Lesson 4.1 Semantic 3D city models

GE01004: 3D modelling of the built environment

https://3d.bk.tudelft.nl/courses/geo1004



- JavaScript Object Notation
- Lightweight data-interchange format
- It is easy for humans to read and write.
- It is easy for machines to parse and generate.
- It is originally based on a subset of JavaScript (but is now in most languages)
- It is text-based

```
"firstName": "John",
"lastName": "Smith",
"isAlive": true,
"age": 27,
"address": {
  "streetAddress": "21 2nd Street",
  "city": "New York",
  "state": "NY",
  "postalCode": "10021-3100"
"phoneNumbers": [
    "type": "home",
    "number": "212 555-1234"
    "type": "office",
    "number": "646 555-4567"
    "type": "mobile",
    "number": "123 456-7890"
"children": [],
"spouse": null
```

Virtually all languages have <u>native</u> support for it

It is built on two (very common) data

structures:

- 1. collection of name-value pairs
 - Python dictionaries
 - C++ std::map
 - also called a "hash"
- 2. arrays
 - Python lists
 - C++ std::vector / std::array

Data types:

- number (float and double)
- integer
- string
- Boolean
- null
- (no support for datetime type)

To represent a person

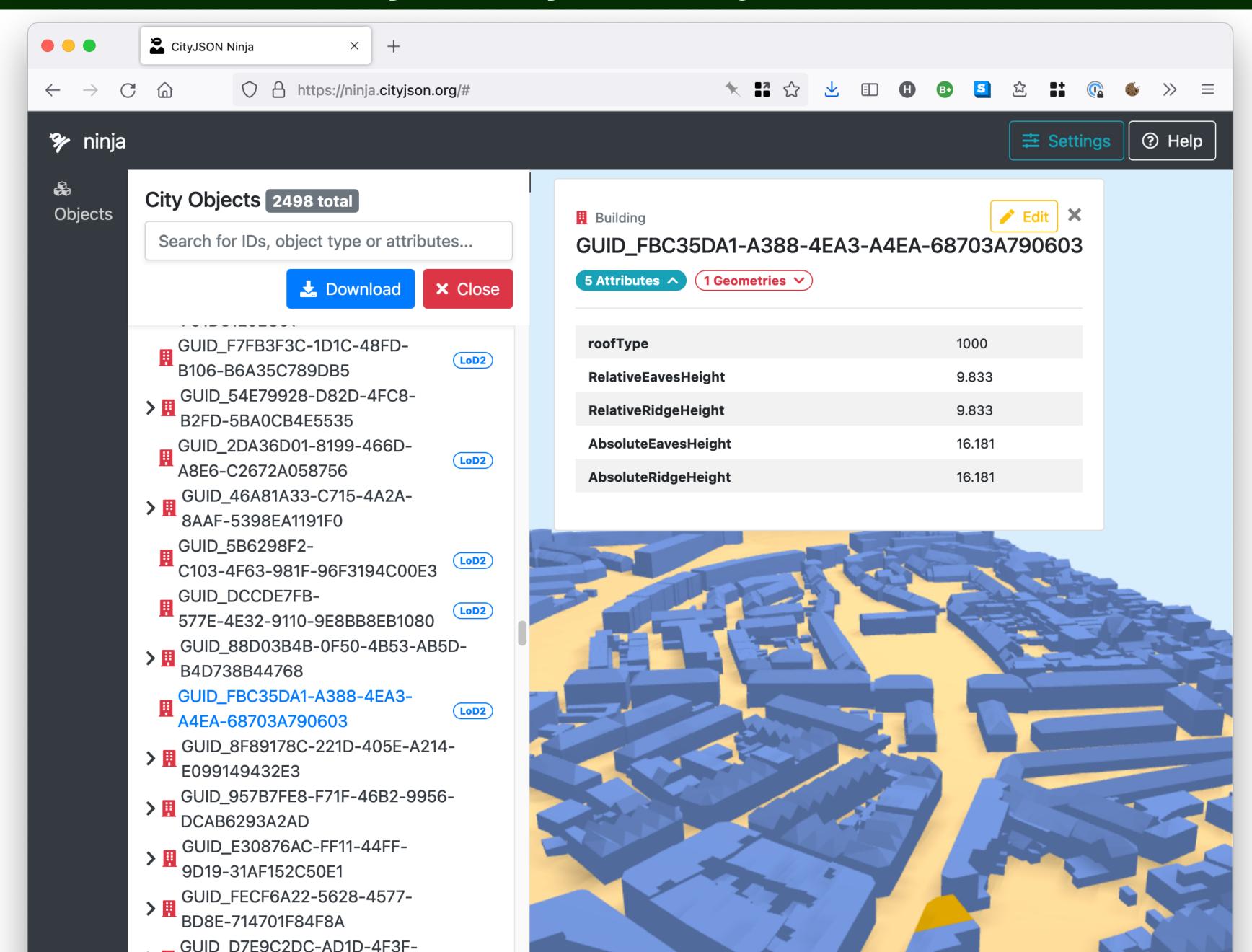
```
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  "streetAddress": "21 2nd Street",
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    "type": "office",
    "number": "646 555-4567"
    "type": "mobile",
    "number": "123 456-7890"
"children": [],
"spouse": null
```

