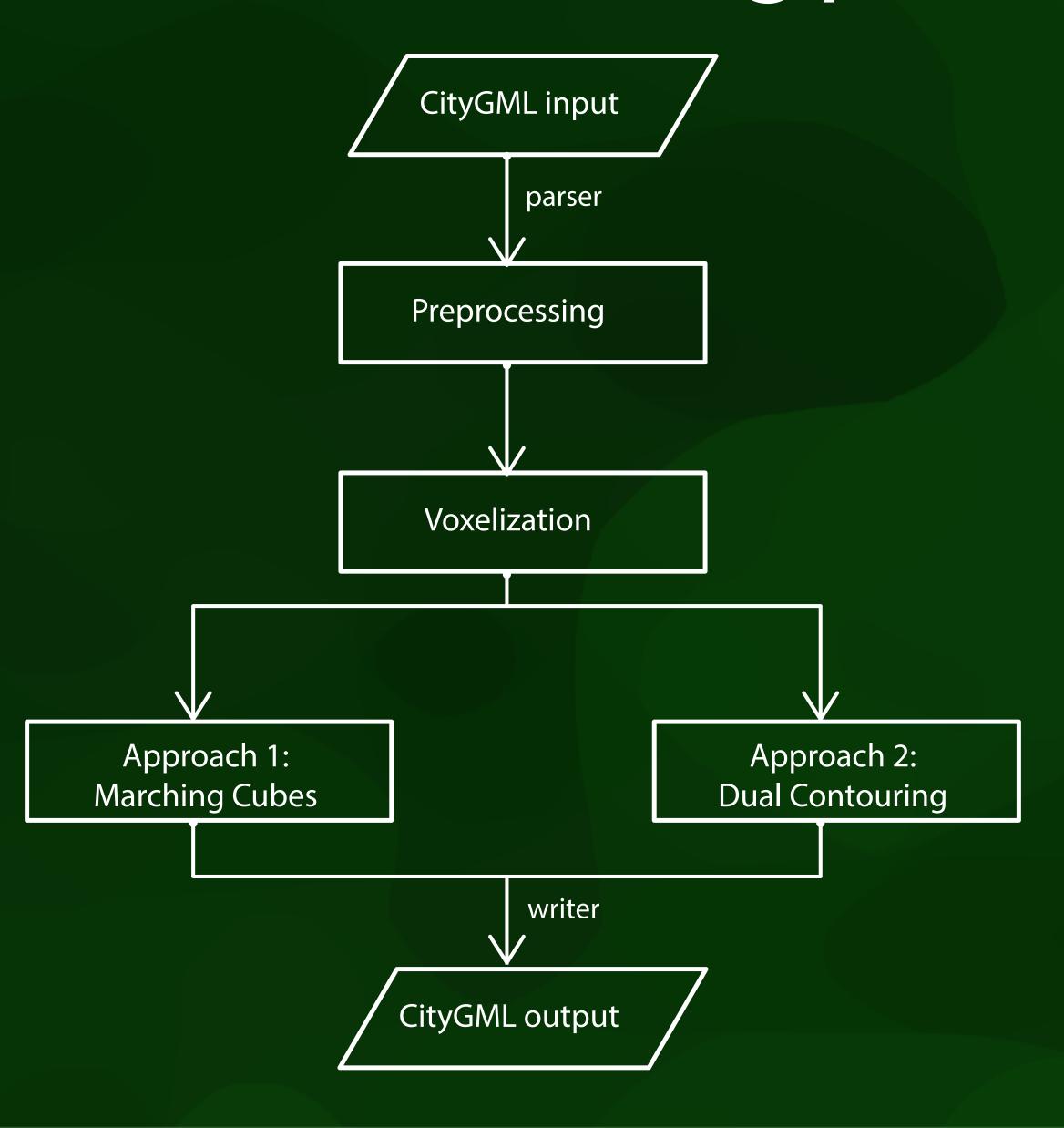
June 2015

Fixing 3D models

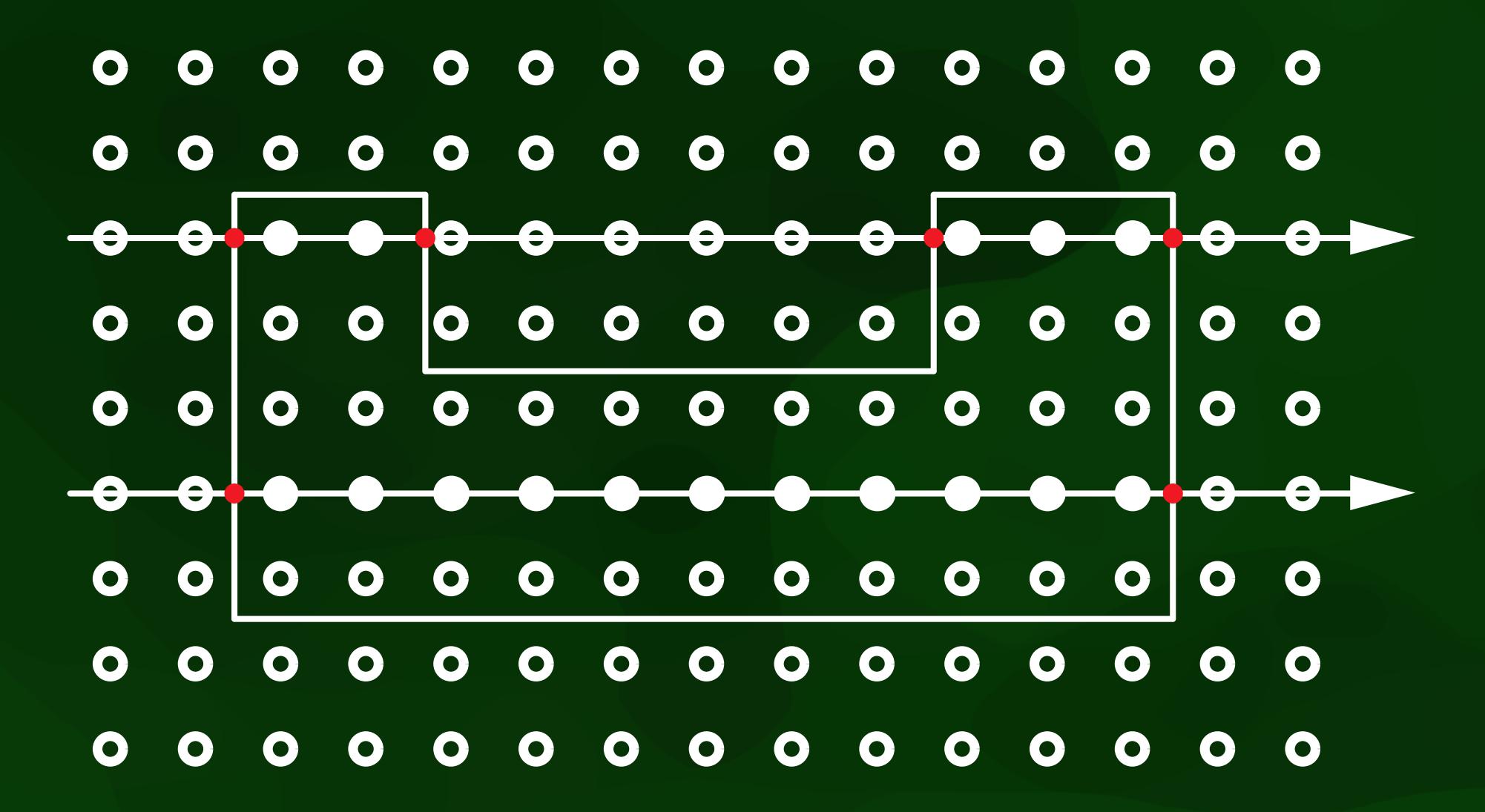




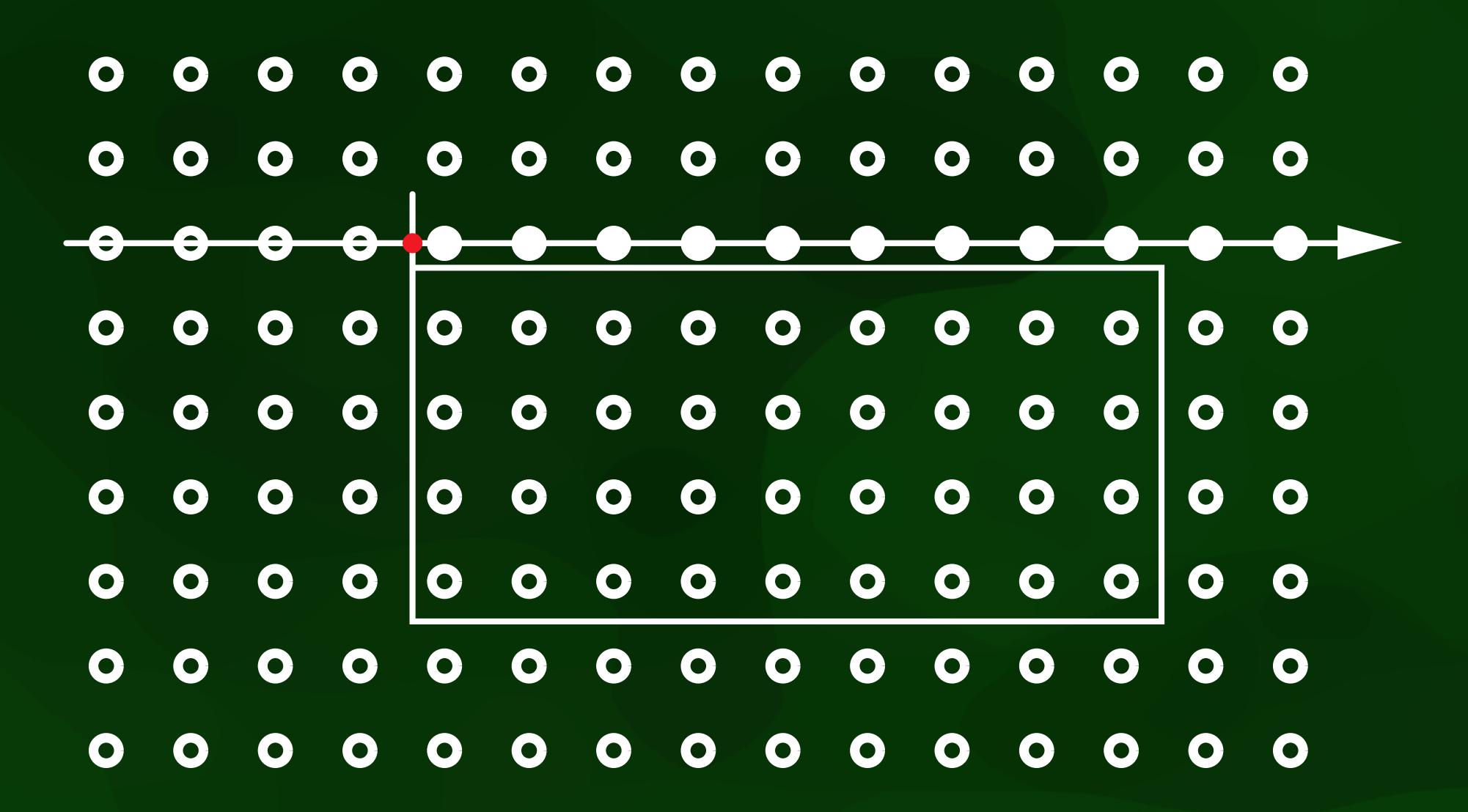
Methodology



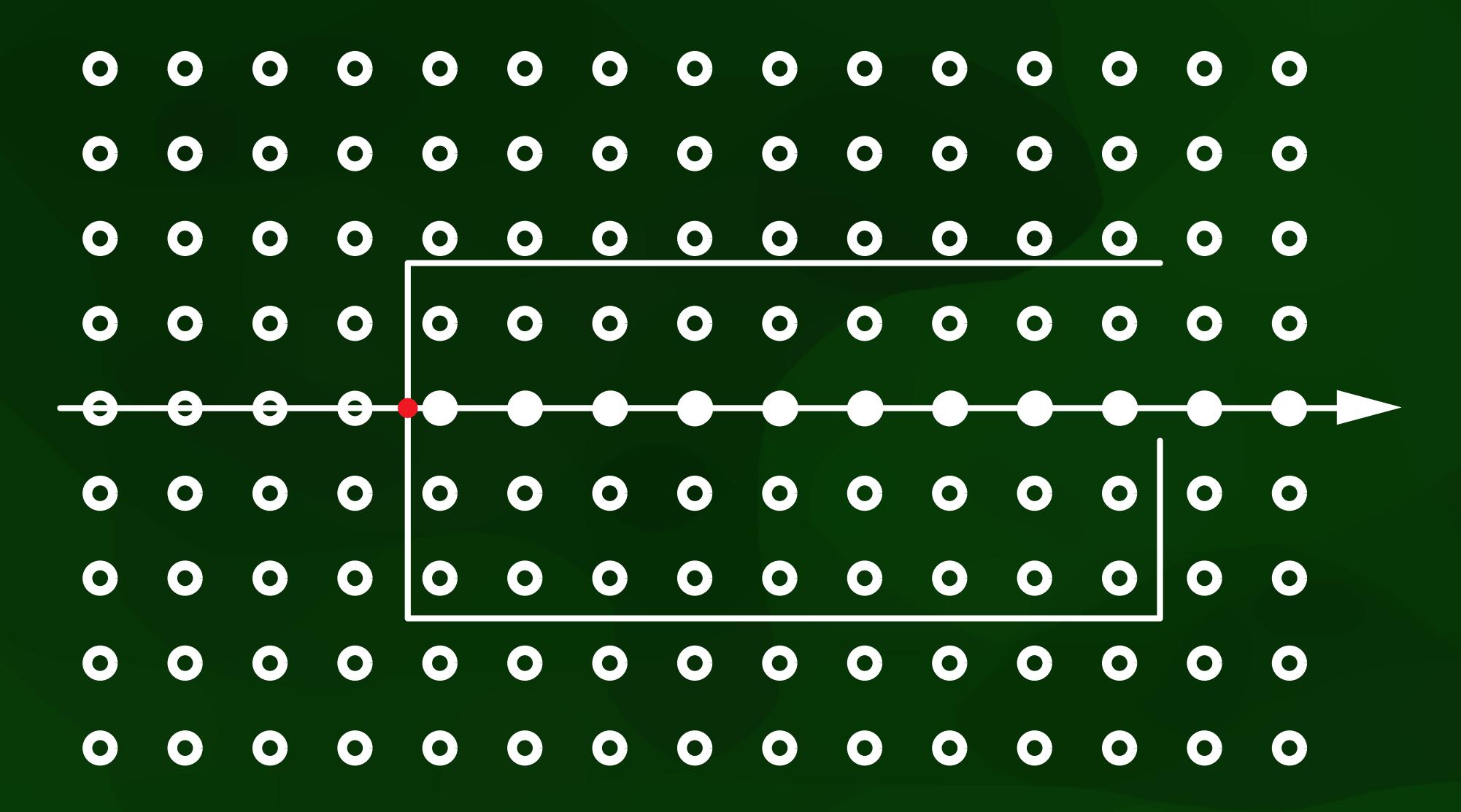
Voxelisation



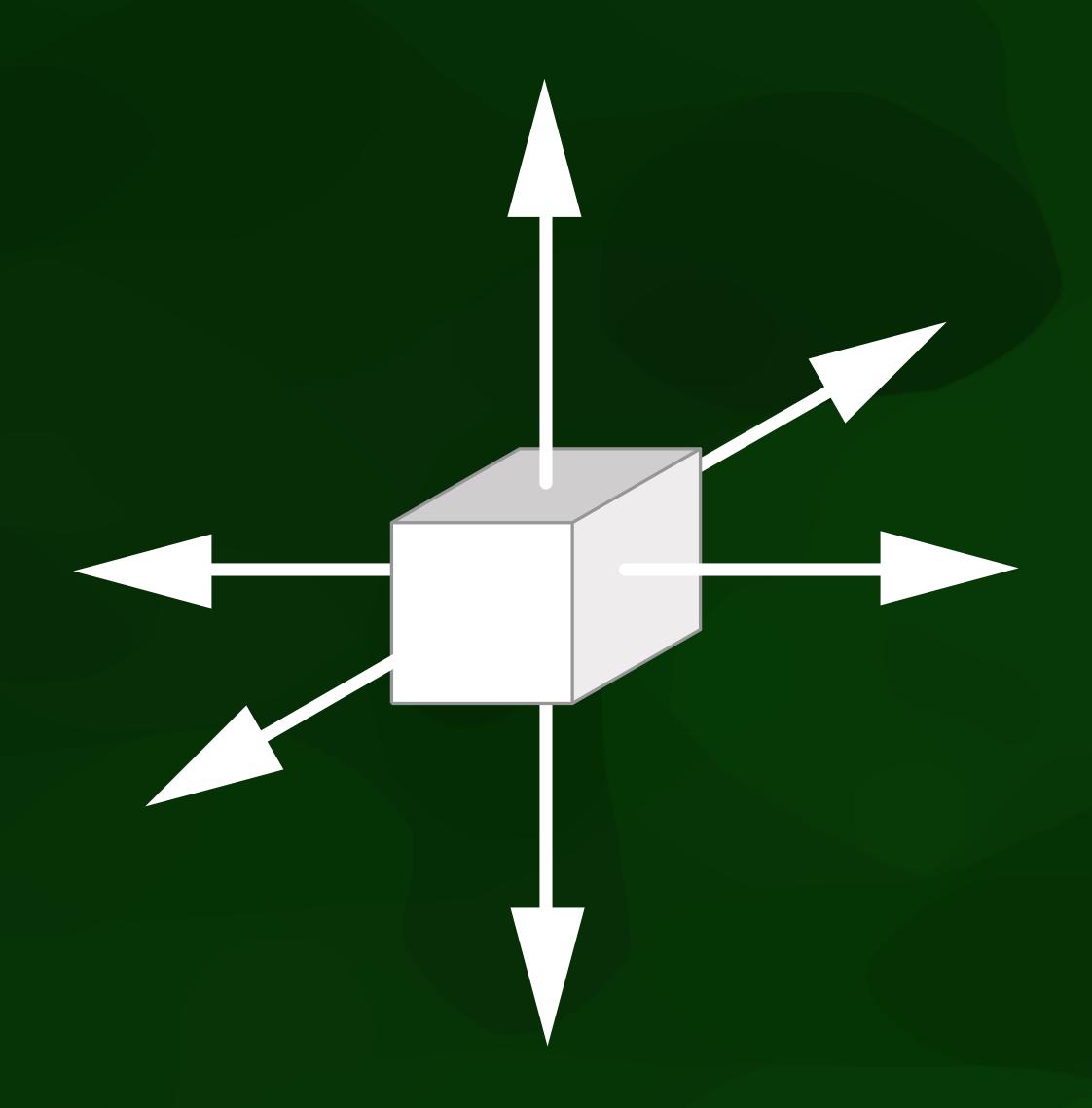
Voxelisation: overshoot



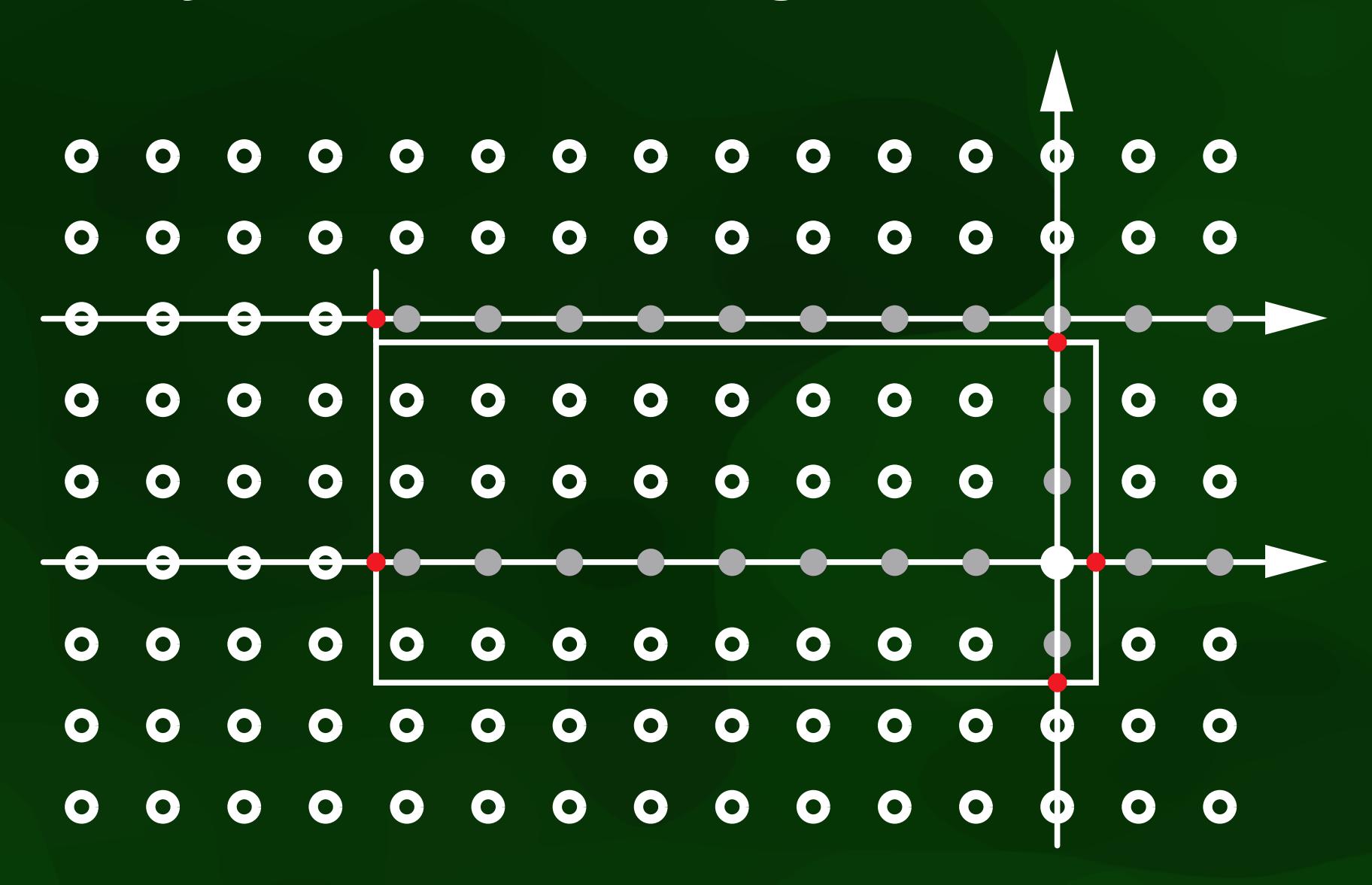
Voxelisation: gap



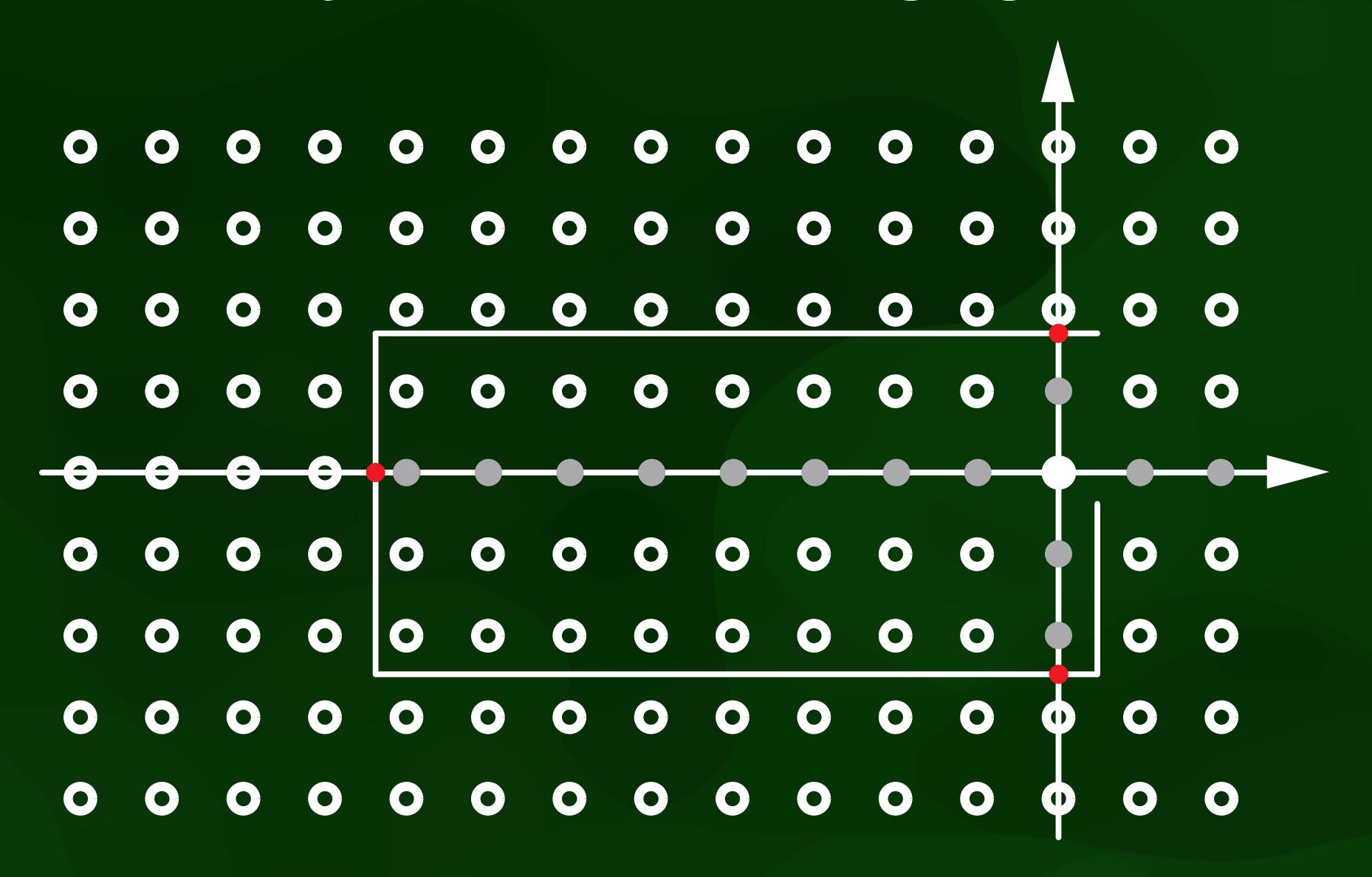
Voxelisation: shooting rays



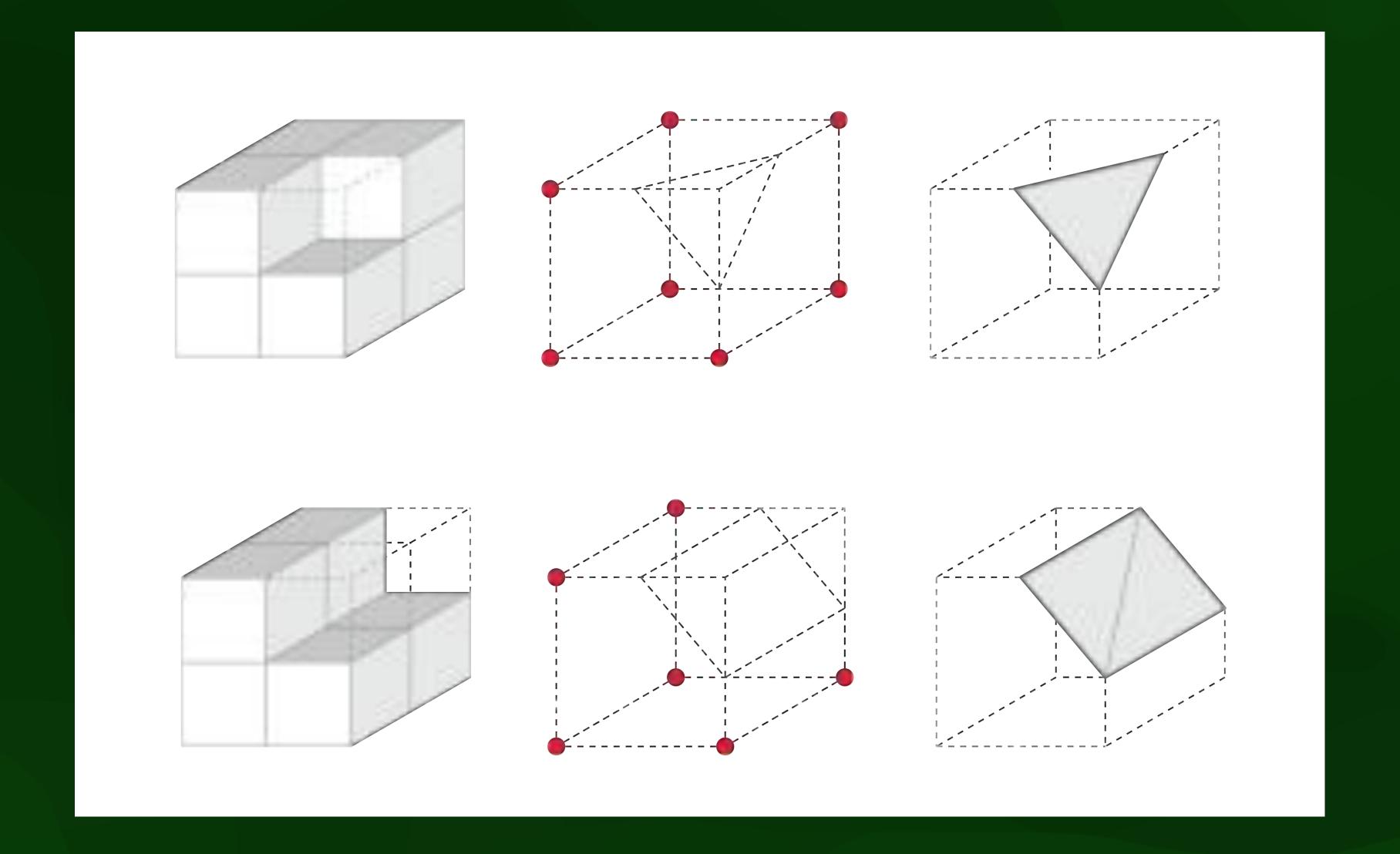
Majority counting: overshoot

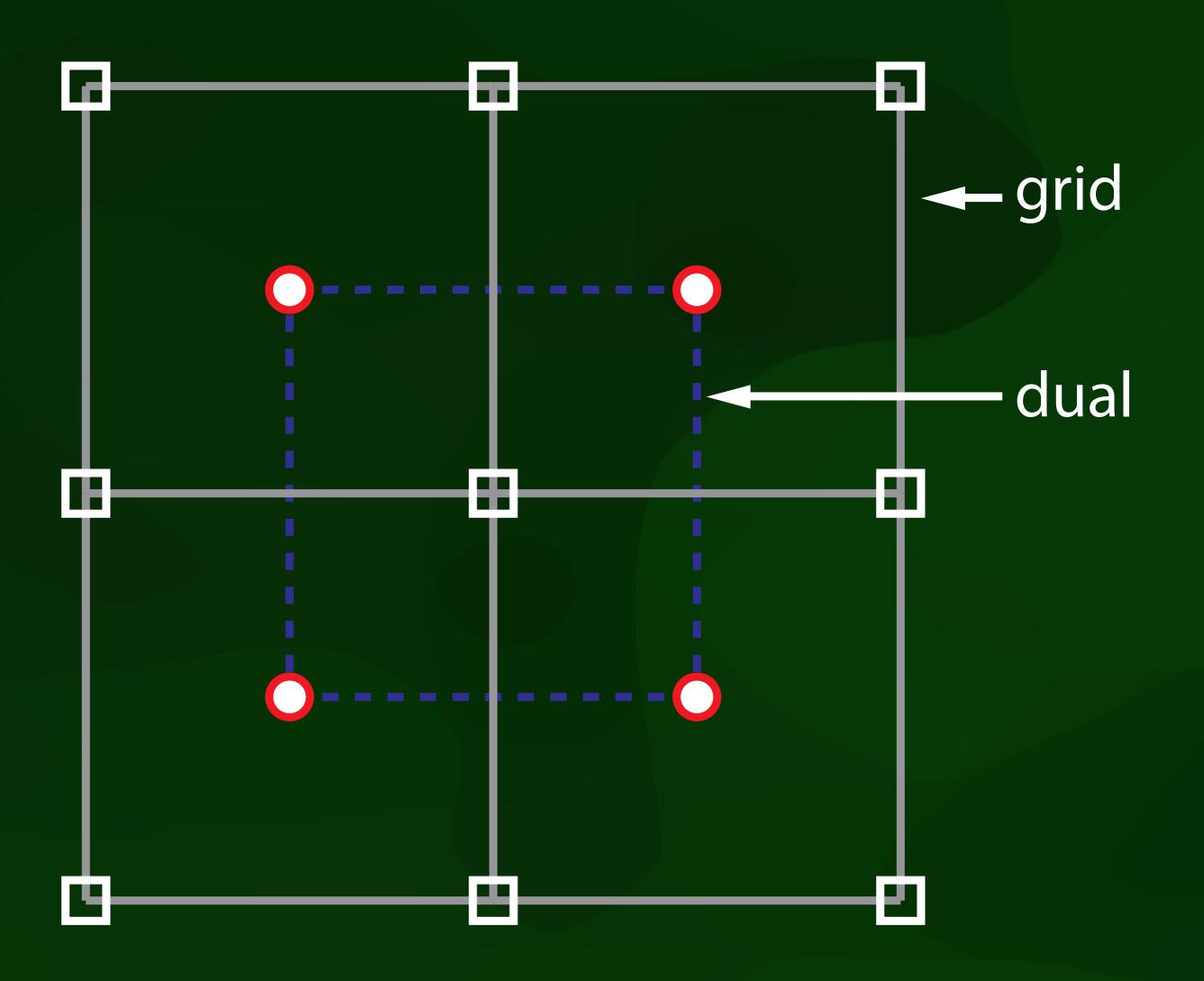


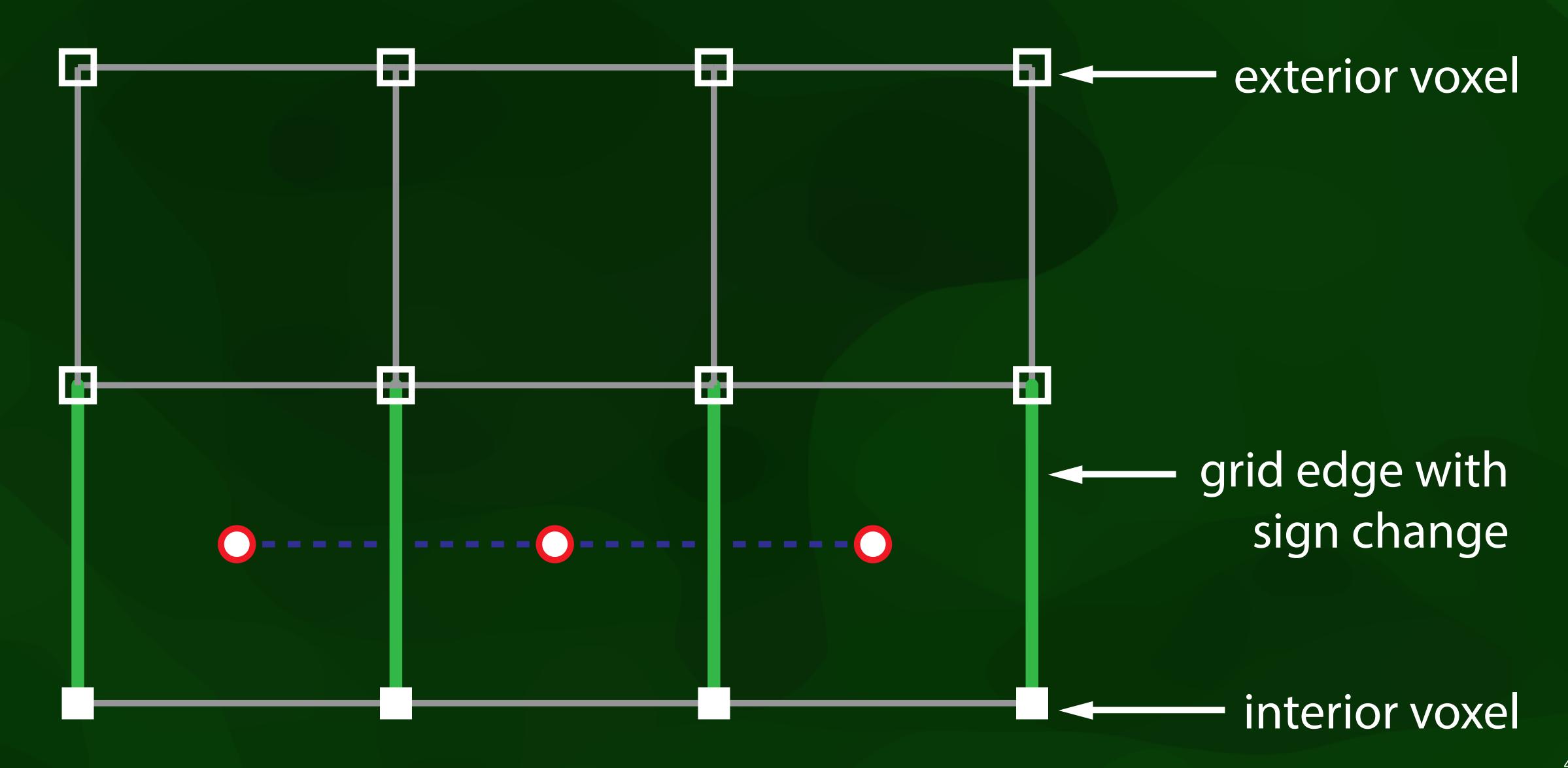
Majority counting: gap

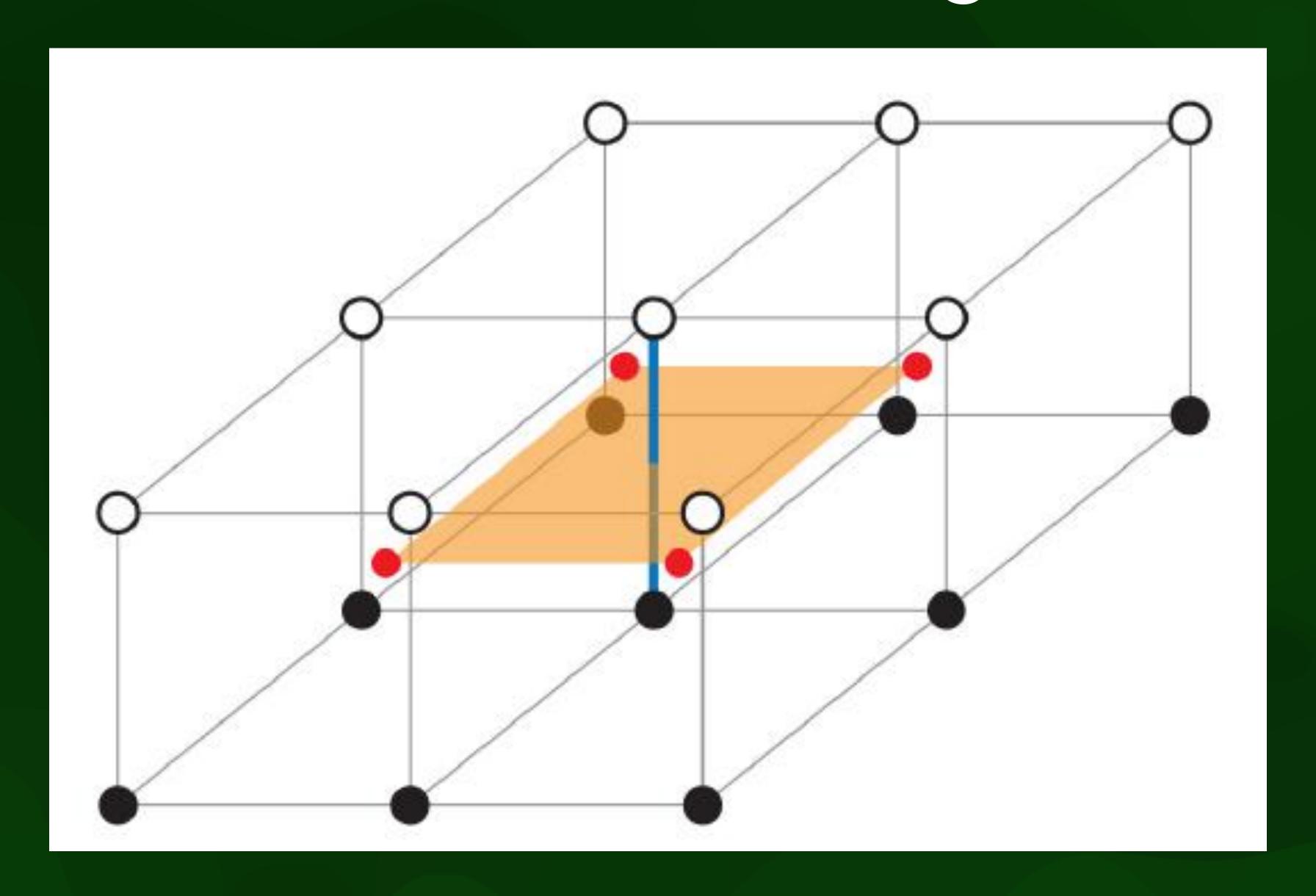


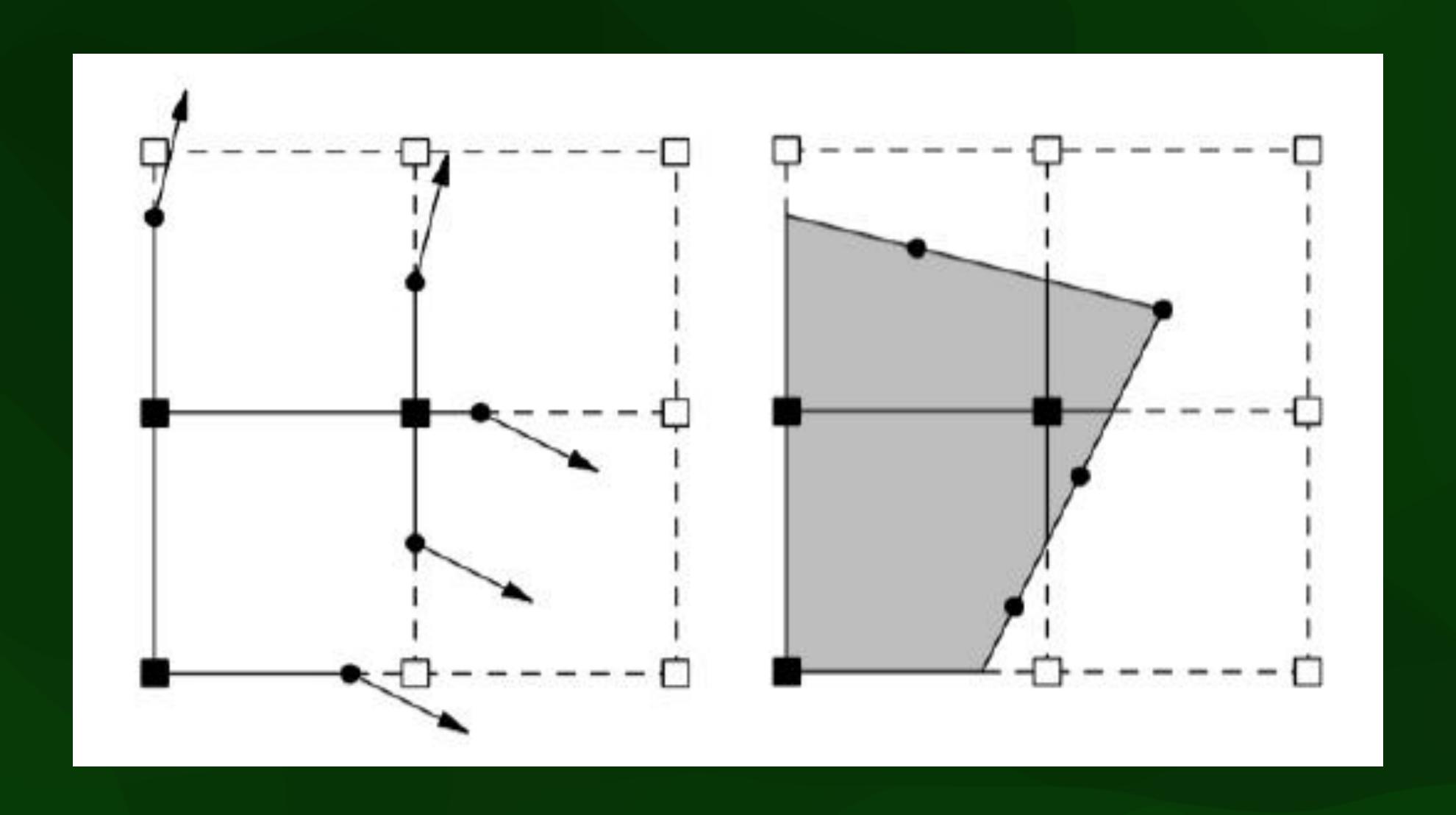
Marching cubes



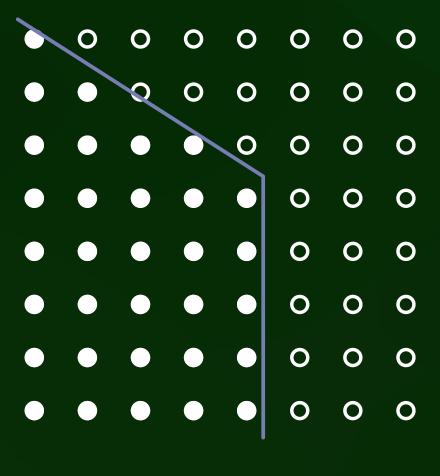


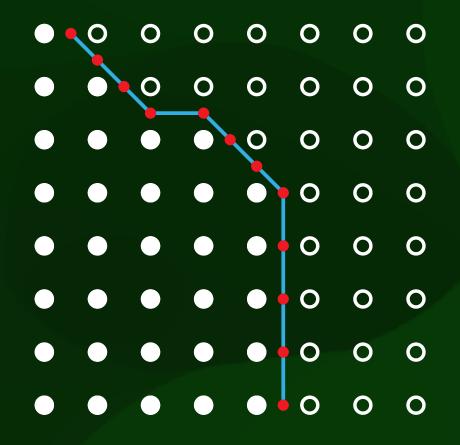






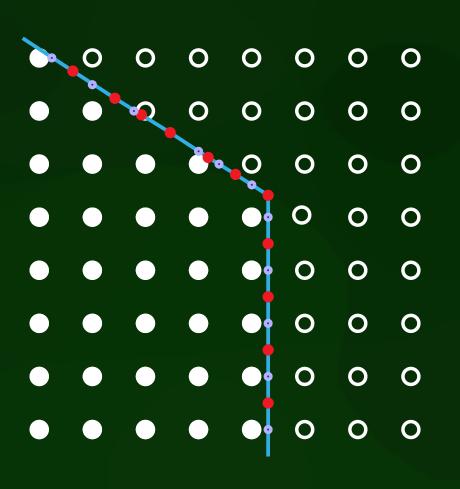
Full process

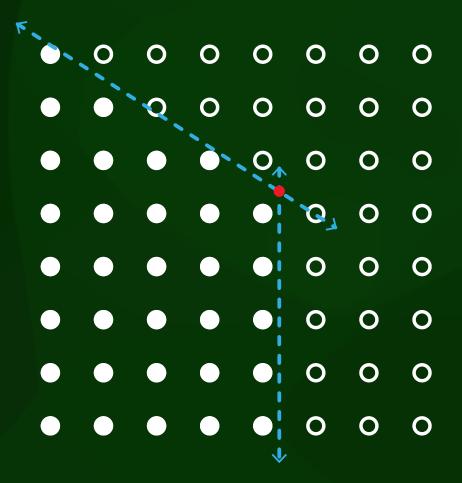






(b) Marching Cubes result

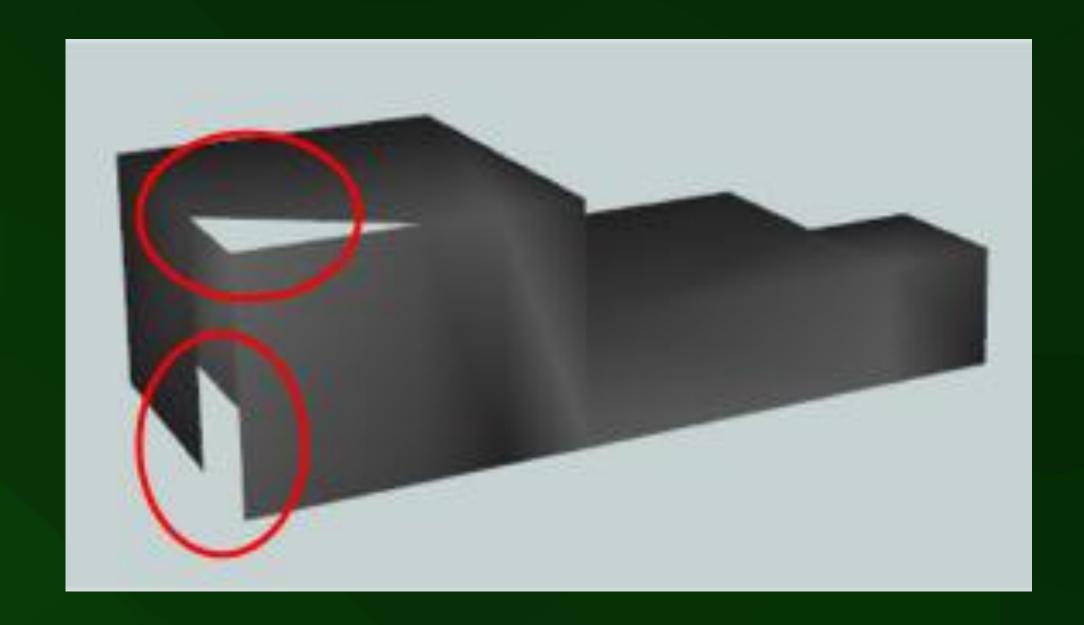


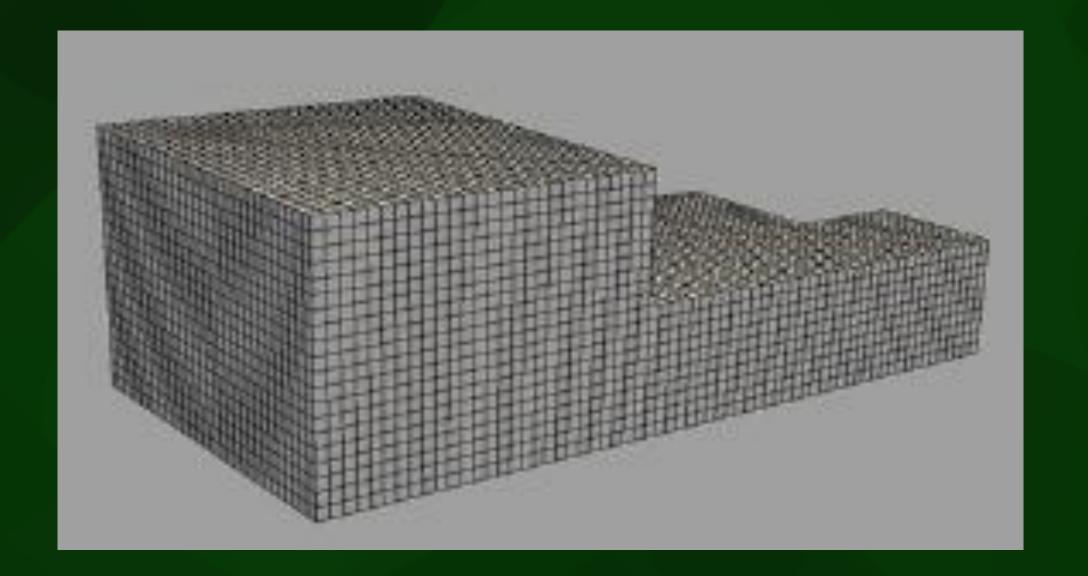


(c) Dual Contouring result

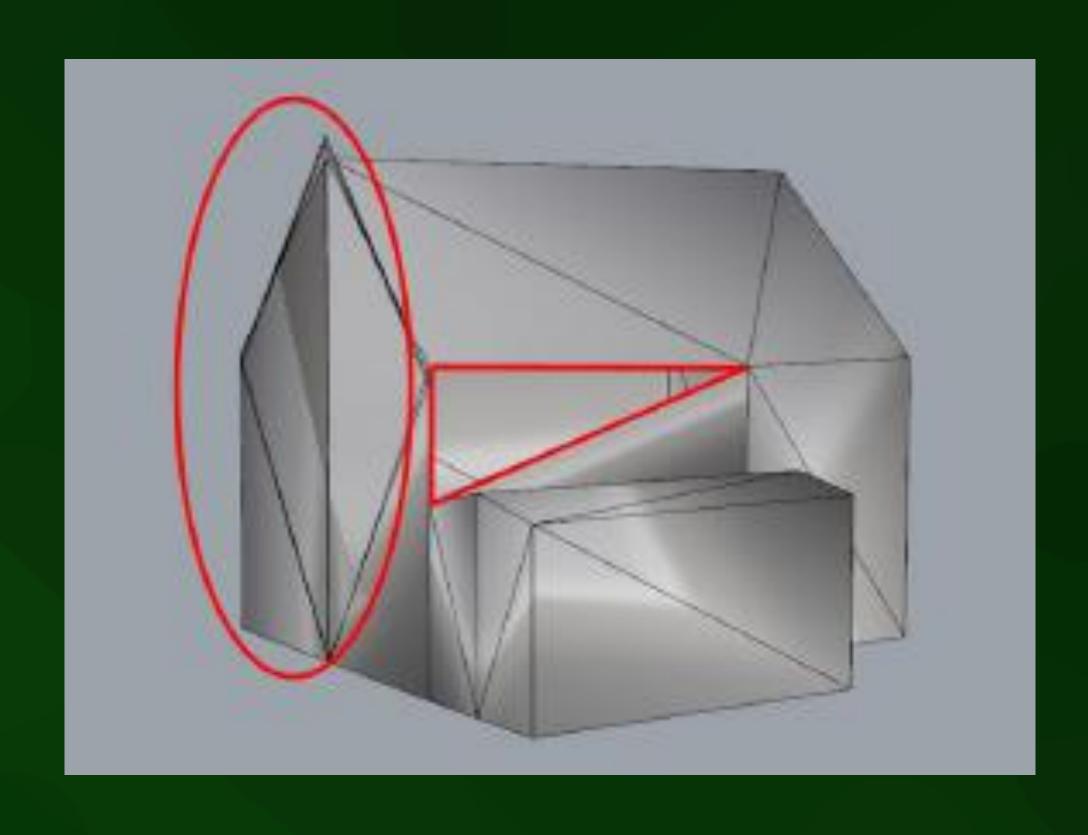
(d) Pressing result