A CityJSON file

```
"type": "CityJSON",
"version": "1.1",
"metadata": {
 "referenceSystem": "https://www.opengis.net/def/crs/EPSG/0/7415"
"transform": {...}
"CityObjects": {
 "id-1": {
   "type": "Building",
   "attributes": {
     "measuredHeight": 22.3,
     "roofType": "gable",
     "owner": "Elvis Presley"
    "geometry": [
        "type": "MultiSurface",
        "boundaries": [
          [[0, 3, 2, 1]], [[4, 5, 6, 7]], [[0, 1, 5, 4]]
"vertices": [
 [231, 23212, 110],
 [1111, 3211, 120],
"appearance": {
 "materials": [],
 "textures":[],
 "vertices-texture": []
```

CityJSON software

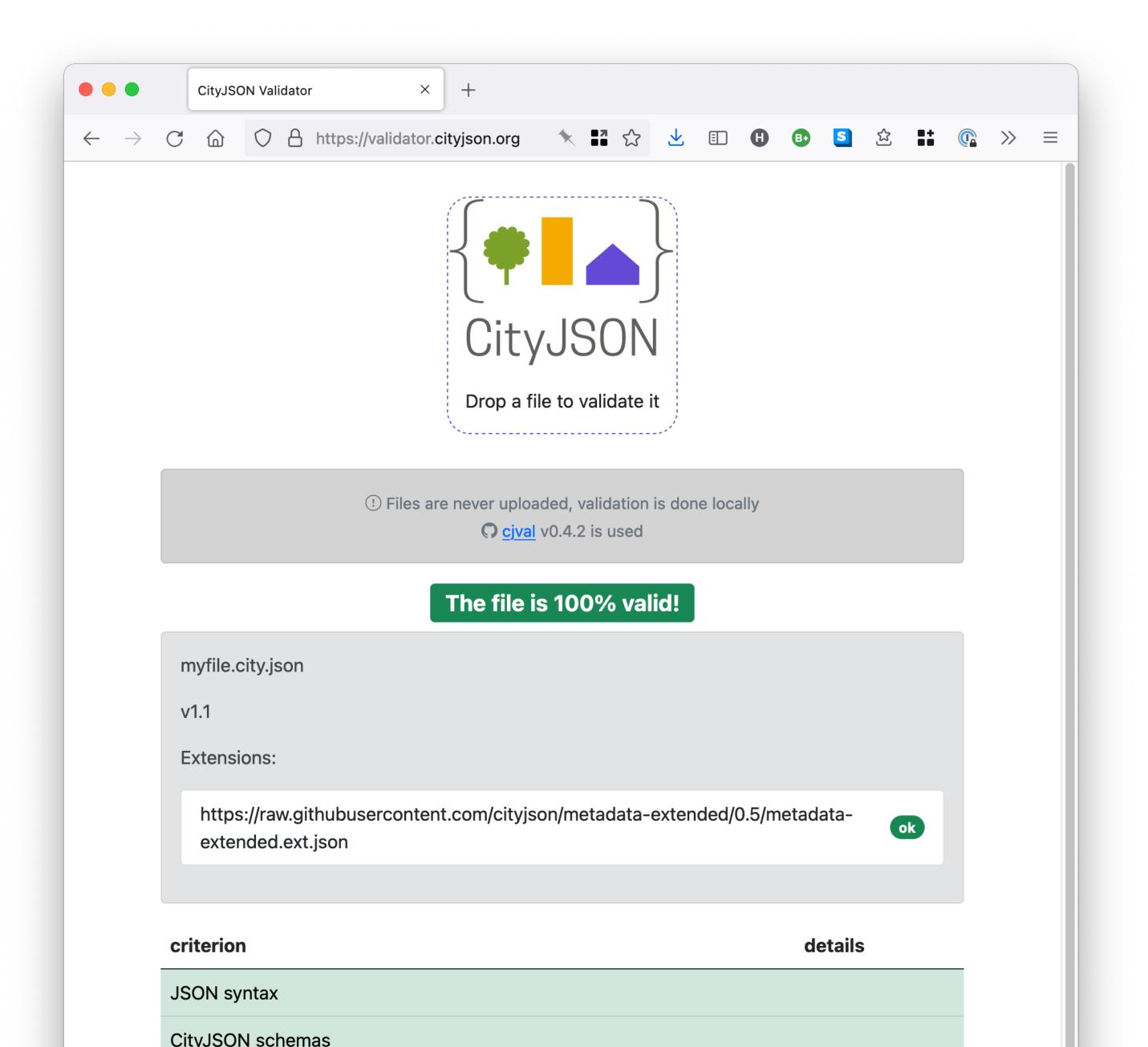
web-viewer: ninja.cityjson.org



Cool fact: programmed mostly by 2
Geomatics students, as projects for
GE05010

You can do the same (or similar!)

Validation of the syntax of a file: cjval



```
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"version": "1.1",
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"transform": {...}
"CityObjects": {
  "id-1": {
    "type": "Buildnig"
    "attributes": {
      "measuredHeight": 22.3,
      "roofType": "gable",
      "owner": "Elvis Presley"
    "geometry": [
        "type": "MultiSurface",
        "boundaries": [
          [[0, 3, 2, 1]], [[4, 5, 6, 7], [[0, 1, 5, 4]]
"vertices": [
  [231, 23212, 110.223],
  [1111, 3211, 120],
"appearance": {
  "materials": [],
  "textures":[],
  "vertices-texture": []
```

cjio (CityJSON/io) => pip install cjio

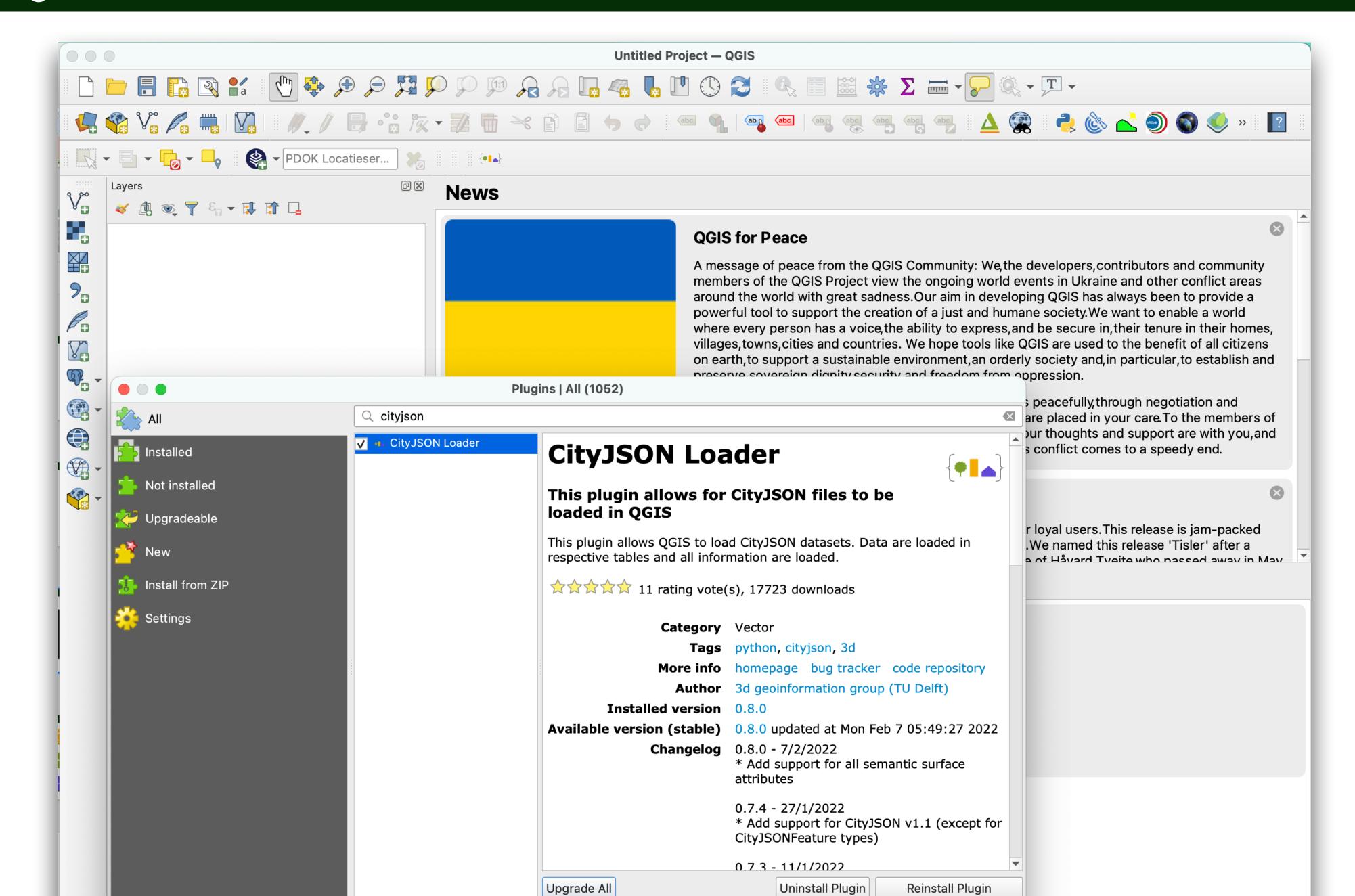
```
2. bash
Hugos-MacBook-Pro:rotterdam hugo$ cjio
Usage: cjio [OPTIONS] INPUT COMMAND1 [ARGS]... [COMMAND2 [ARGS]...]...
 Process and manipulate a CityJSON file, and allow different outputs. The
 different operators can be chained to perform several processing in one