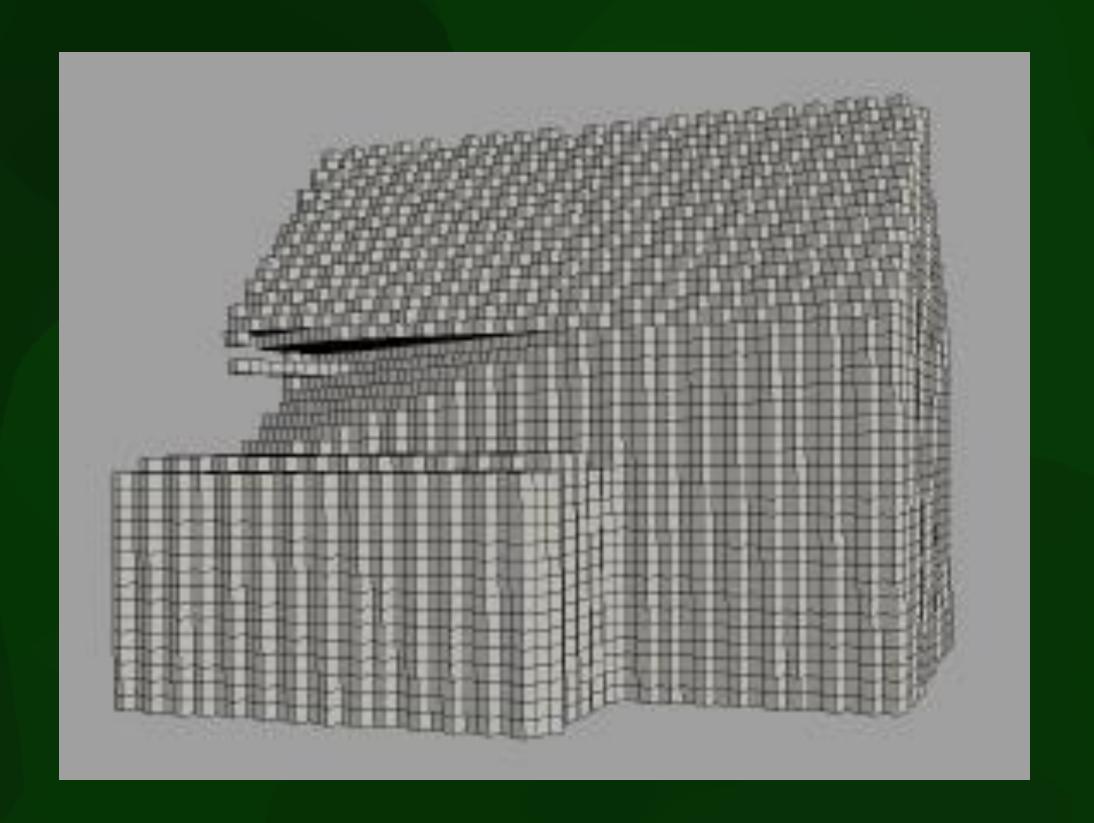
Results



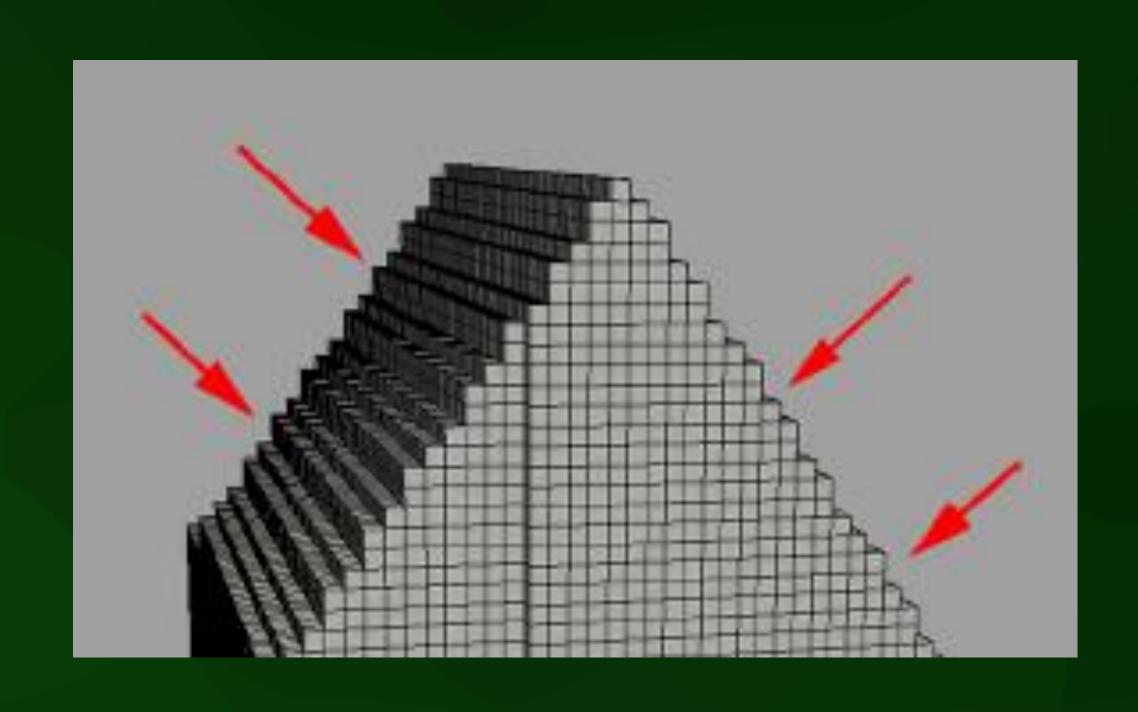


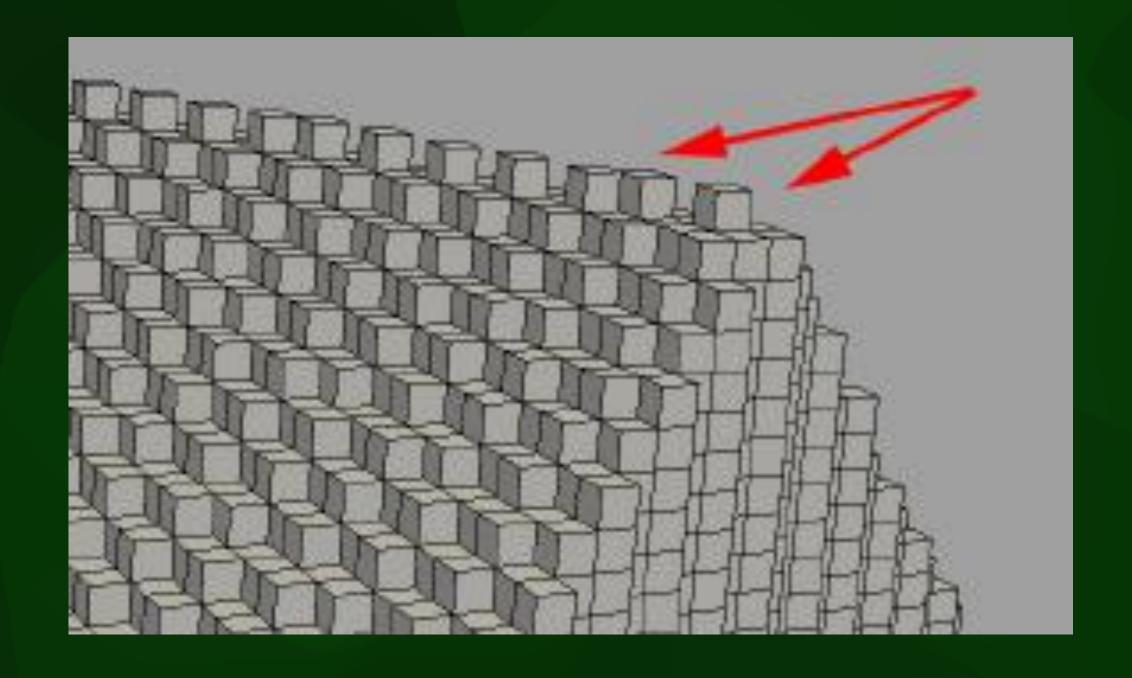
Results



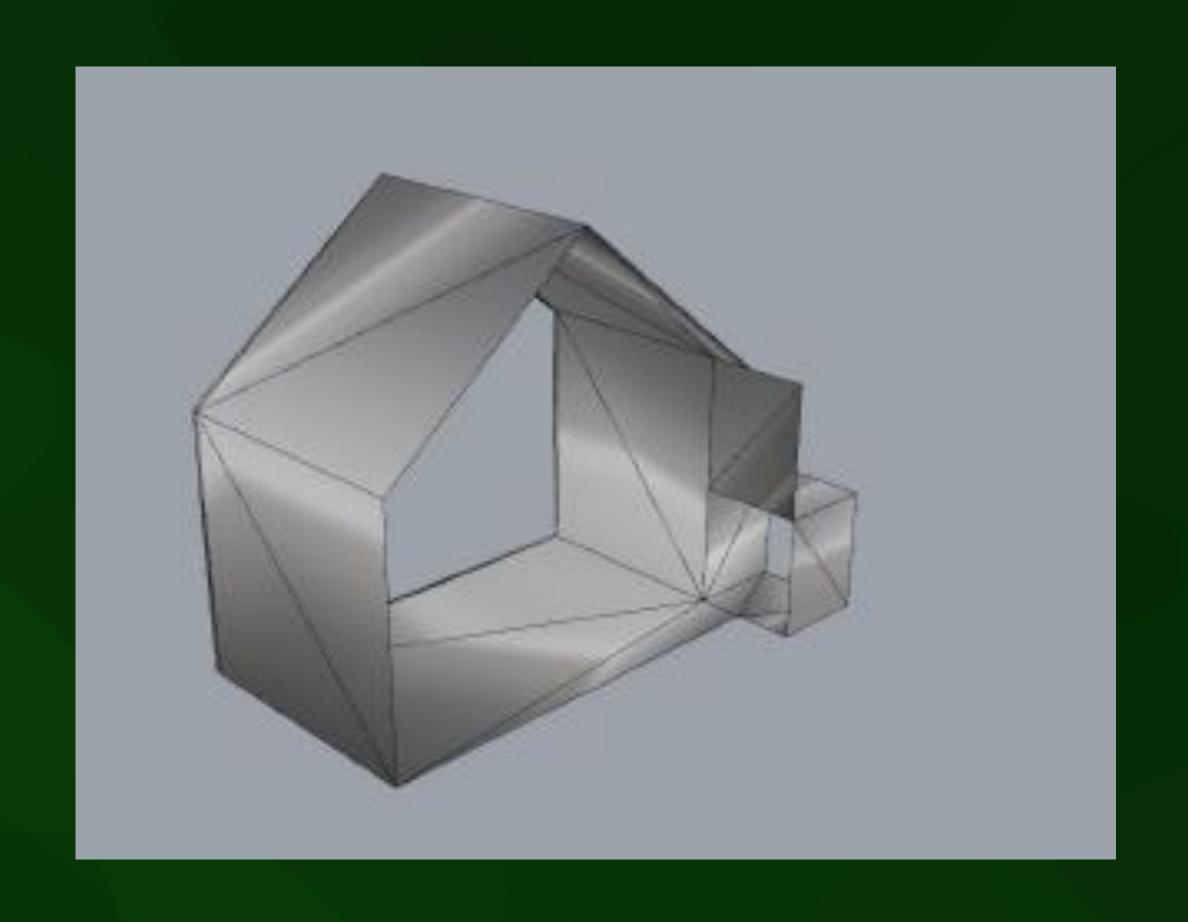


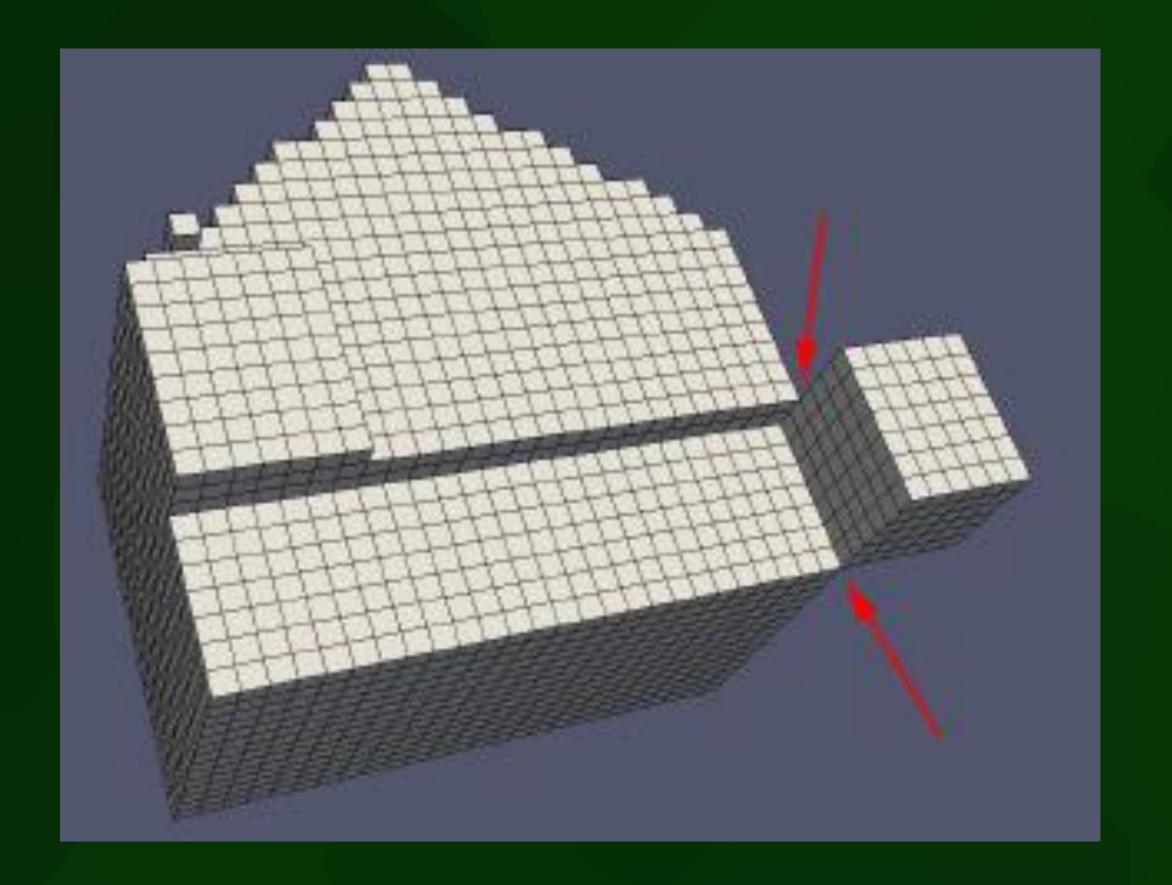
Artefacts



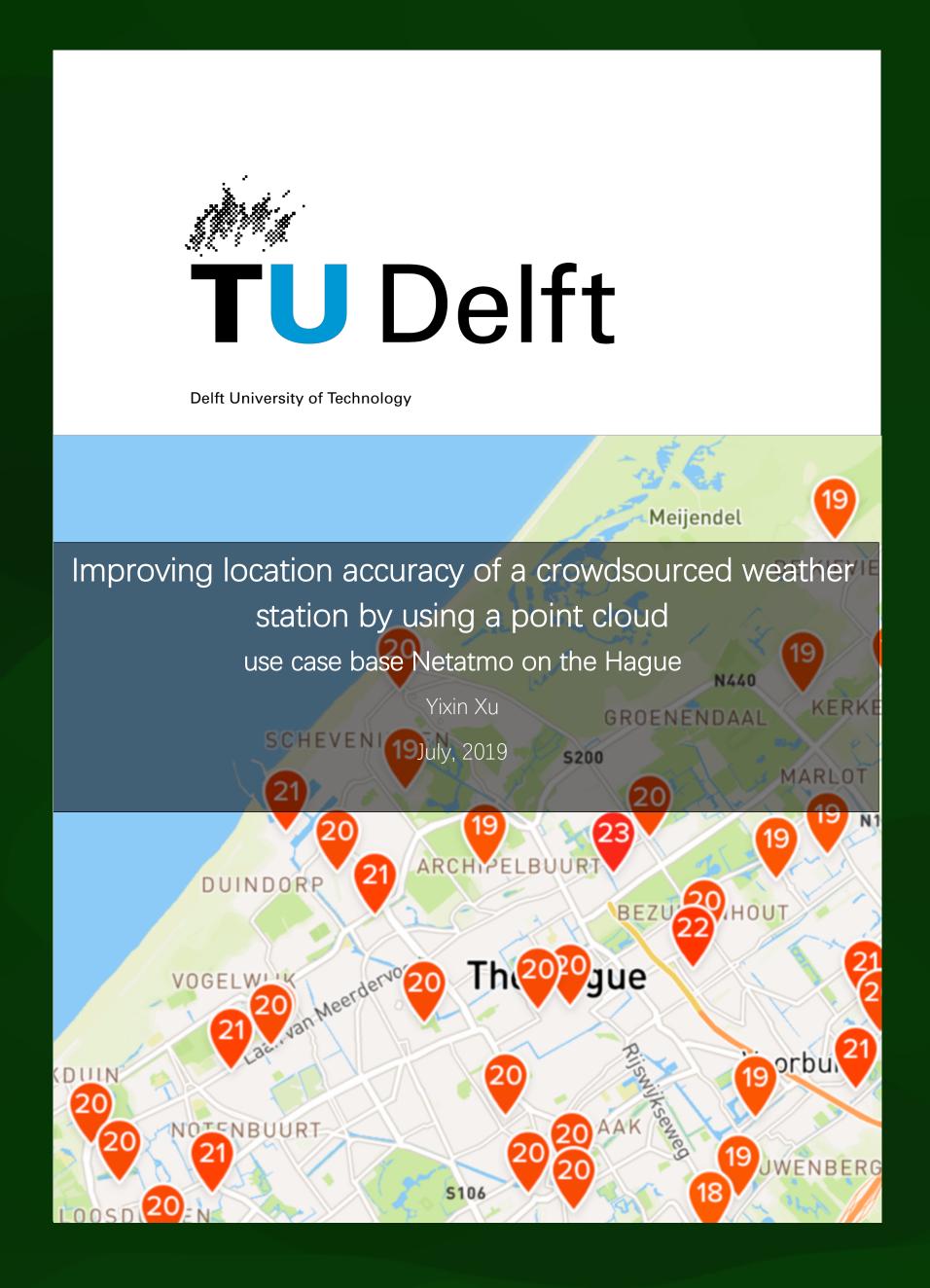


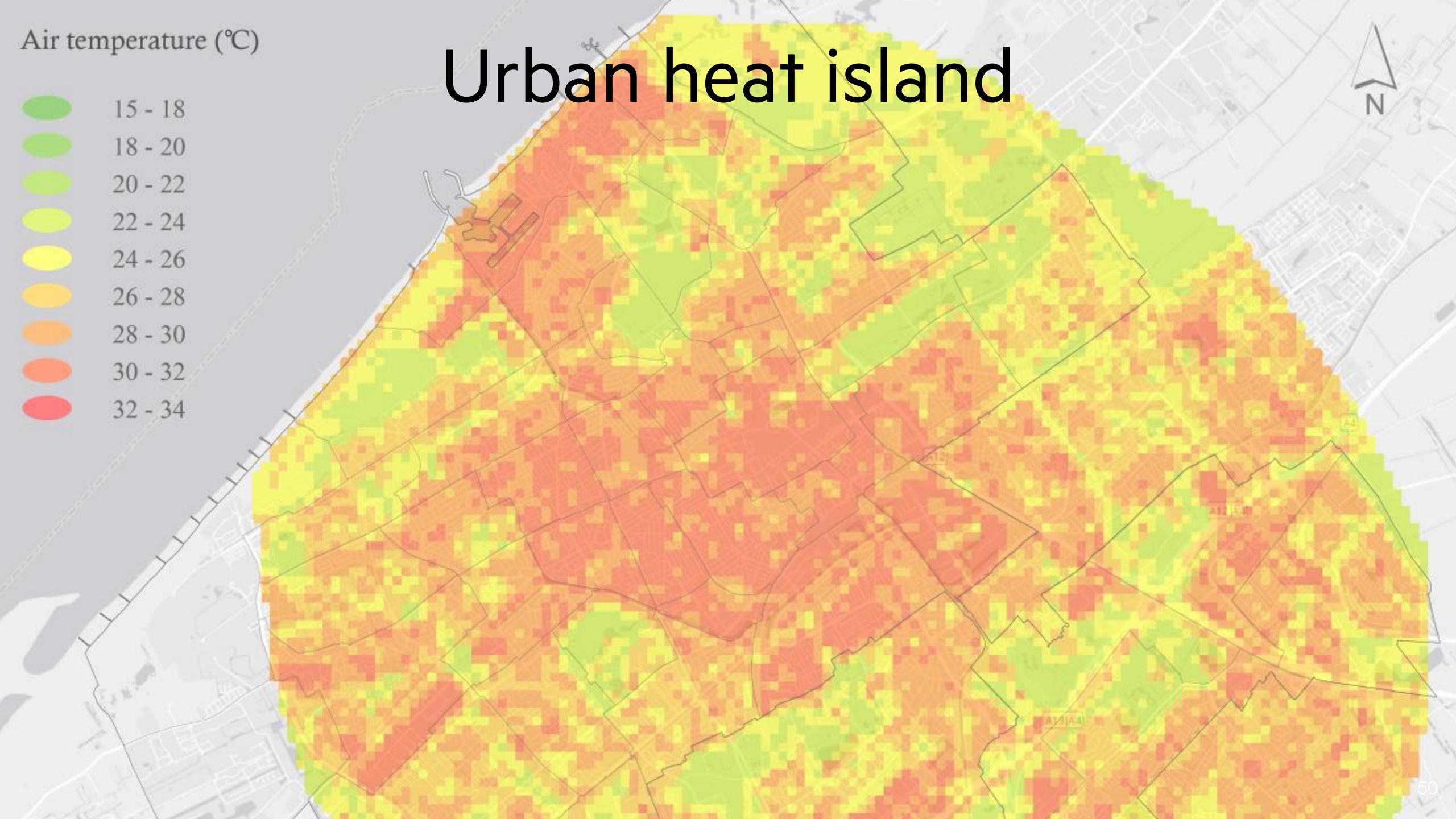
Results





- Motivation: improving the accuracy of the location of personal weather stations for urban heat island research
- Generate potential locations
- Evaluate them through skyview + solar modelling





Traditional weather stations



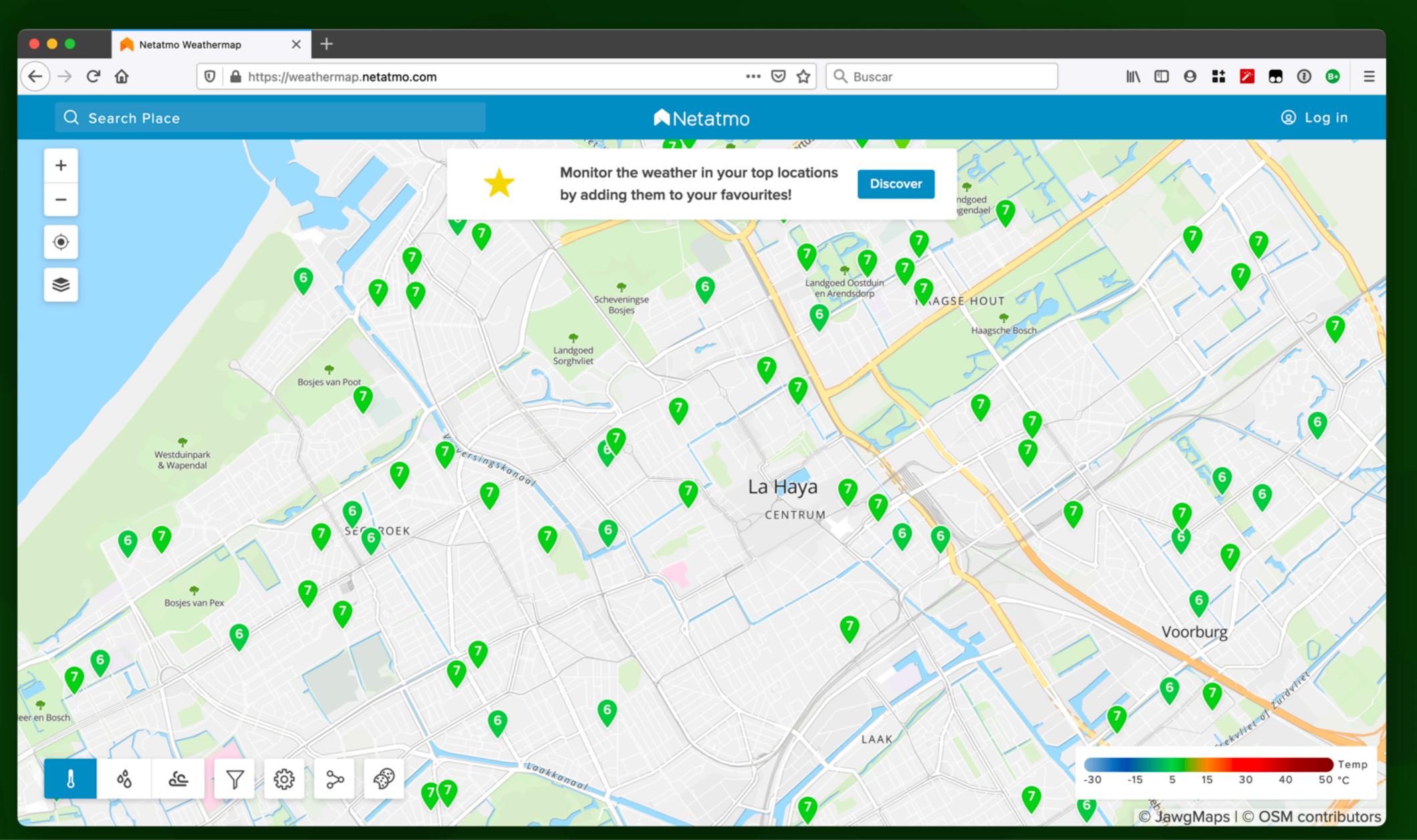
Personal weather stations

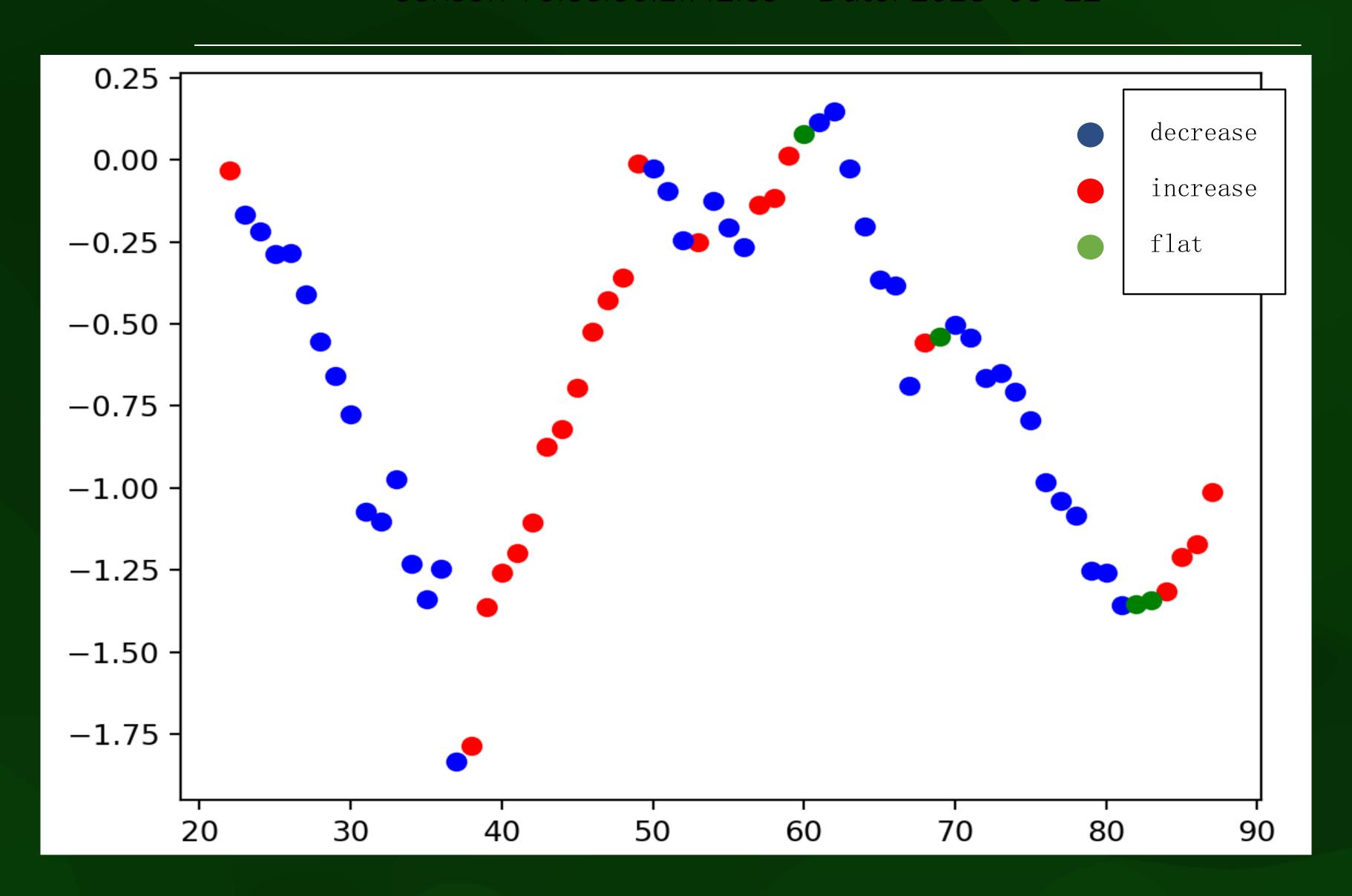




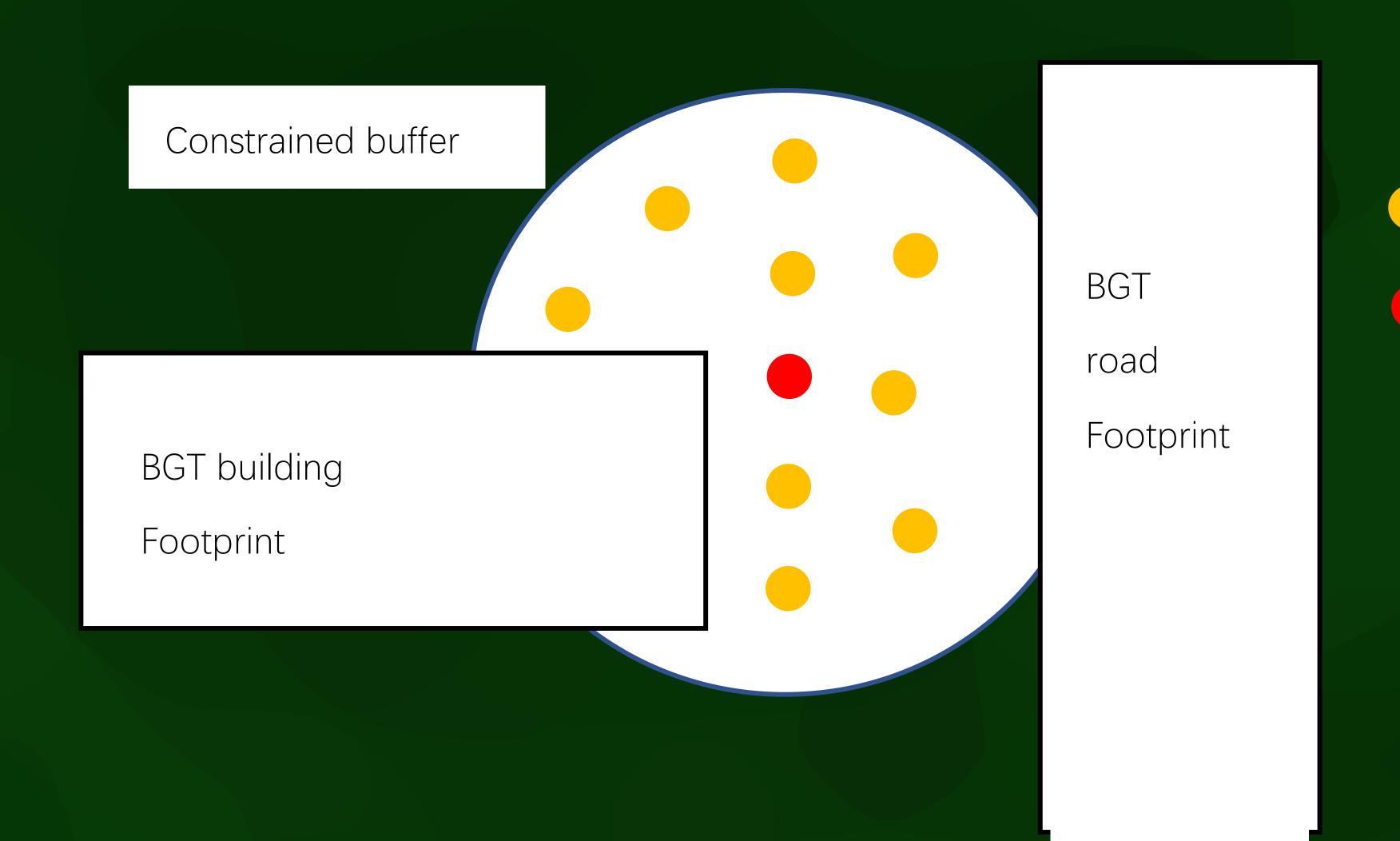


Crowdsourced weather data





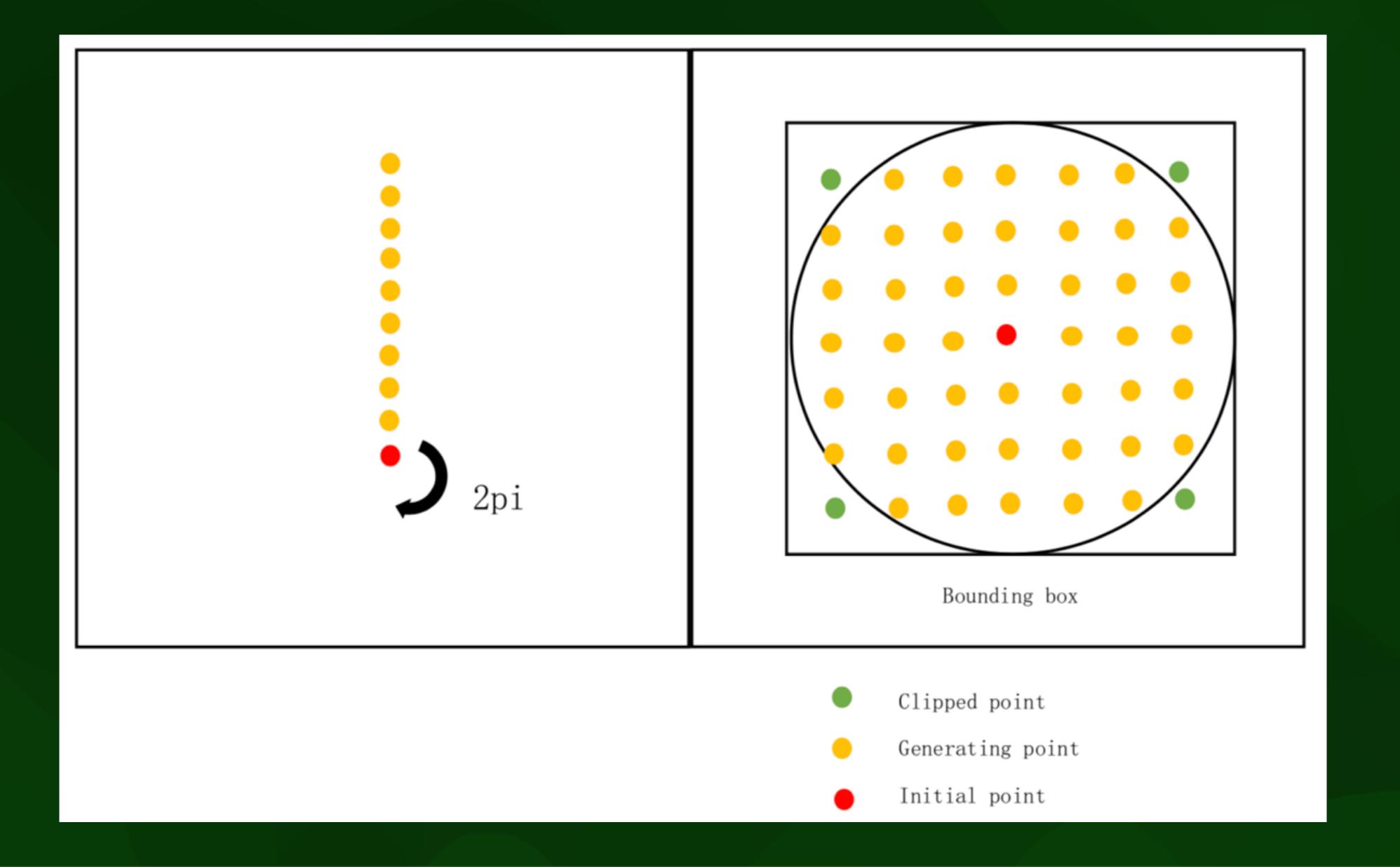
Potential locations



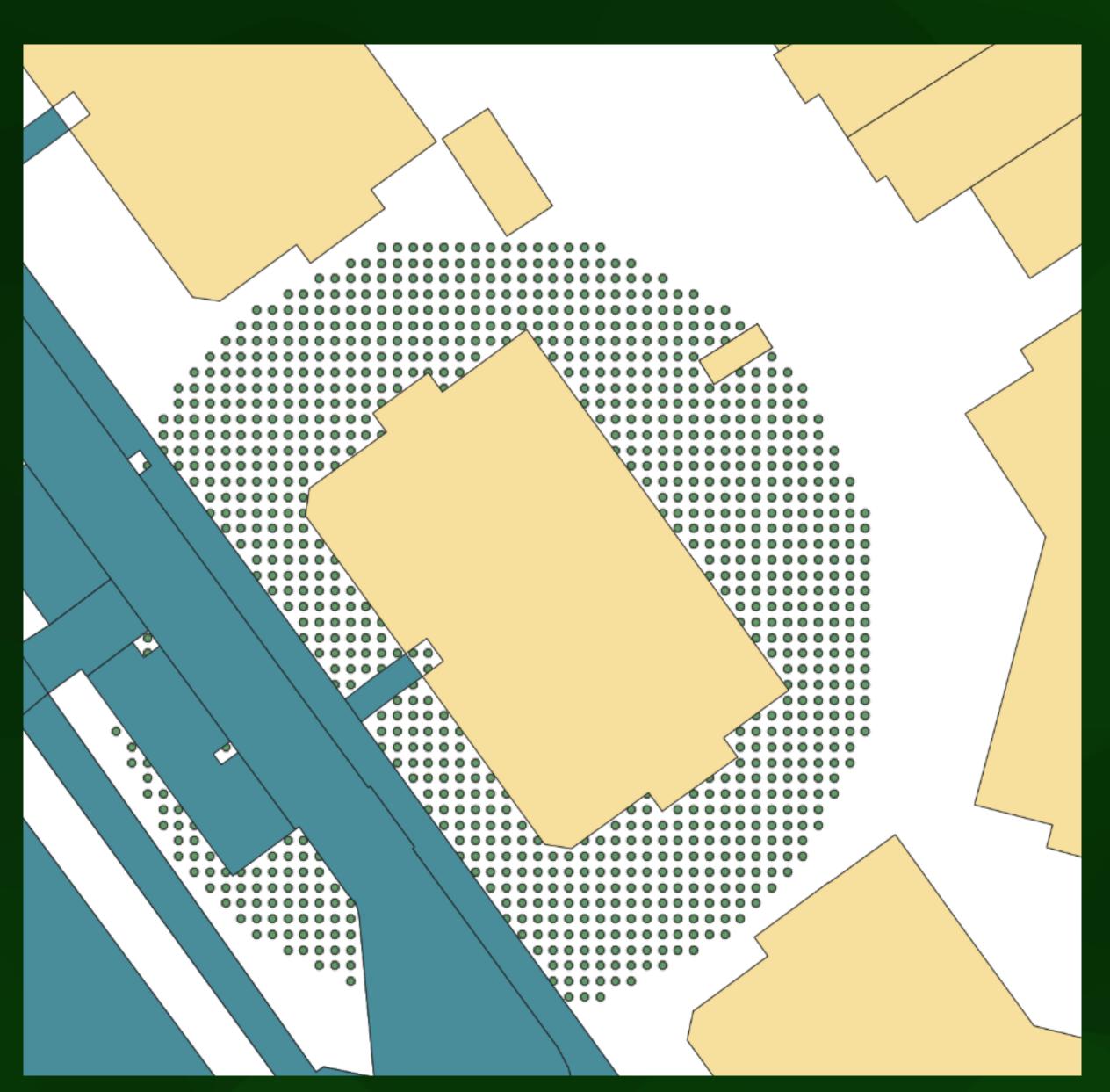
Potential location

Given location

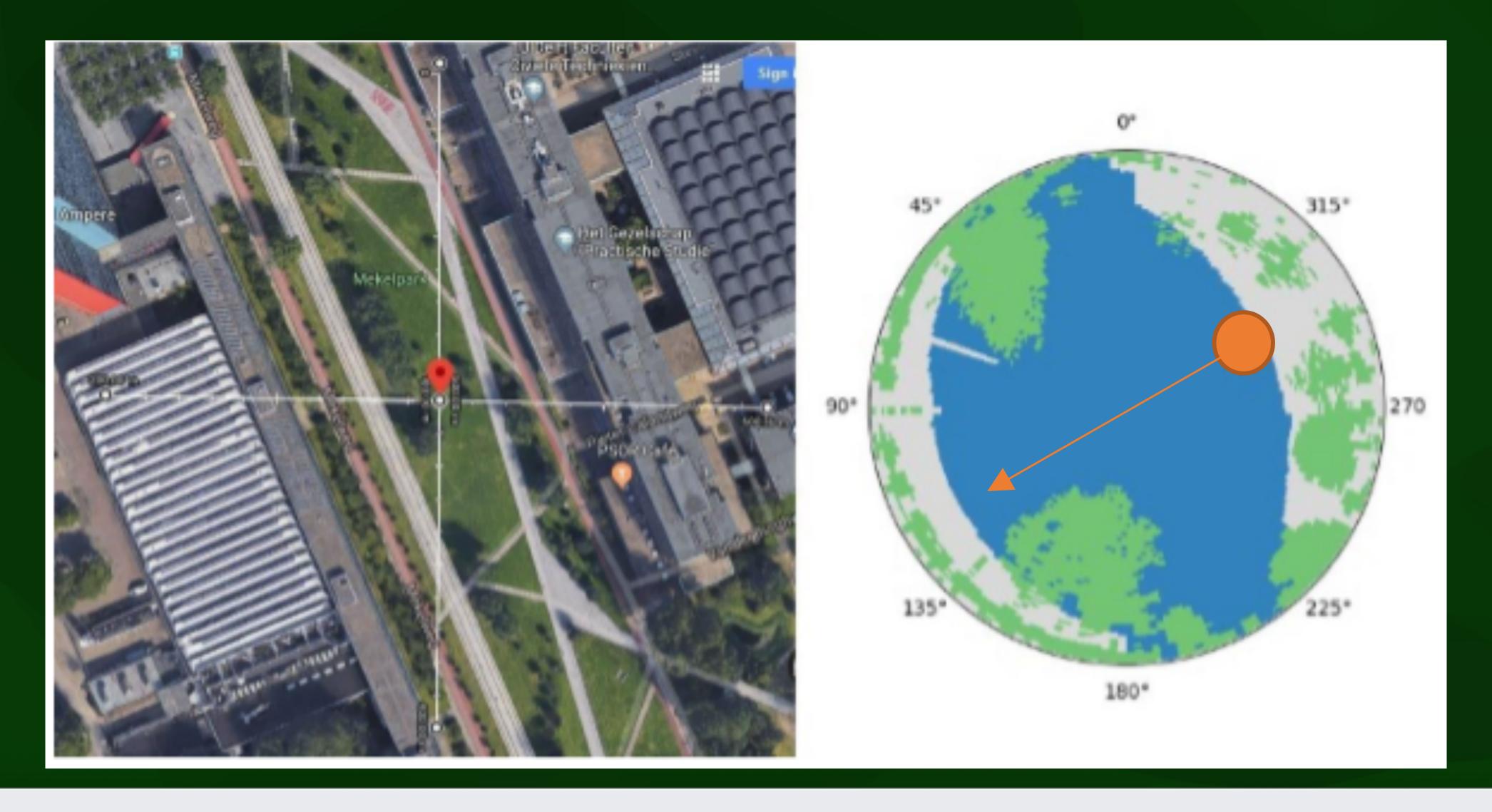
Potential locations



Potential locations



Skyview computation





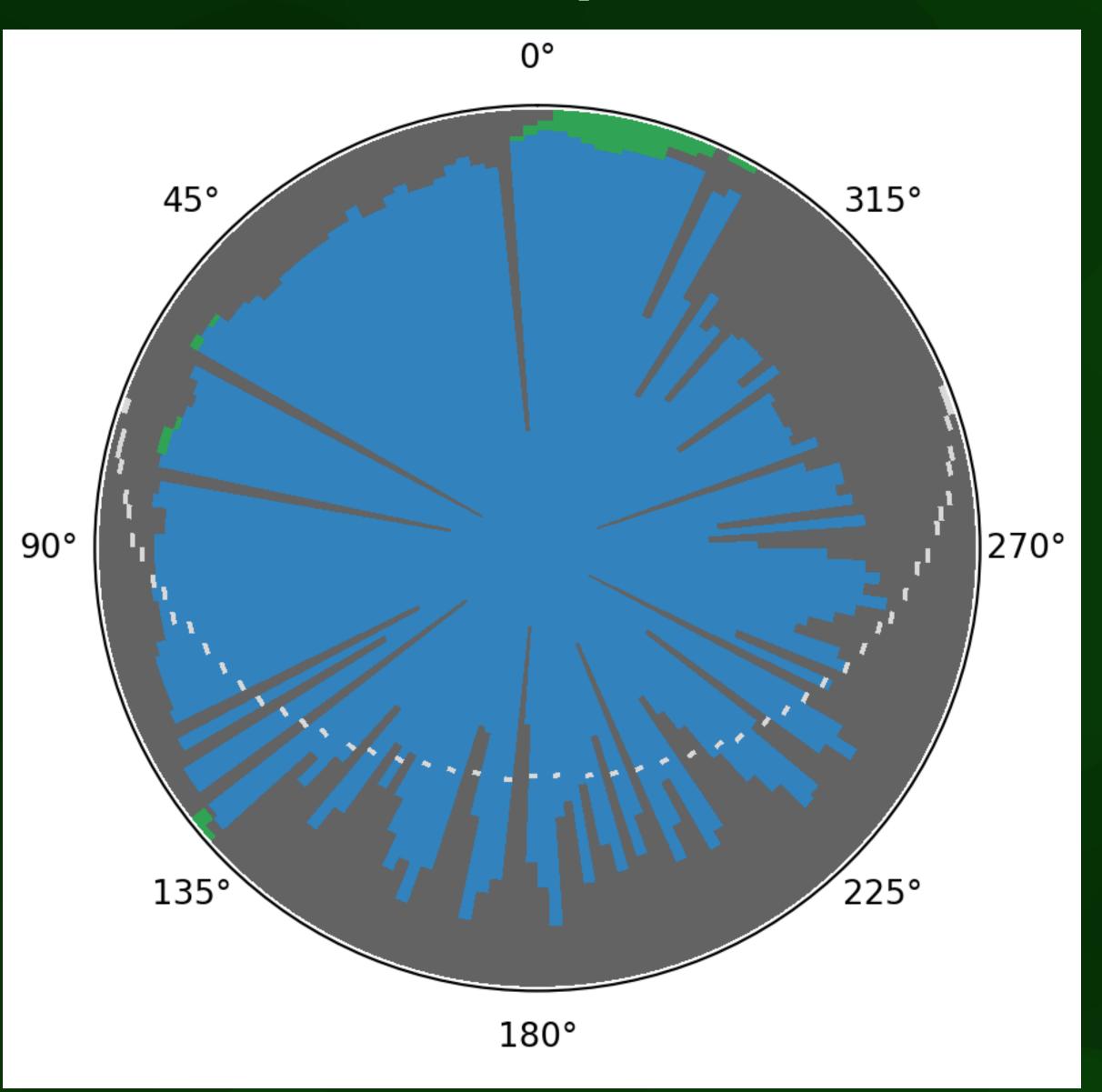




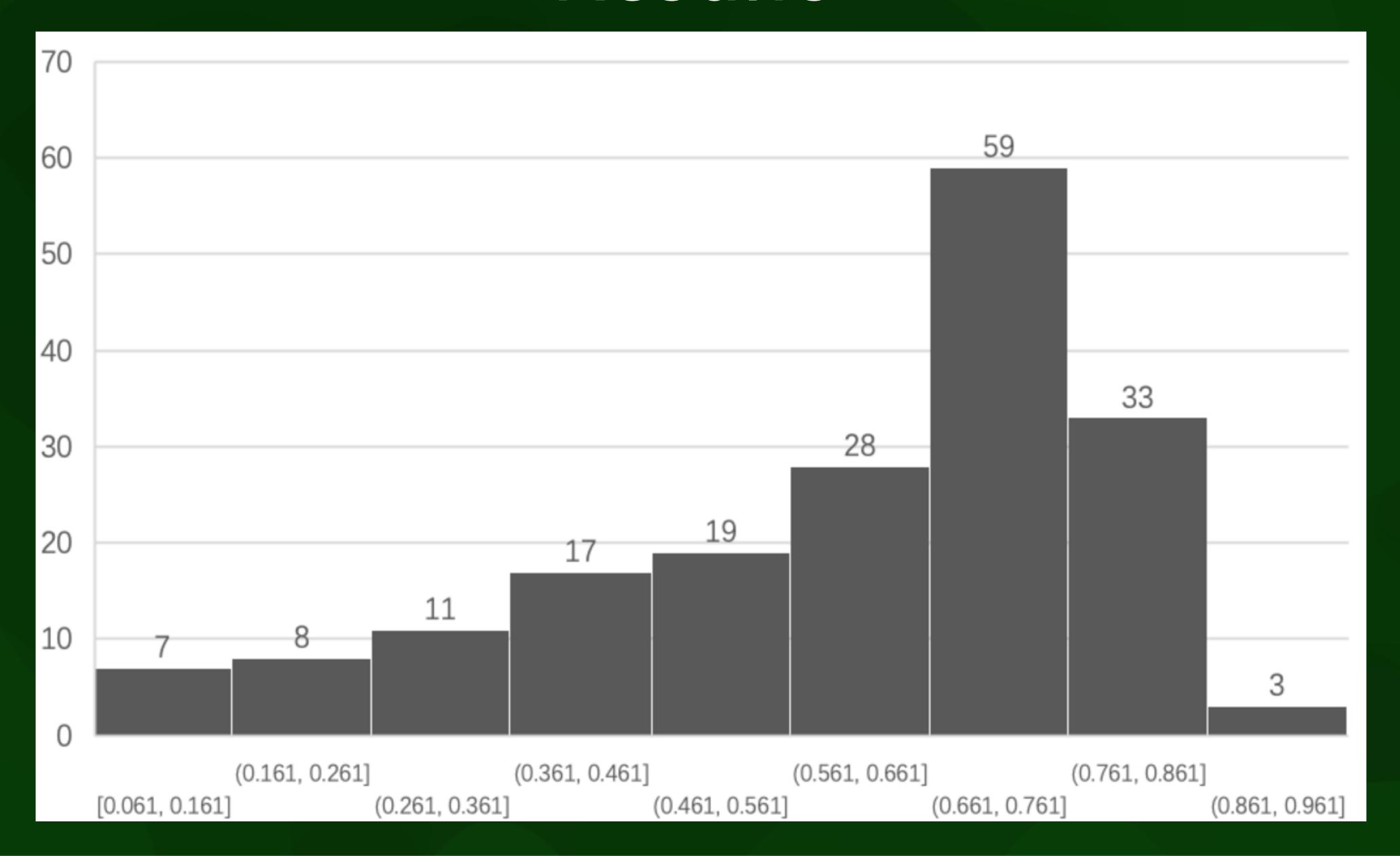




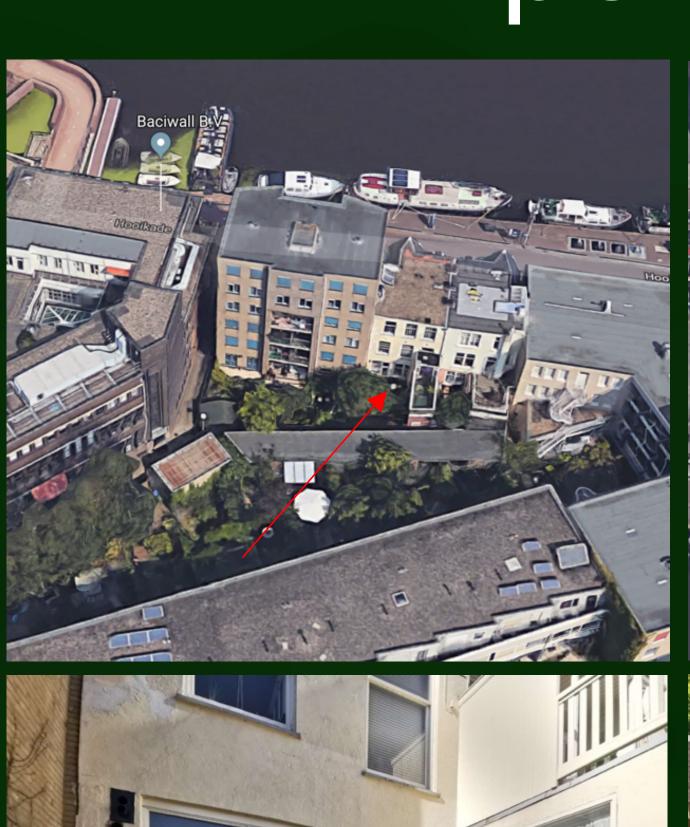
Analysis

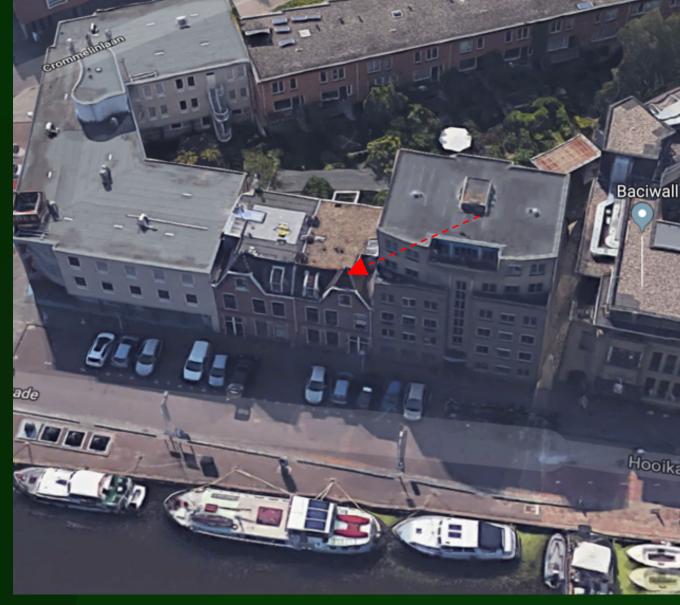


Results



Experiment

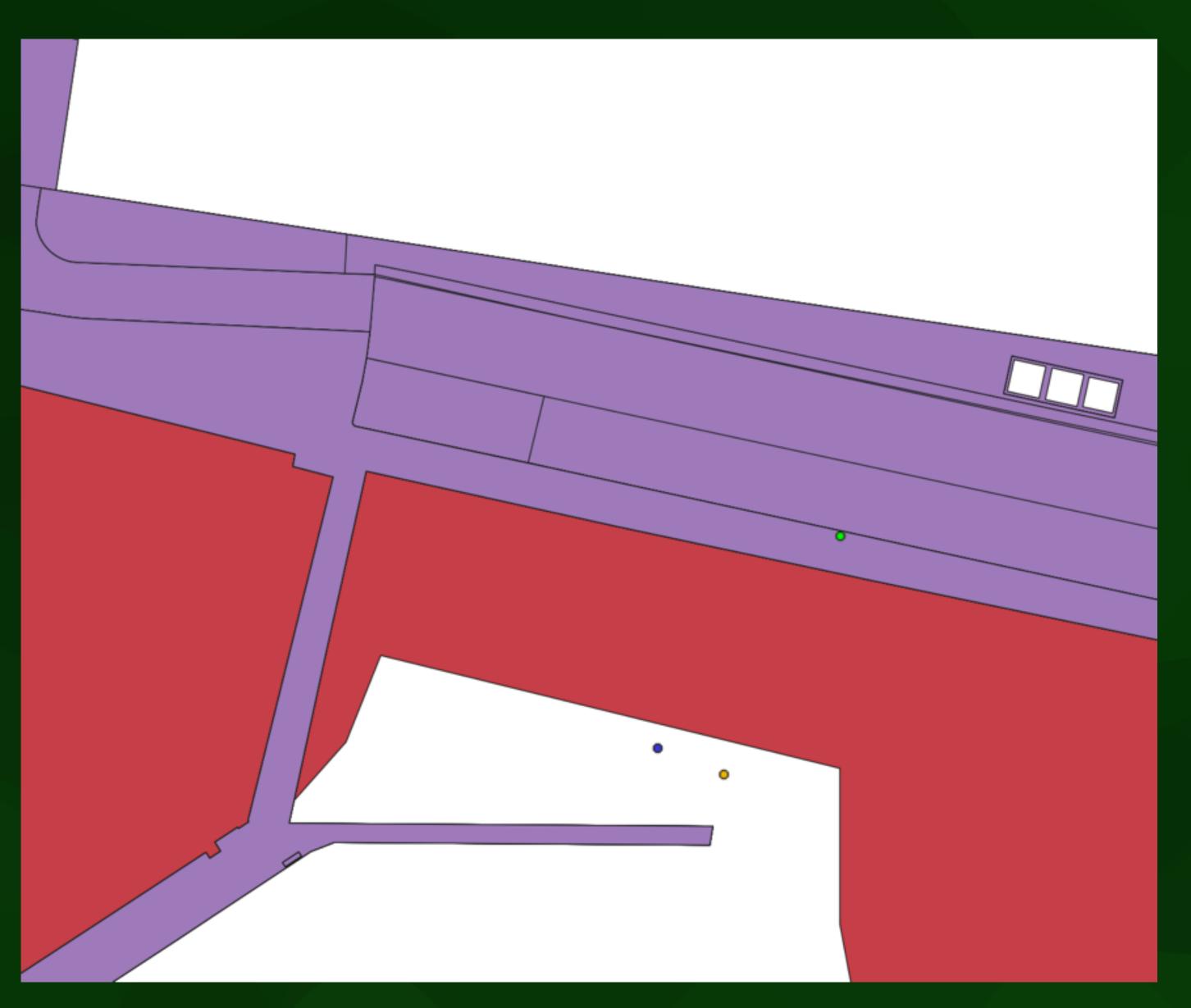








Experiment



- Motivation: automate some (simple)
 building permit checks using a 3DCM
- Formalisation of regulations
- Store necessary data in CityJSON extension
- Automate some checks (car + bicycle parking)

MSc thesis in Geomatics

Automatic building permits checks by means of 3D city models

Jialun Wu 2021



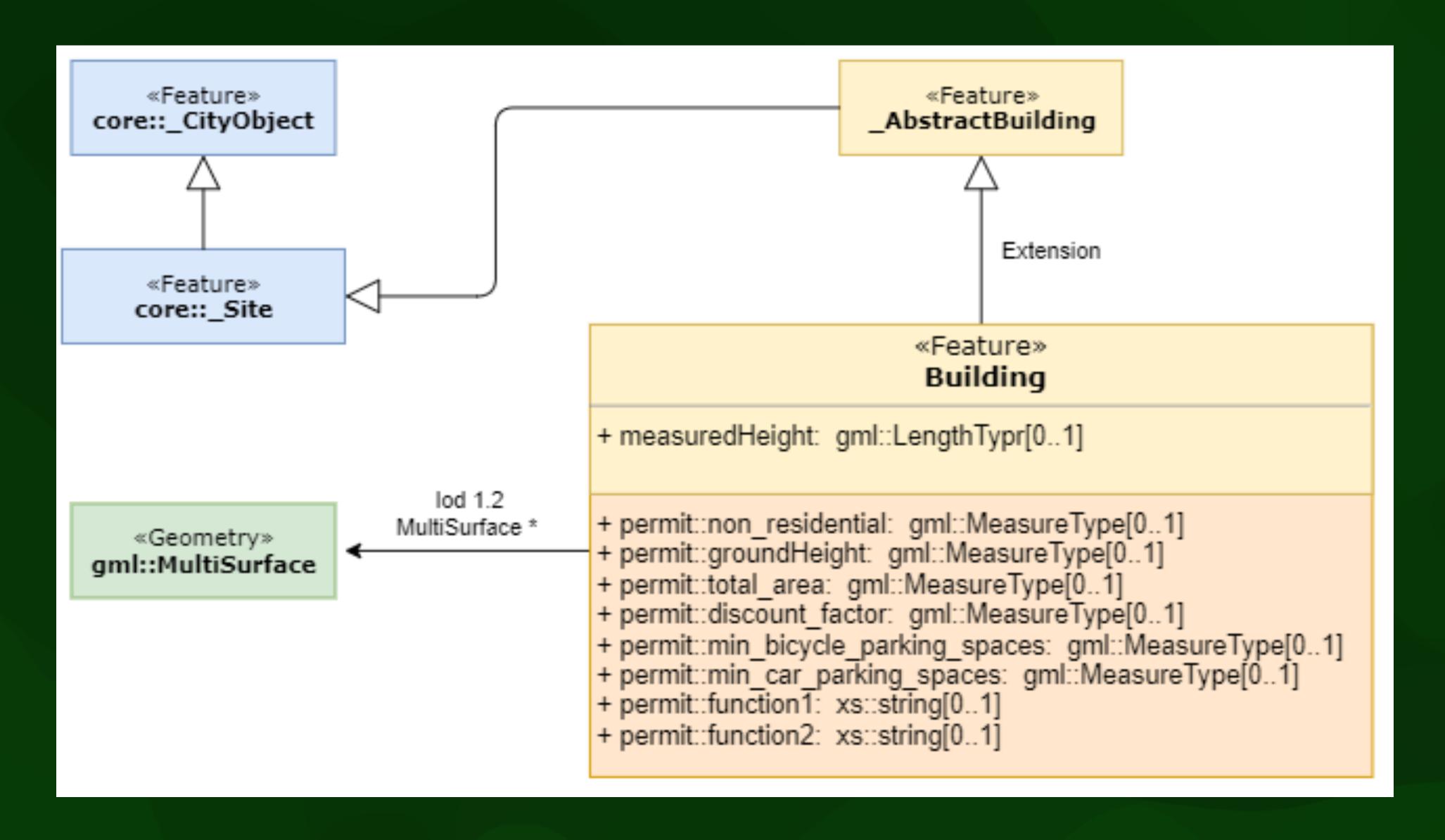
Formalisation of regulations

```
For residential buildings:
BUH40 = Count BU (function."home")
AND (A(BU) 40 m2)
BUH40-65 = Count BU (function."home")
AND (40 A(BU) 65 m2)
BUH65-85 = Count BU (function."home")
AND (65 A(BU) 85 m2)
BUH85 = Count BU (function."home")
AND (85 m2 A(BU))
Rules (must be true)
IF BU(function) = "home"THEN
MinNPP = (BUH40*2) + (BUH40-65*3)
+ (BUH65-85*4) + (BUH85*5)
NewParkings \geq sum(MinNPP) + sum((MinMQPP/parkingArea))
```

New attributes to store

	Information	Explanation	Sources	name in sources
7*Attributes	id	Bag id of building	BAG	identificatie
	+function	Function of buildings	BAG	NR_XXX
		included in codelist		(different functions)
	+groundHeight	Elevation above sea level	3D BAG	ground-0.00
		at the ground level		
	measuredHeight	Elevation above sea level	3D BAG	roof-0.75
	Incasarcariergia	at rooflevel	JD DAG	1001-0.75
	+zone	Zone where the building	Digital	zone
		is located	map	
	+height_valid	Indicate the height	3D BAG	height_valid
		is valid		
	+total_area	Gross floor area (GFA)	BAG	Calculation results
		of building		on different attributs
2*Geometry	type	geometry type of	BAG	type
		buildings		
	coordinates	a lists contain	BAG	coordinates
		[x,y,z] 3D coordinates		

CityJSON extension



CityJSON extension

```
"68": {
 "type": "Building",
  "toplevel": true,
  "attributes": {
    "+height_valid": 1,
    "+non_residential": 1,
    "+groundHeight": 0,
   "measuredHeight": 28.0,
    "+total area": 1371.5687999999999,
    "+discount_factor": 0.95,
    "+min_bicycle_parking_spaces": 117,
    "+min_car_parking_spaces": 78,
    "+function": "catering I"
```

Generating required info