 step, the CityJSON model goes through the different operators.
 To get help on specific command, eg for 'validate':
     cjio validate --help
  Usage examples:
     cjio example.json validate
     cjio example.json remove_textures info
     cjio example.json subset --id house12 remove_materials save out.json
Options:
 --version
                          Show the version and exit.
 --off
                          Load an OFF file and convert it to one CityJSON
                          GenericCityObject.
 --ignore_duplicate_keys Load a CityJSON file even if some City Objects have
                          the same IDs (technically invalid file)
                          Show this message and exit.
 --help
Commands:
                            Compress a CityJSON file, ie stores its...
 compress
                            Decompress a CityJSON file, ie remove the...
 decompress
                            Output info in simple JSON.
  info
                            Merge the current CityJSON with others.
  merge
  remove_duplicate_vertices Remove duplicate vertices a CityJSON file.
  remove_materials
                             Remove all materials from a CityJSON file.
  remove_orphan_vertices
                             Remove orphan vertices a CityJSON file.
                             Remove all textures from a CityJSON file.
  remove_textures
                             Save the CityJSON to a file.
  save
                             Create a subset of a CityJSON file.
  subset
                             Update the bbox of a CityJSON file.
 update_bbox
                             Update the CRS with a new value.
 update_crs
  validate
                             Validate the CityJSON file: (1) against its...
```