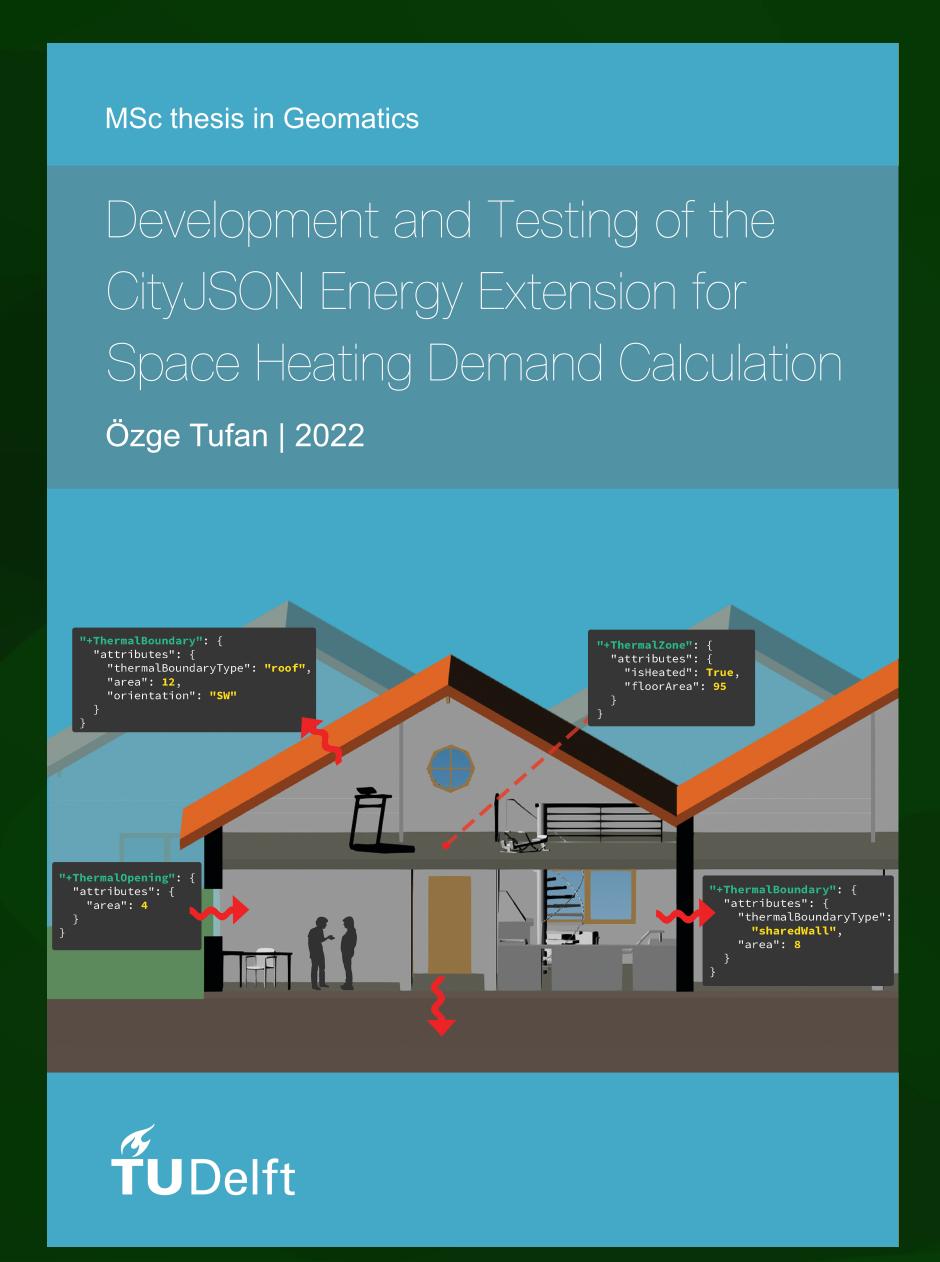
Programming checks

```
N_40 = int(f['properties']['N_40'])
N_{-}40_{-}65 = int(f['properties']['N_{-}40_{-}65'])
N_{-}65_{-}85 = int(f['properties']['N_{-}65_{-}85'])
N_{-}85_{-}120 = int(f['properties']['N_{-}85_{-}120'])
N_{-}120 = int(f['properties']['N_{-}120'])
if f['properties']['zone'] == 'A':
    oneb['attributes']['+min_car_parking_spaces'] = int(
    N_40 * 0.1 + N_40_65 * 0.4 + N_65_85 * 0.6 + N_85_120 * 1 +
    N_{-}120 * 1.2
if f['properties']['zone'] == 'B':
    oneb['attributes']['+min_car_parking_spaces'] = int(
    N_{-}40 * 0.1 + N_{-}40_{-}65 * 0.5 + N_{-}65_{-}85 * 0.8 + N_{-}85_{-}120 * 1 +
    N_{-}120 * 1.2
if f['properties']['zone'] == 'C':
    oneb['attributes']['+min_car_parking_spaces'] = int(
    N_40 * 0.1 + N_40_65 * 0.6 + N_65_85 * 1.4 + N_85_120 * 1.6
    + N_{-}120 * 1.8
```

Results: tool

Minimum Bicycle and Car Par	ing Spaces for New Buildings	?
INPUT (Buffer map) INPUT (new buildings)		Calculate the minimum bicycle and car parking spaces for new buildings
Initial (Men Dallaings)		
		For parameters:
Output		Input: Select the layer which contains buffer map for
	OK	discount, new building data.
	Cancel	Output: Select path to store the output CityJSON results.
		Click OK/Cancel to

- Motivation: use 3DCM for space heating demand calculations
- Develop CityJSON extension with all required information
- Implement space heating models
- Use implementation to improve extension design



Development of the CityJSON Energy Extension

Assessing the use of the Energy ADE vs. the Energy ADE KIT profile

Determining the mapping rules

CityJSON Energy
Extension as a semi-direct
translation from the Energy
ADE KIT Profile

Validation through the use case

Validation through *cjval*

Valid CityJSON Energy Extension

Valid CityJSON + Energy Extension file

Space heating demand calculation

Choosing the calculation method to be used

Deciding on the simplifications and assumptions to be made

Collection of needed input data

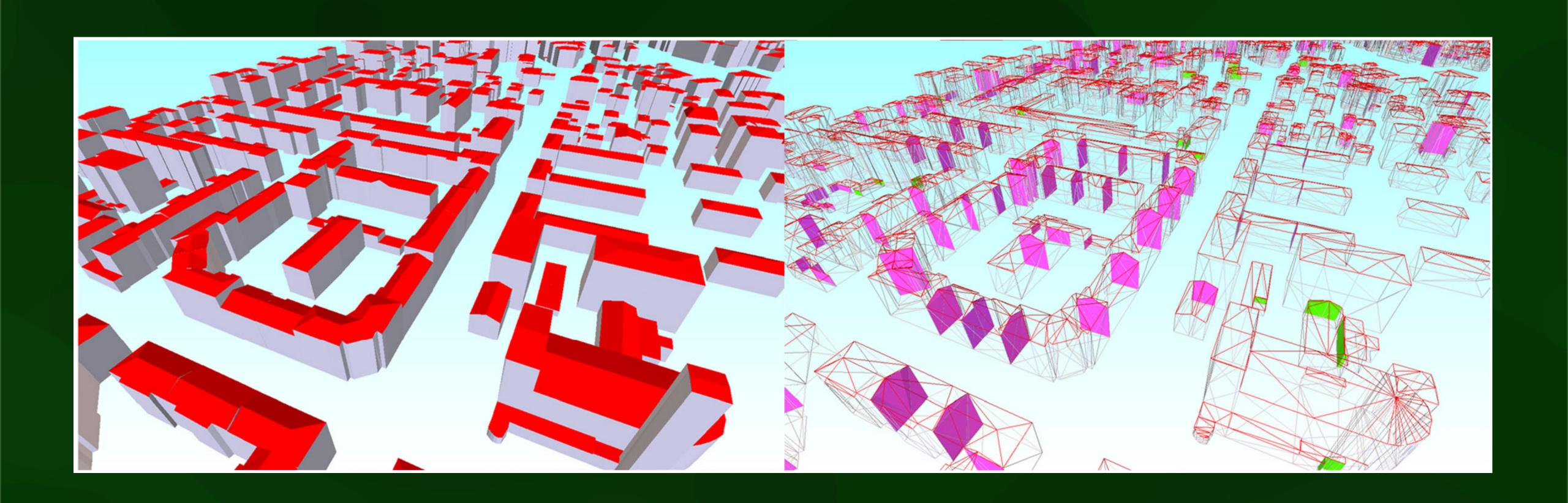
Creating a CityJSON +
Energy Extension file with
the needed input data for
the use case

Calculation of space heating demand

Enhancing the CityJSON +
Energy Extension file with
output space heating
demand values

Improvements to the CityJSON Energy Extension

Storing new (complex) geometries



New attributes

Net internal area Exludes internal structural elements

Class Type of use of the building, e.g. residential, mixed-use

Further description of the class, e.g., health, business

Usage Whether the building is still in use

Measured height Height of the building, in m

Function*

Relative to terrain Whether the building is (entirely) above or below the terrain

Roof type E.g. slanted, single/multiple horizontal

Year of construction Construction year of the building

Footprint area* Footprint area, calculated from the LoD0 geometry, in m^2

Storeys above ground* Number of storeys situated above ground level

Storeys below ground* Number of storeys situated below ground level

Building name* Unique name of the building

Is single part Boolean value to show whether the building has *BuildingParts*

of adjacent buildings Number of topologically adjacent buildings

LoD2 volume* Building volume, calculated from the LoD2 geometry, in m^3

LoD max Maximum LoD present for the building

Building (pand) ID Unique ID of the building

List adjacent buildings Building (pand) ID of topologically adjacent buildings

Surface ID Unique ID of the BoundarySurface

Parent building ID Building (pand) ID of the building that the surface belongs to

Surface name Unique name of the BoundarySurface

Azimuth of the surface, in degrees

Inclination Inclination of the surface, in *degrees*

Direction Direction of the surface

LoD2 area Surface area, calculated from the LoD2 geometry, in m^2

Surface normal Normal vector of the surface

New attributes

```
"extraAttributes": {
    "Building": {
        "+buildingType": {...},
        "+constructionWeight": {...},
        "+volume": {...},
        "+floorArea": {...},
        "+heightAboveGround": {...}
    }
}
```

```
"Build1": {
    "type": "Building",
    "geometry": [...],
    "attributes": {
        "+buildingType": "singleFamily",
        "+constructionWeight": "heavy",
    }
}
```

New City Objects

```
"extraCityObjects": {
  "+WeatherData": {
    "type": "object",
    "properties": {
      "type": {...},
      "attributes": {
        "type": "object",
        "properties": {
          "weatherDataType": {...}, "RegularTimeSeries1": {
          "values": {...},
          "position": {...}
```

```
"OutdoorTemperature": {
 "type": "+WeatherData",
 "attributes": {
    "weatherDataType": "airTemperature",
   "values": "RegularTimeSeries1",
              //ID of TimeSeries object
 "type": "+RegularTimeSeries",
 "attributes": {
   "values": [2.61, 4.82, 5.91, 9.32,
       14.73, 16.12],
```

Test data



Results: heating energy demand



- Motivation: unreliable or non-existent information in IFC models
- Automatically create shapes of rooms, storeys and apartments
- Built on IfcOpenShell