cjio (CityJSON/io)

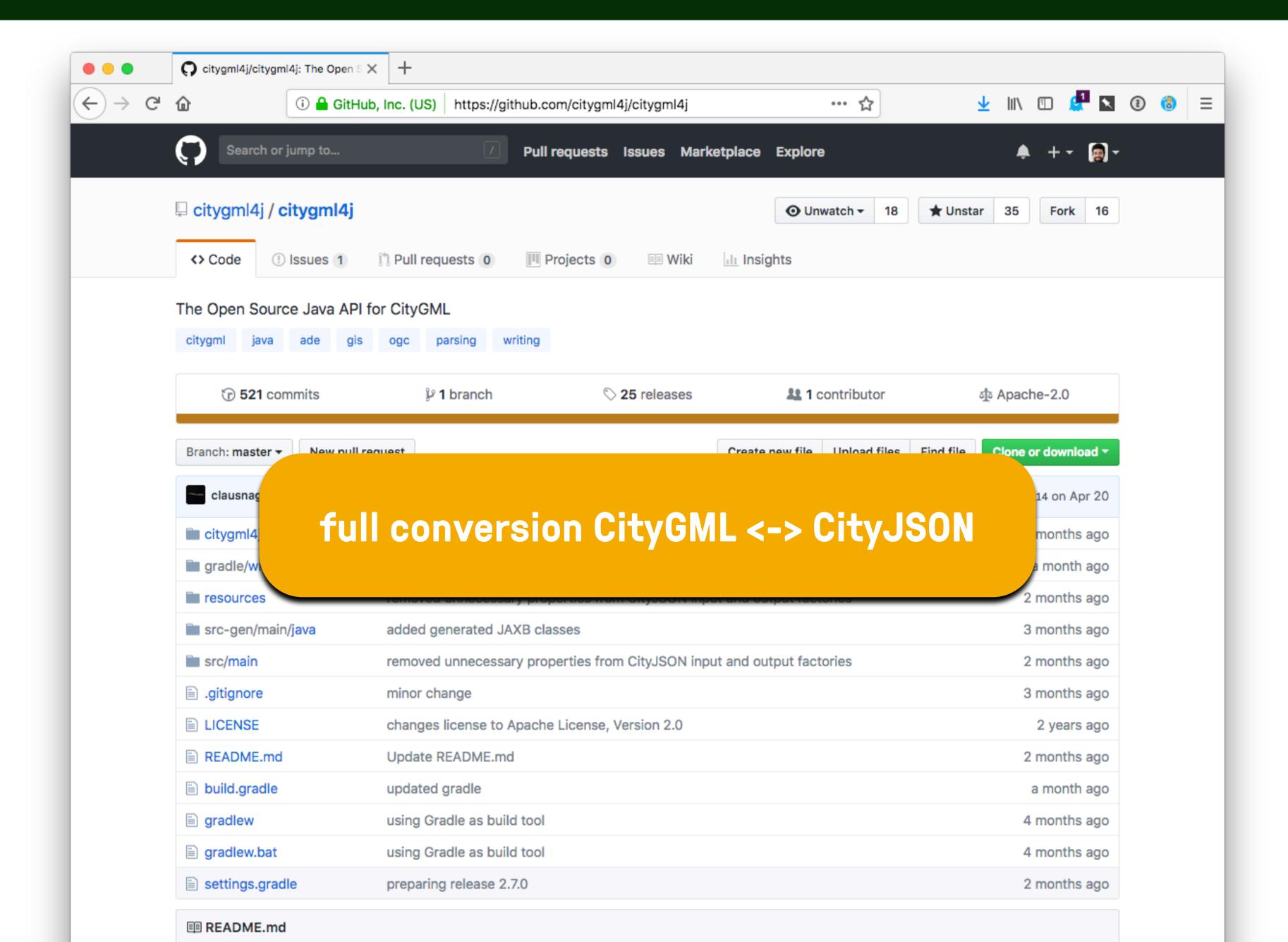
\$ cjio myfile.json crs_assign 7415 subset --cotype Building lod_filter 2.2 save out.json

No need to save temp files between operators: pipeline is used

QGIS plugin



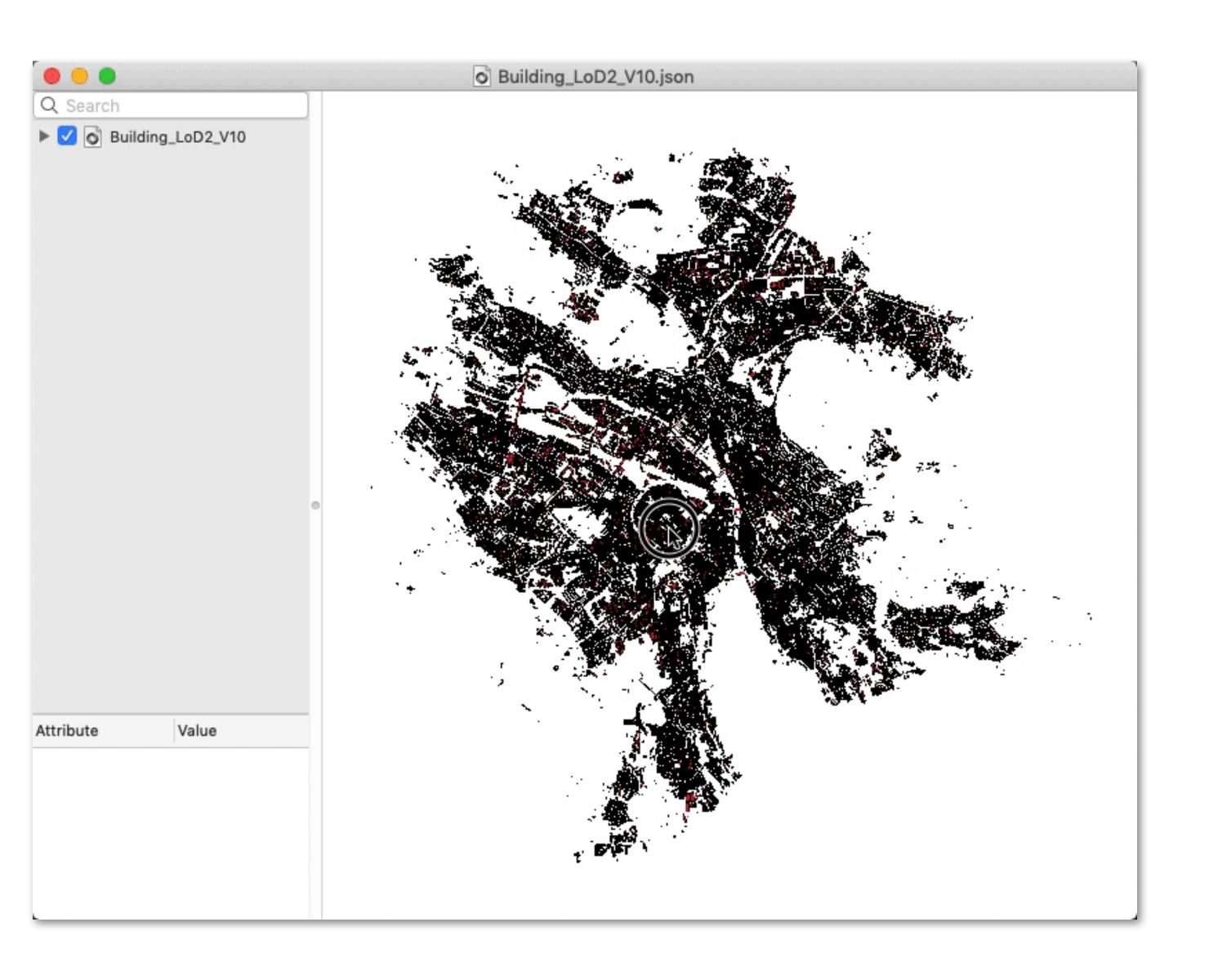
citygml4



Compression factor == ~6X

file	CityGML size (original)	CityGML size (w/o spaces)	textures?	CityJSON	CityJSON compressed	compression factor
CityGML demo "GeoRes"	4.3MB	4.1MB	yes	582KB	524KB	8.0
CityGML v2 demo "Railway"	45MB	34MB	yes	4.5MB	4.3MB	8.1
Den Haag "tile 01"	23MB	18MB	no, material	3.1MB	2.9MB	6.2
Montréal VM05	56MB	42MB	yes	5.7MB	5.4MB	7.8
New York LoD2 (DA13)	590MB	574MB	no	110MB	105MB	5.5
Rotterdam Delfshaven	16MB	15MB	yes	2.8MB	2.6MB	5.4
Vienna	37MB	36MB	no	5.6MB	5.3MB	6.8