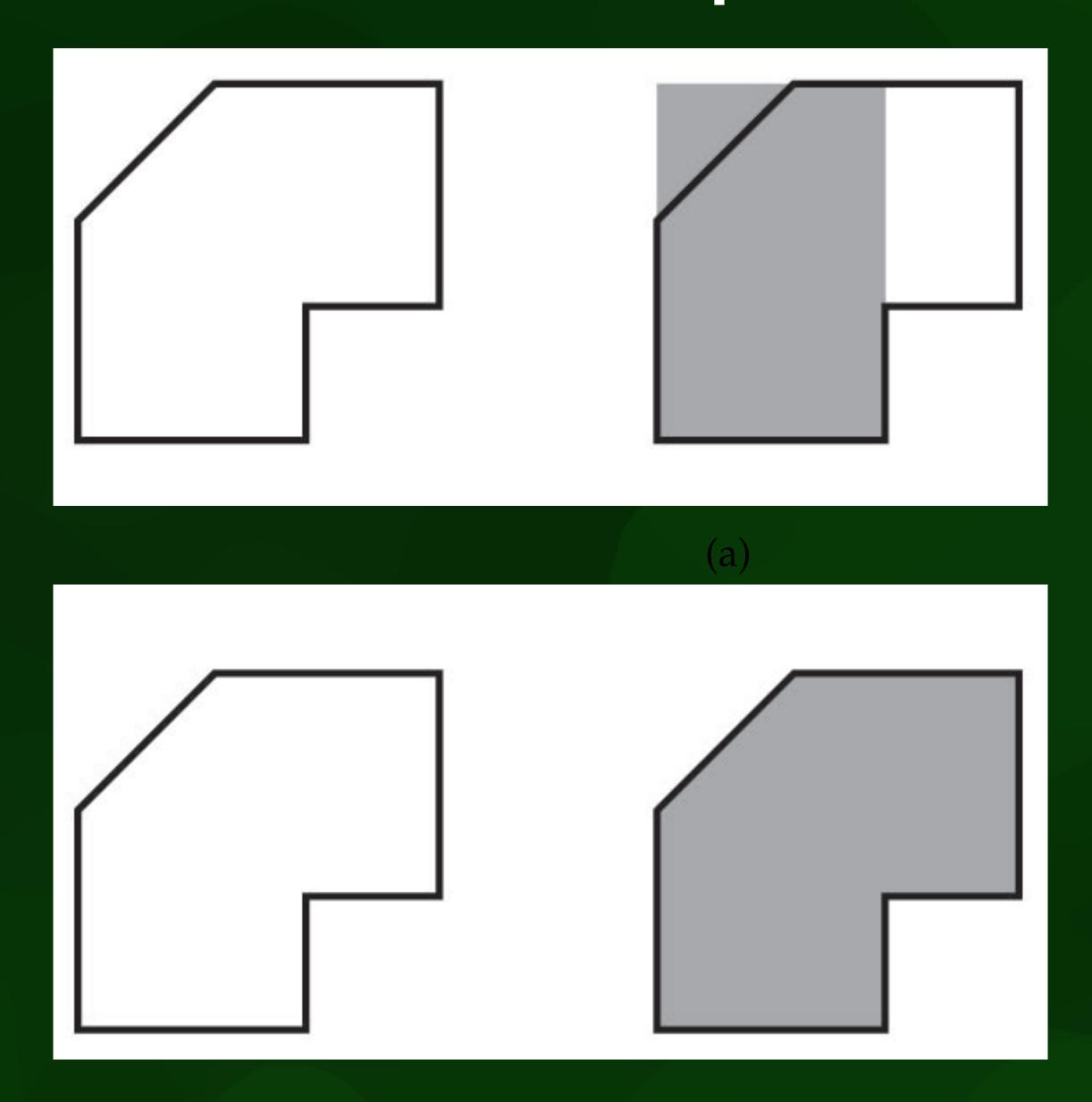
MSc thesis in Geomatics

Automatic building feature detection and reconstruction in IFC models

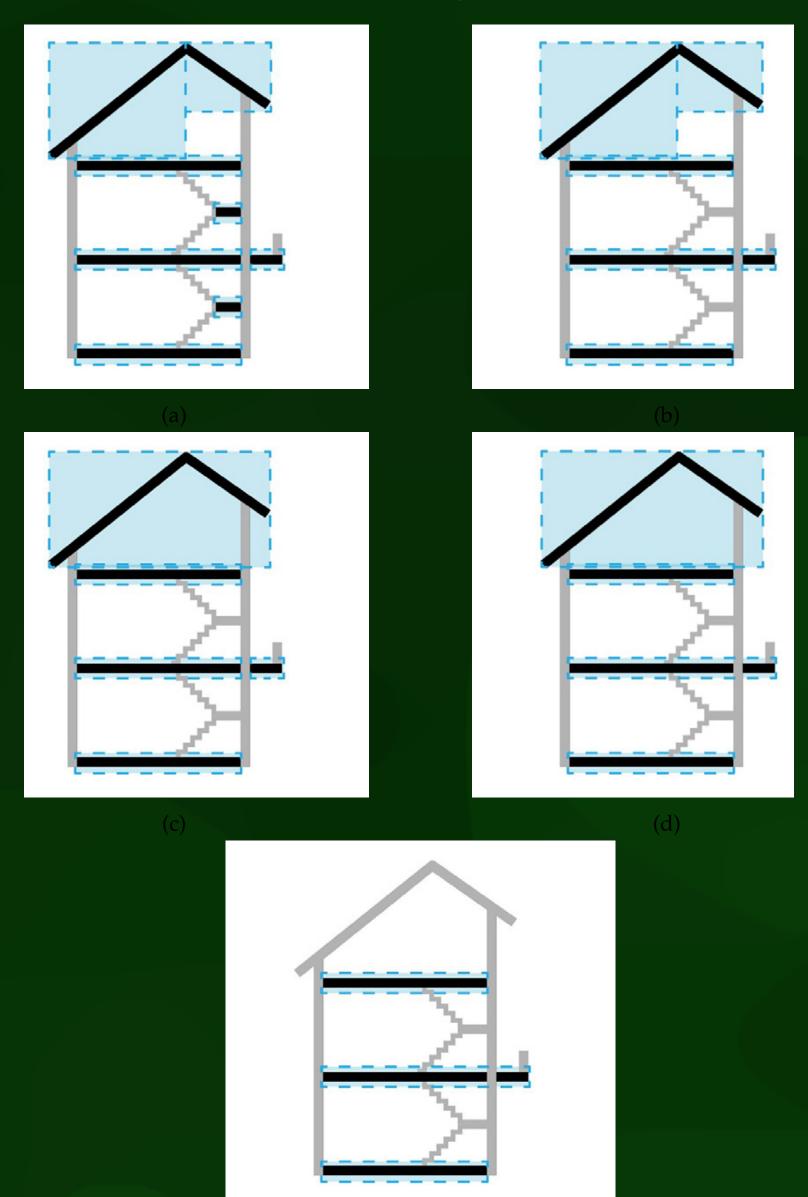
Jasper van der Vaart 2022



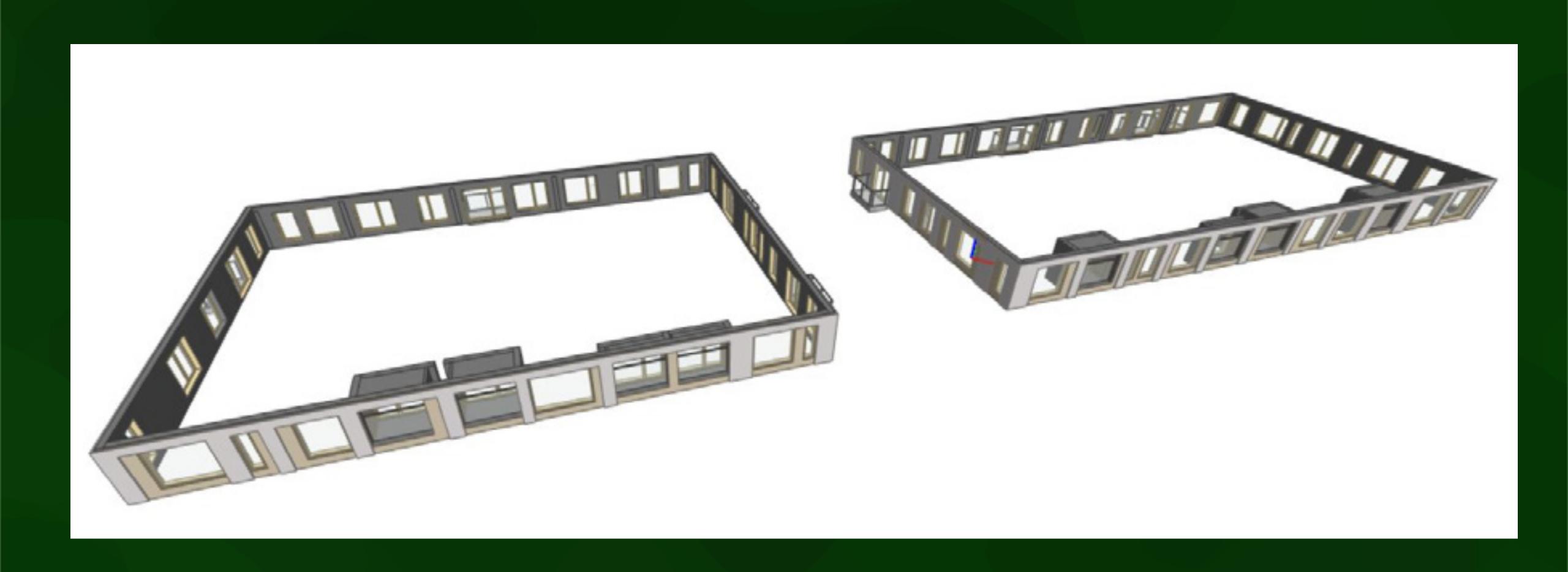
Current IfcSpaces

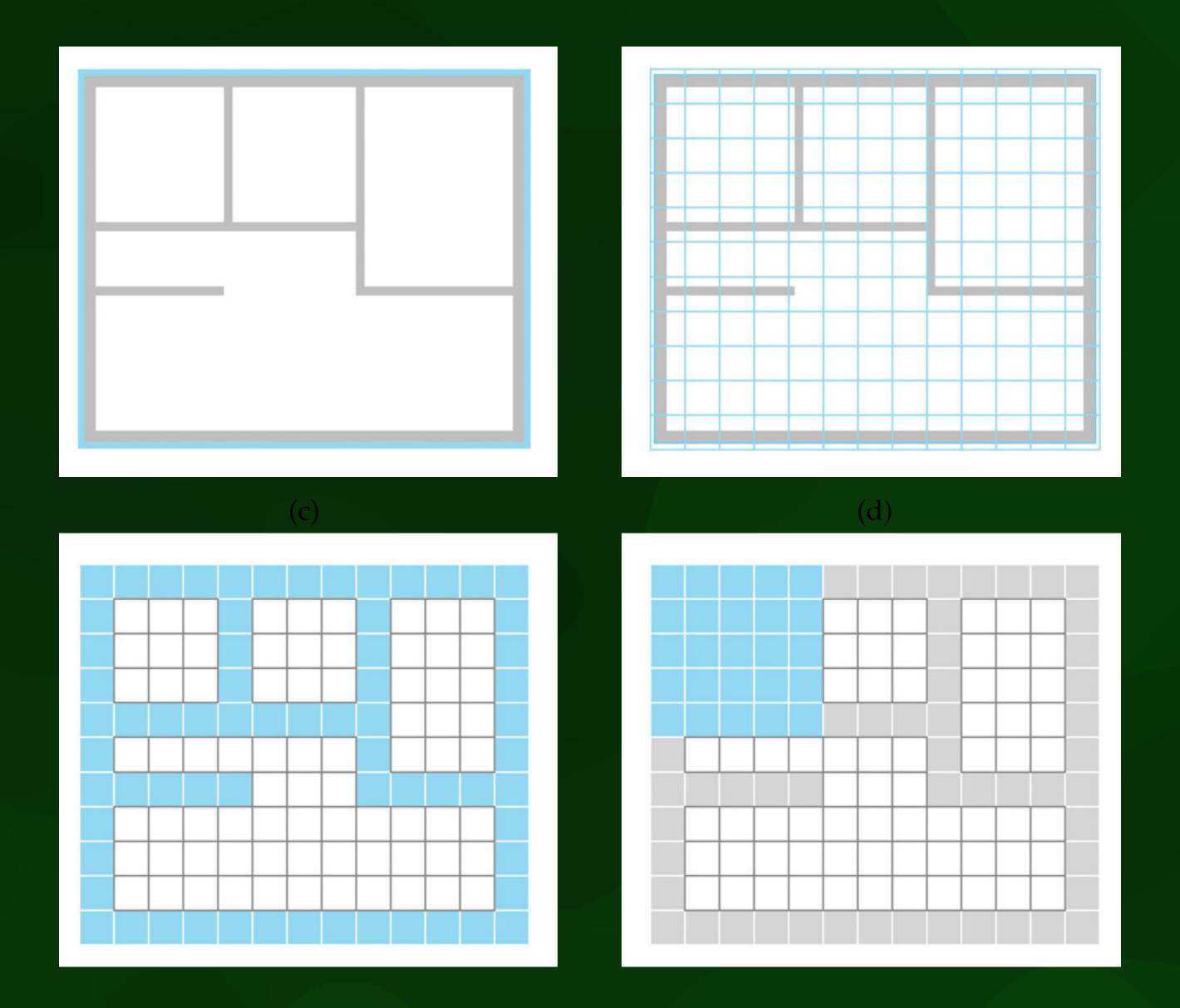


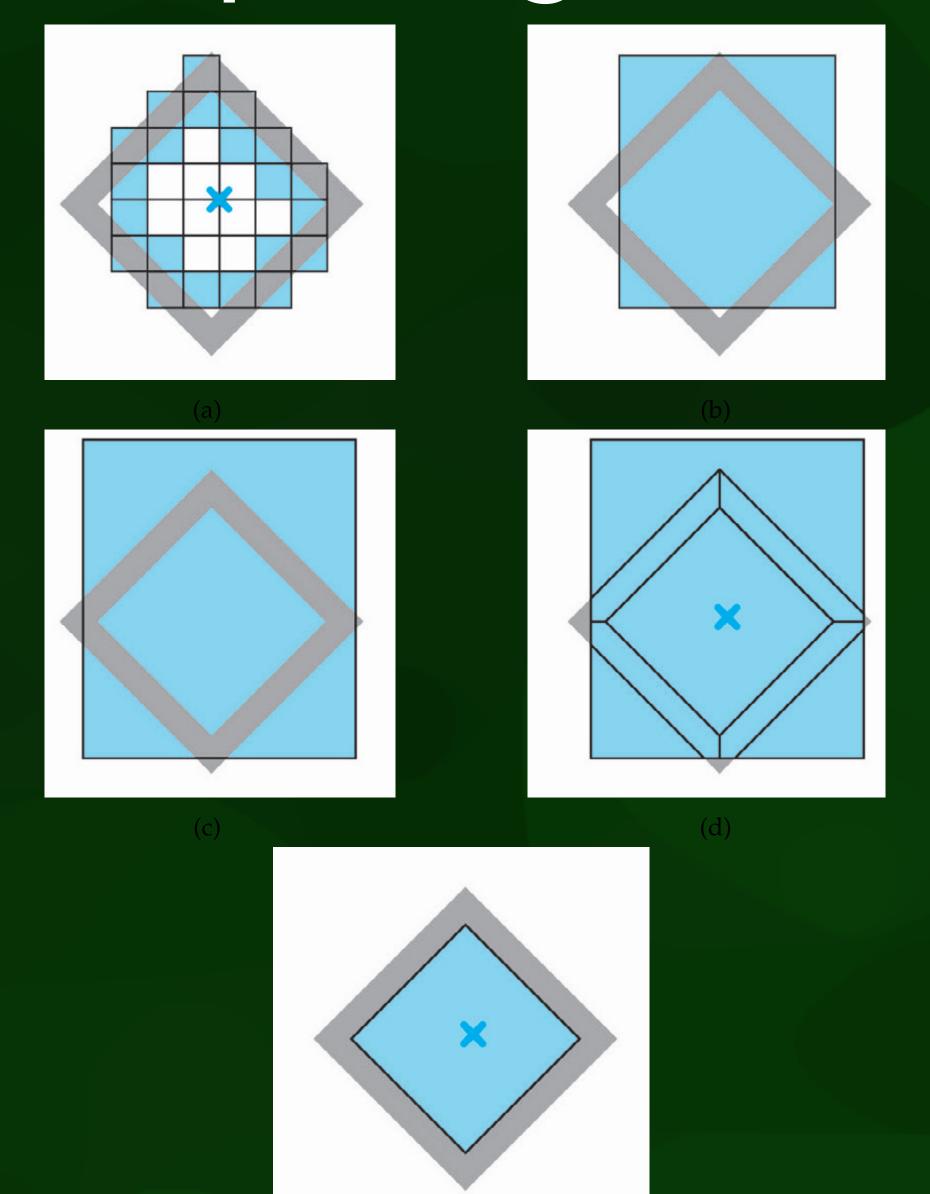
Computing storeys

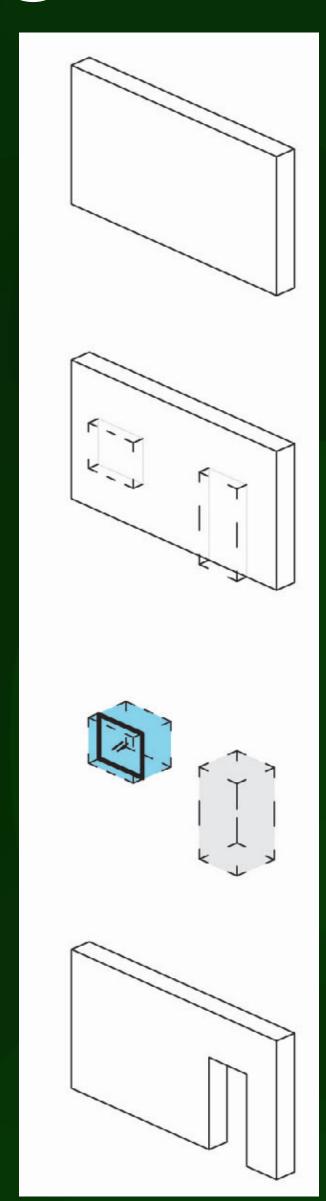


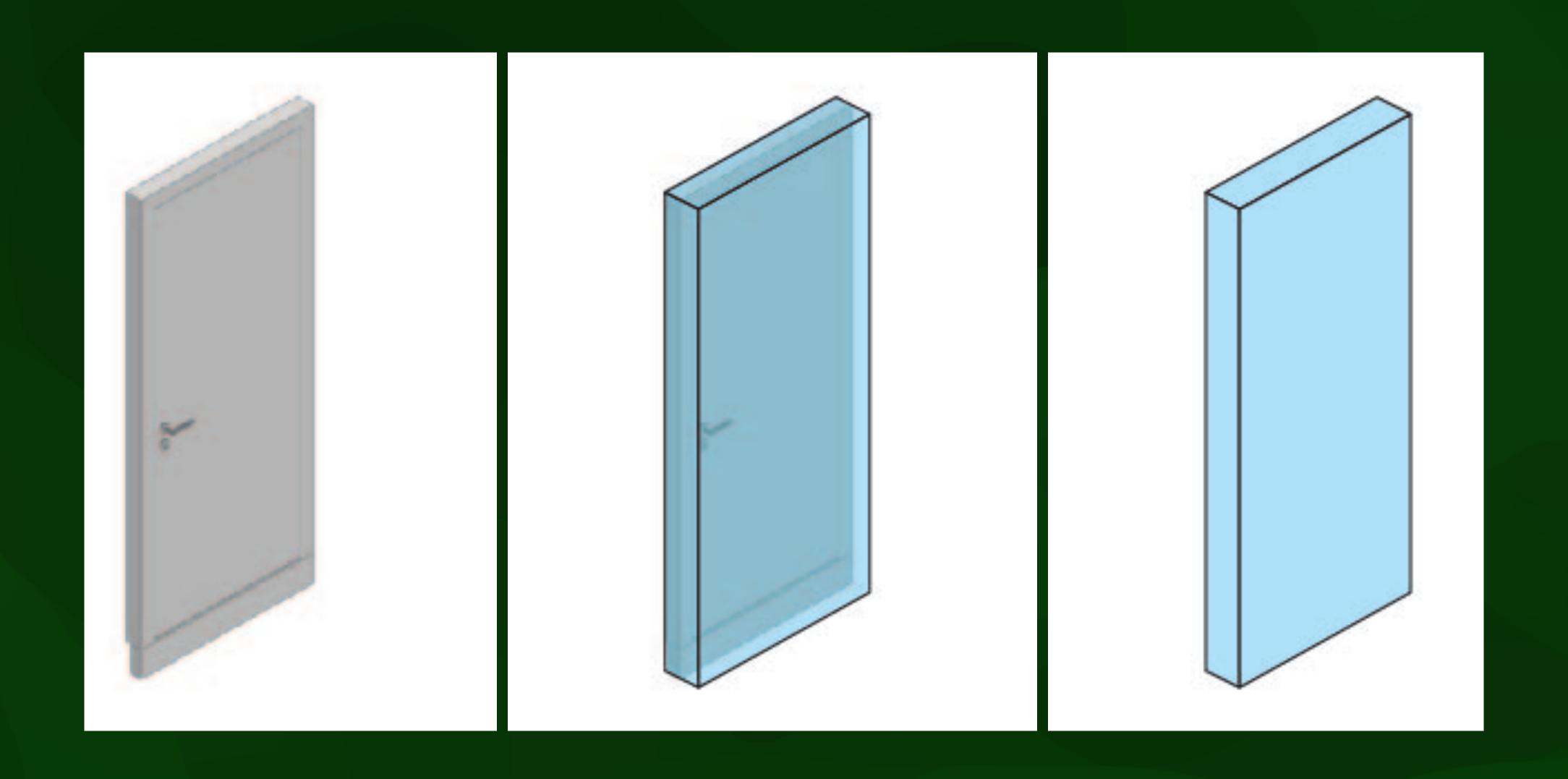
Computing storeys

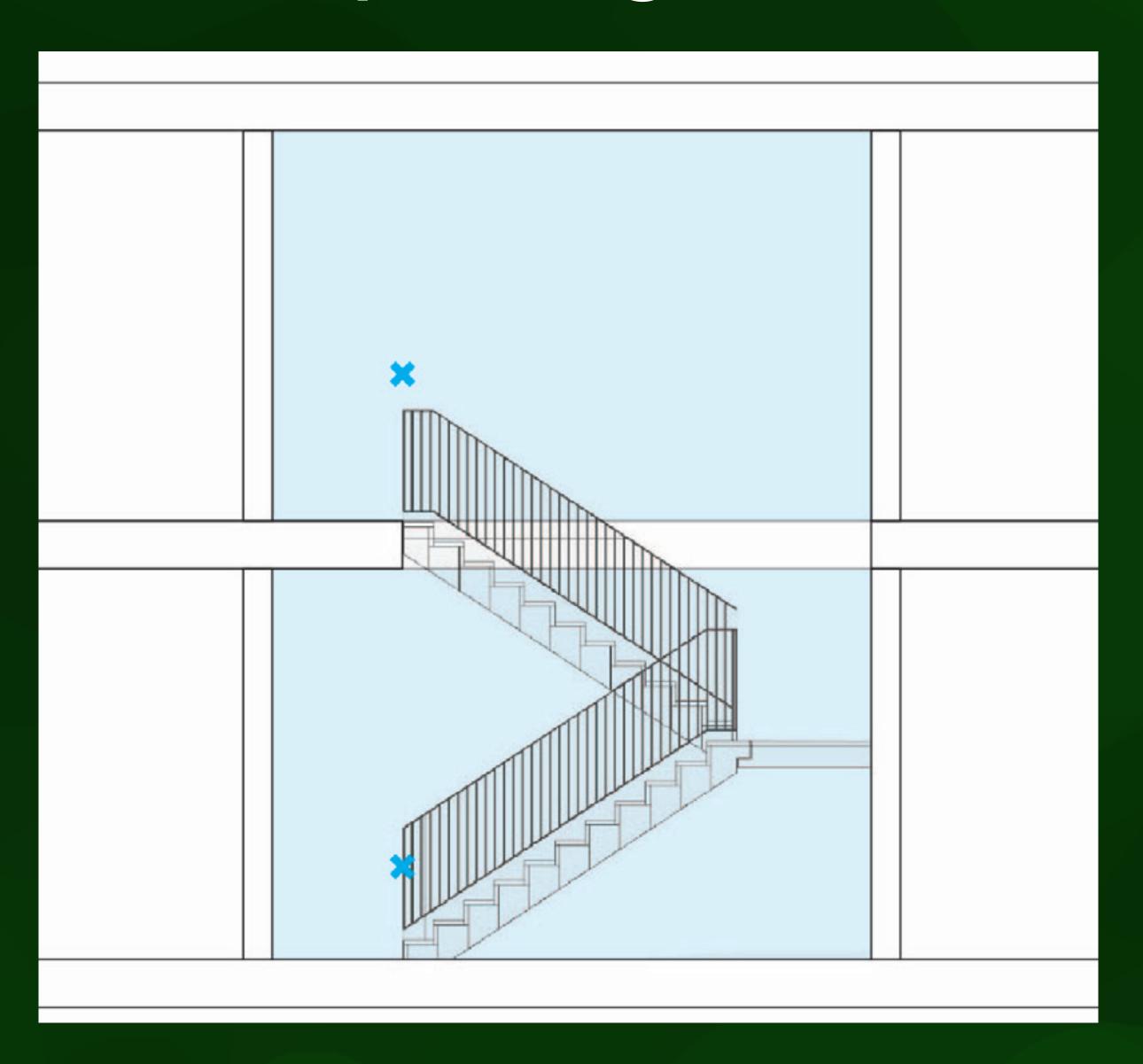




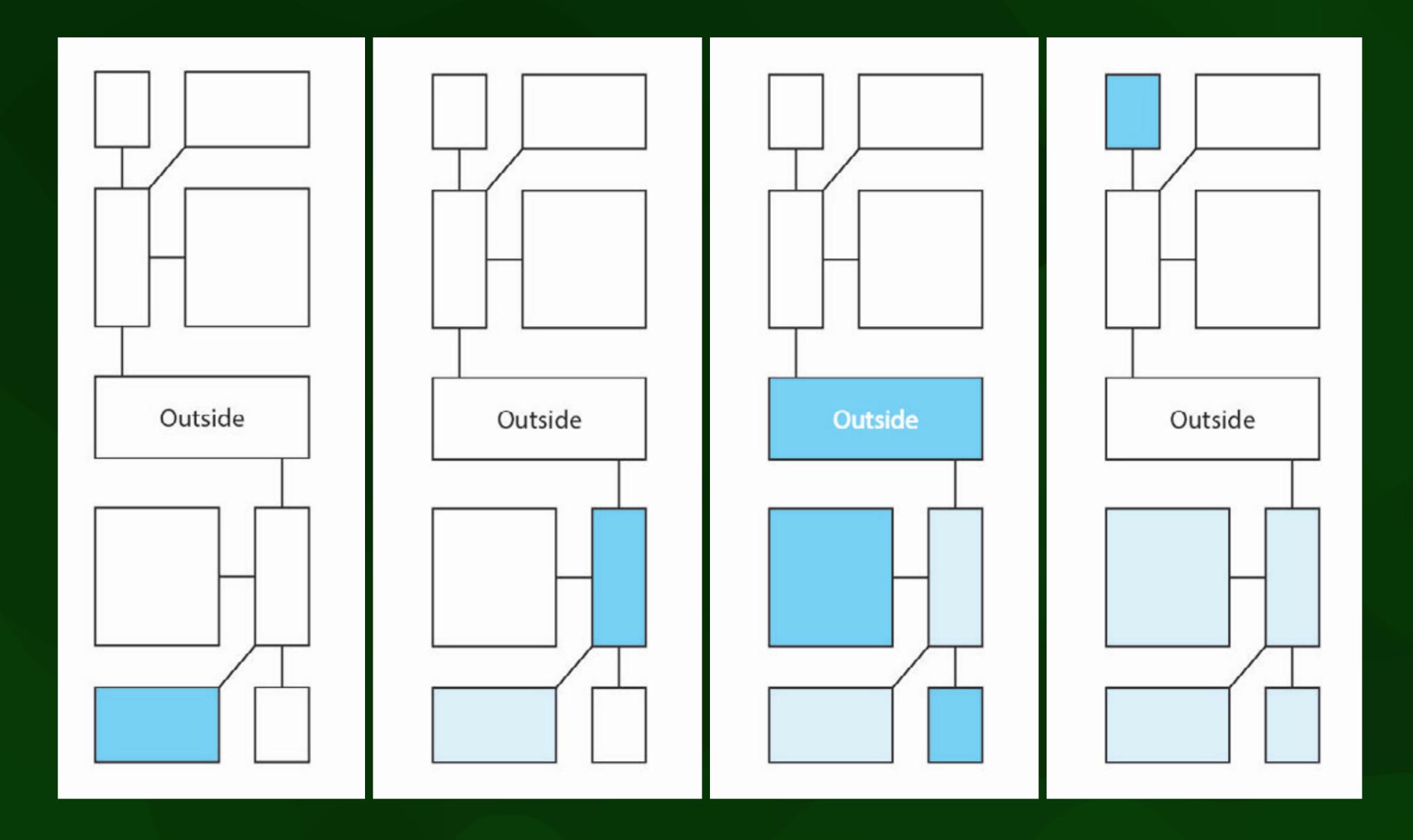




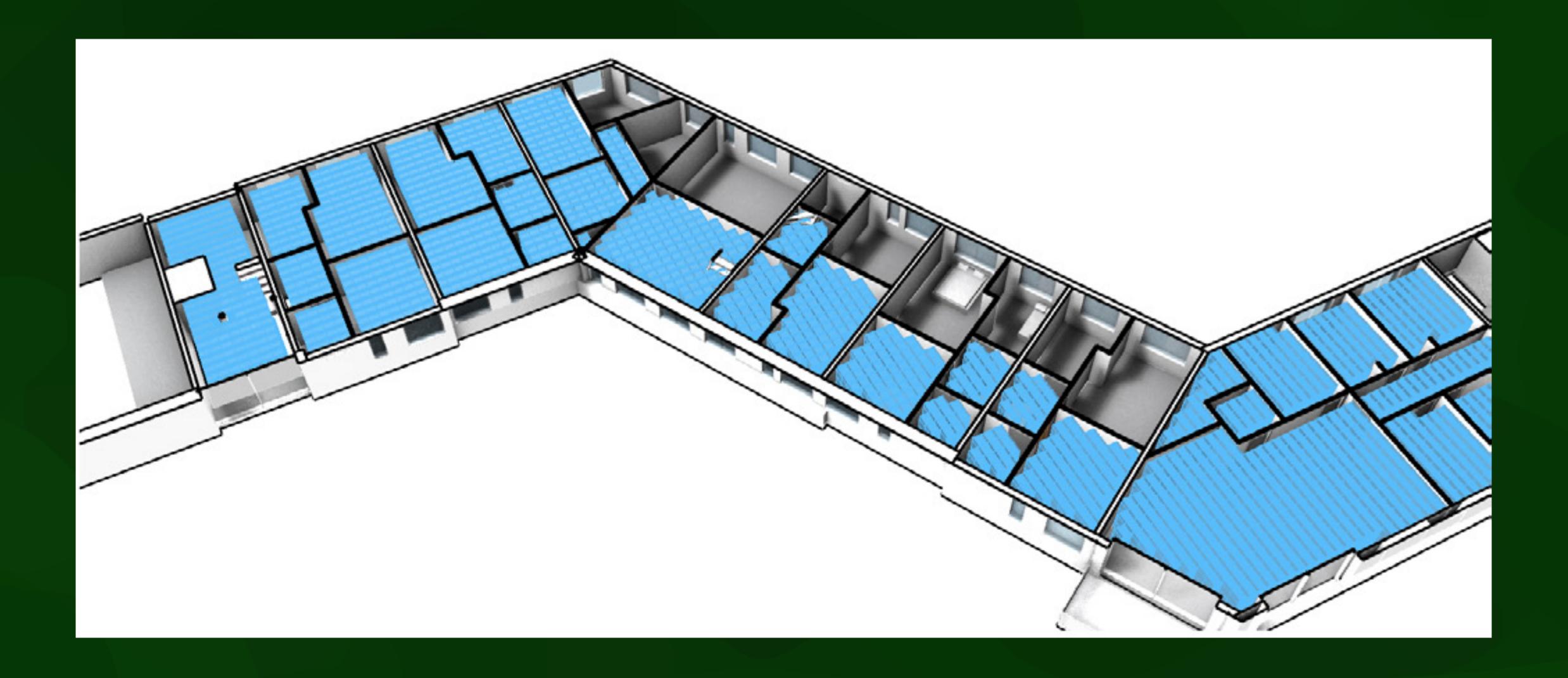




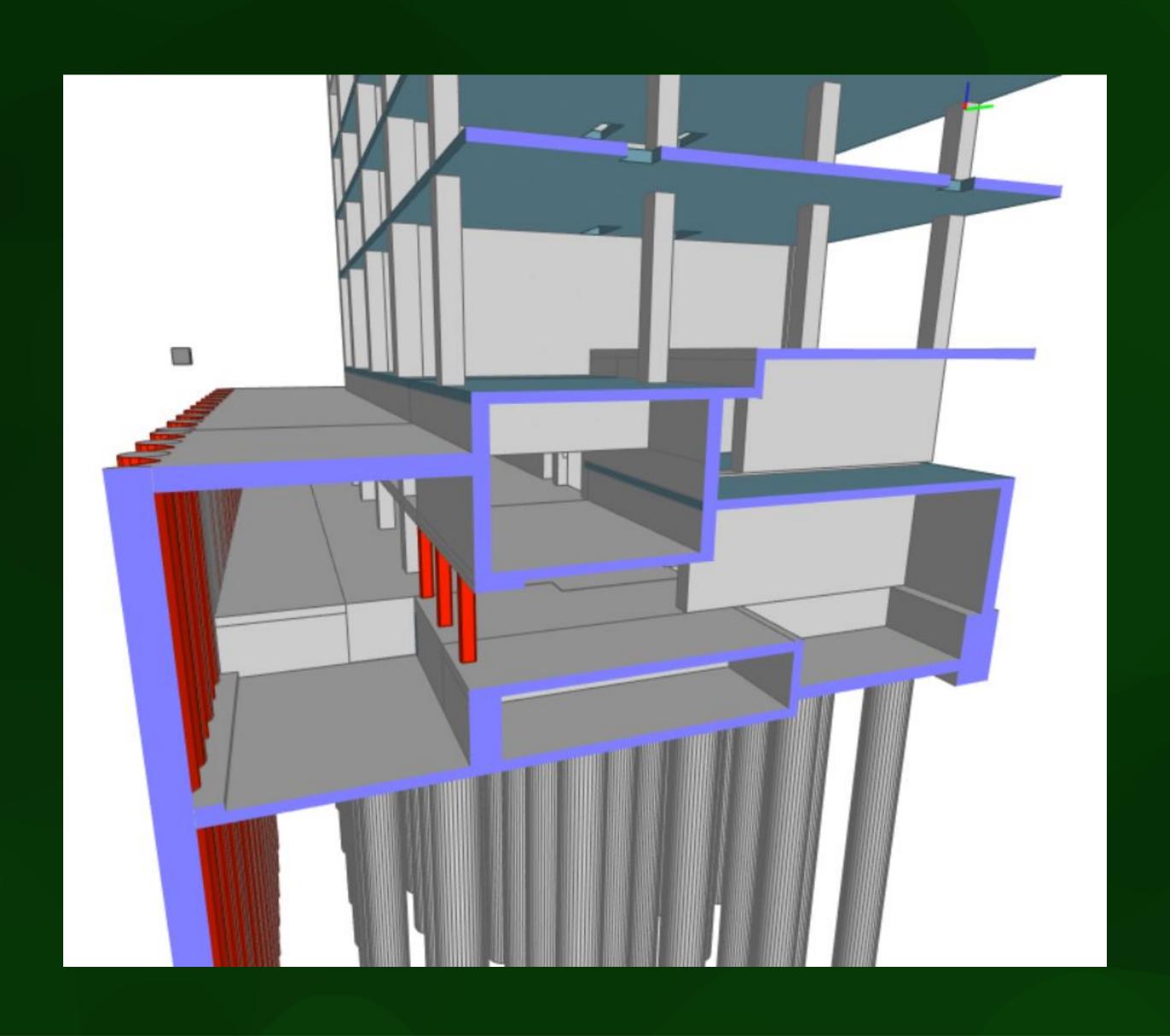
Computing apartments