One example: Zürich LoD2 buildings



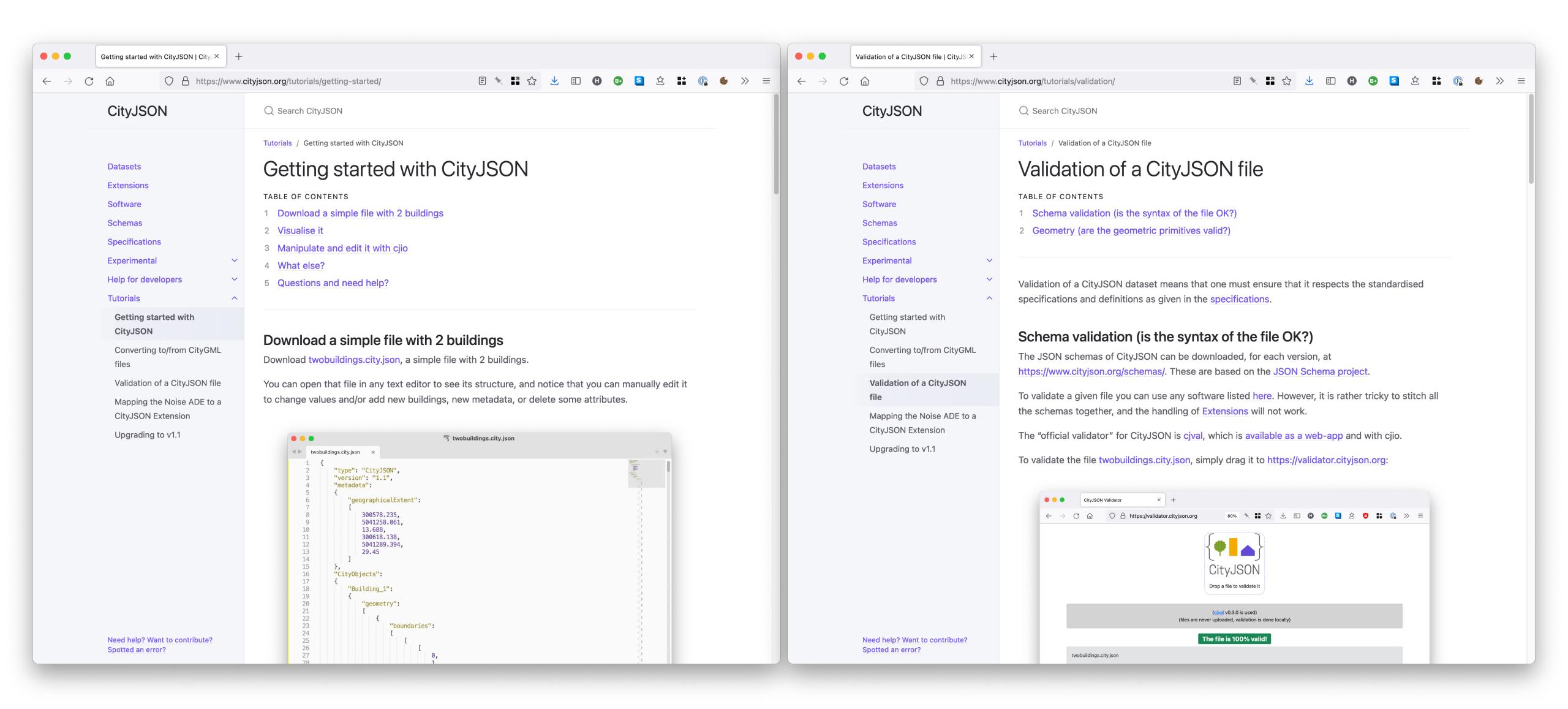
CityGML = 3.0GB

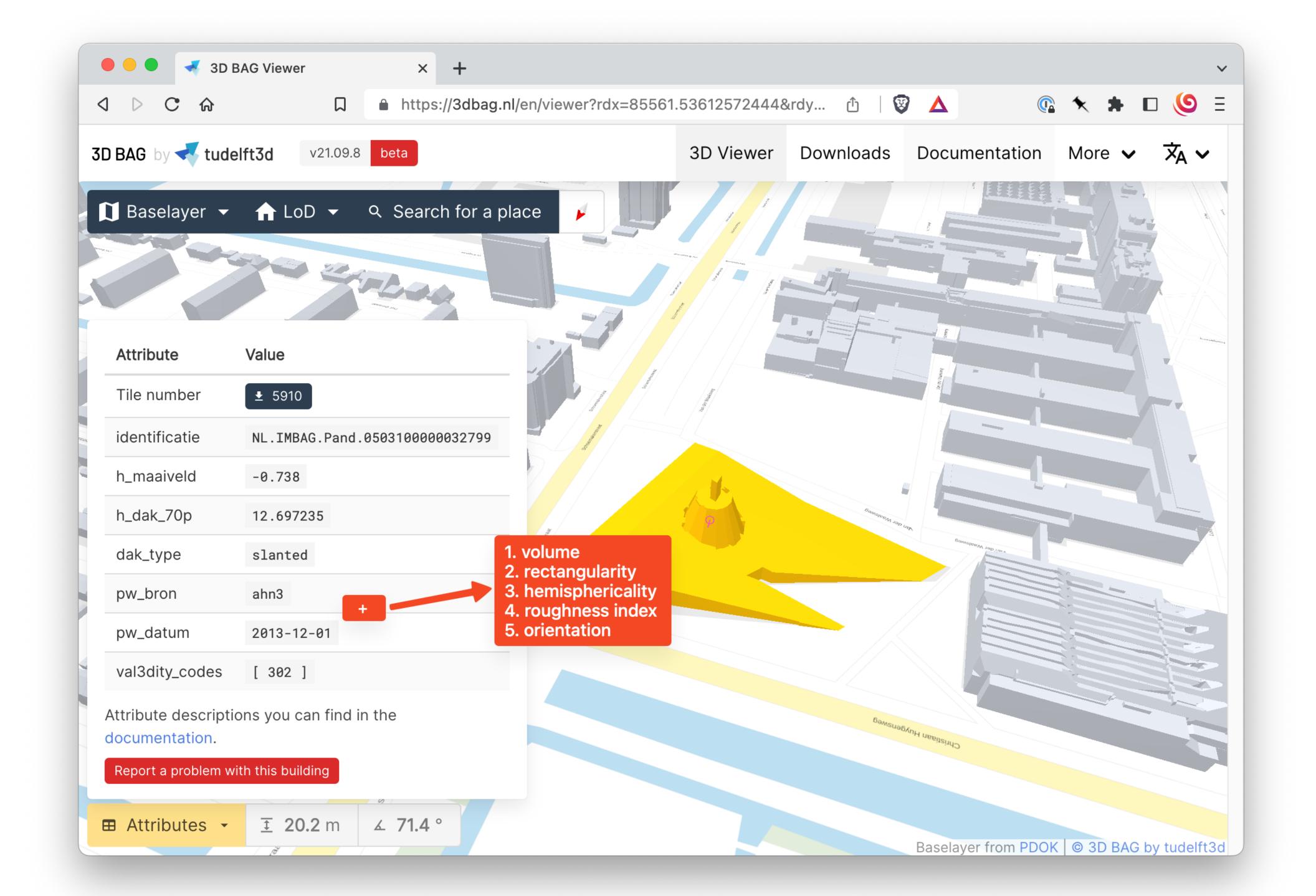
(but 1GB of spaces/CRs/tabs!)