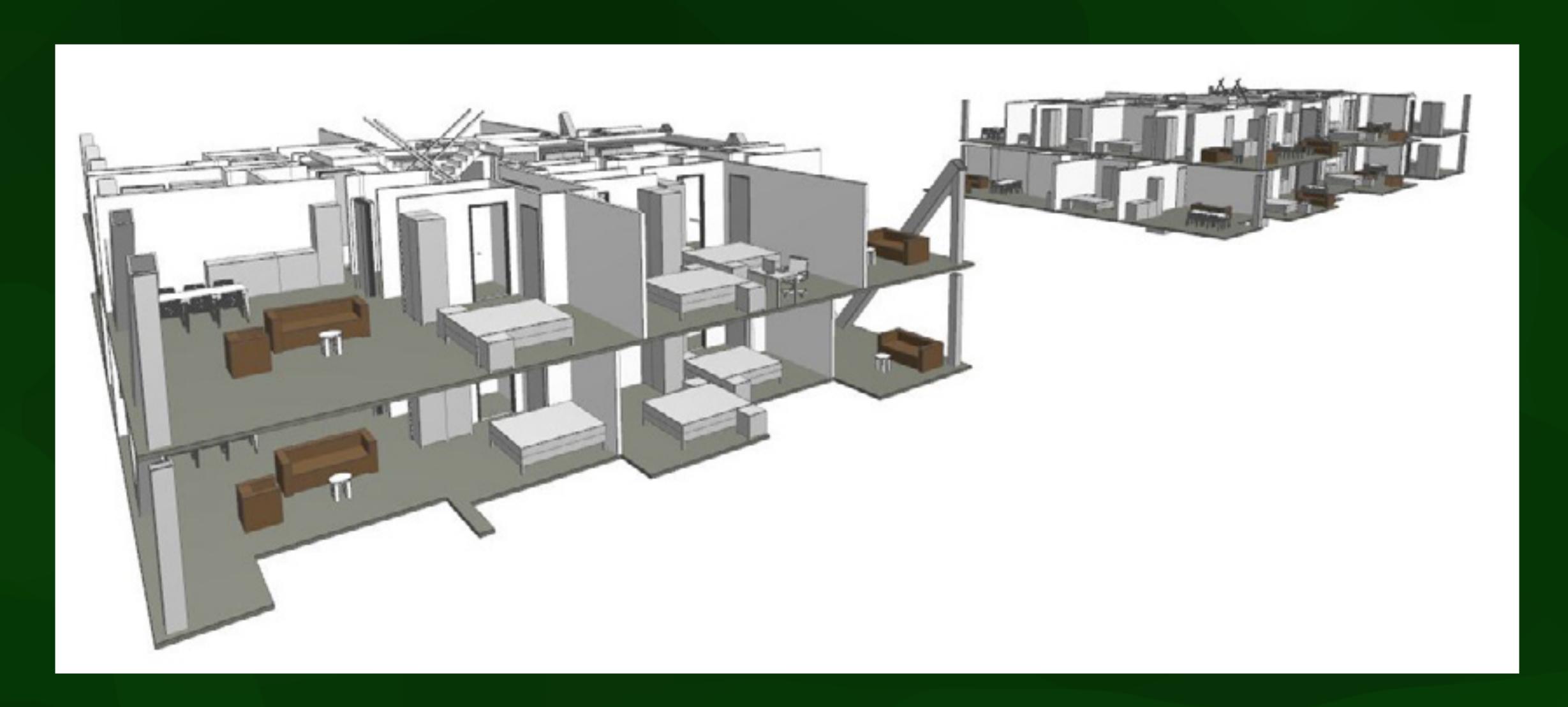
Results



Results



Results



Recommendations

- GEO5014: Geomatics as support for energy applications
- GEO5015: Modelling wind and dispersion in urban environments
- Your own MSc thesis

Sources of images

- [2-6]: Filip Biljecki (paper on application of 3D city models and PhD thesis)
- [9-20]: Roeland Boeters (MSc thesis and related paper)
- [21-29]: Sjors Donker (MSc thesis)
- [30-48]: Damien Mulder (MSc thesis)
- [49, 51-62]: Yixin Xu (MSc thesis)

Sources of images

- [50]: Anna-Maria Ntarladima (MSc thesis)
- [63-70]: Jialun Wu (MSc thesis)
- [71-78]: Özge Tufan (MSc thesis)
- [79-91]: Jasper van der Vaart (MSc thesis)