CityJSON = 292MB

Compression == 7.1X

Getting started?





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RESEARCH ARTICLE





3D building metrics for urban morphology

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^a3D Geoinformation Group, Delft University of Technology, Delft, The Netherlands; ^bDepartment of Architecture, National University of Singapore, Singapore, Singapore; ^cDepartment of Real Estate, National University of Singapore, Singapore, Singapore

ABSTRACT

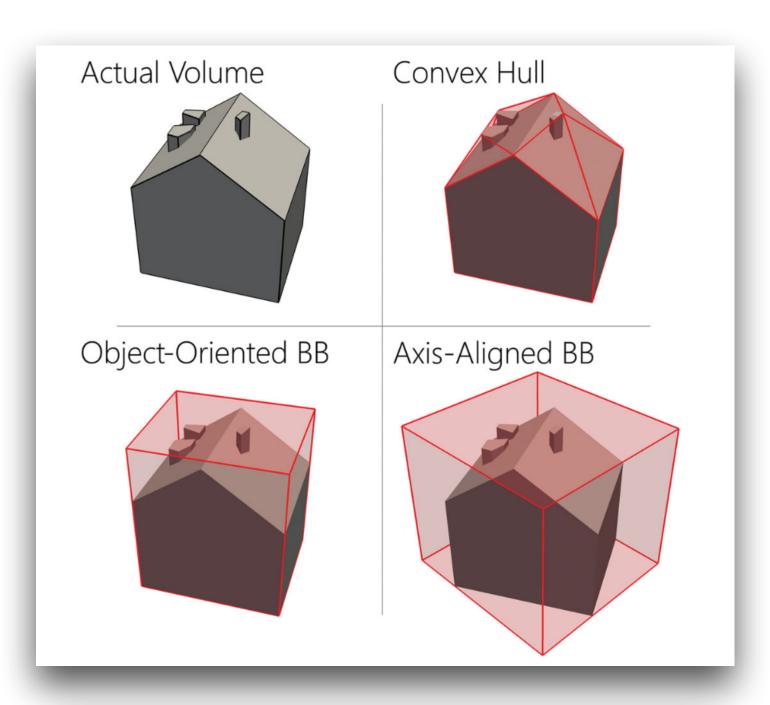
Urban morphology is important in a broad range of investigations across the fields of city planning, transportation, climate, energy, and urban data science. Characterising buildings with a set of numerical metrics is fundamental to studying the urban form. Despite the rapid developments in 3D geoinformation science, and the growing 3D data availability, most studies simplify buildings to their 2D footprint, and when taking their height into account, they at most assume one height value per building, i.e. simple 3D. We take the first step in elevating building metrics into full/true 3D, uncovering the use of higher levels of detail, and taking into account the detailed shape of a building. We set the foundation of the new research line on 3D urban morphology by providing a comprehensive set of 3D metrics, implementing them in openly released software, generating an open dataset containing 2D and 3D metrics for 823,000 buildings in the Netherlands, and demonstrating a use case where clusters and architectural patterns are analysed through time. Our experiments suggest the added value of 3D metrics to complement existing counterparts, reducing ambiguity, and providing advanced insights. Furthermore, we provide a comparative analysis using different levels of detail of 3D building models.

ARTICLE HISTORY

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KEYWORDS

3D GIS; urban fabric; urban modelling; morphometrics; urban indicators



Index	2D	3D
Circularity/Hemisphericality	$CI = rac{A_PN}{A_EPC} = rac{4\pi A_PN}{P_PN^2}$	$HEM = \frac{3\sqrt{2\pi}V}{4^{\frac{3}{2}}}$
Convexity	$CNV_2 = \frac{A_{PN}}{A_{CH}}$	$CNV_3 = \frac{V_{MS}^{\overline{Z}}}{V_{CH}}$
Fractality	$FR_2 = 1 - rac{\log{(A_{PN})}}{2 imes \log{(P_{PN})}}$	$FR_3 = 1 - \frac{\log(V_{MS})}{\frac{3}{2} \times \log(A_{MS})}$
Rectangularity/Cuboidness	$REC = rac{A_PN}{A_MABR}$	$CBD = \frac{V_{MS}}{V_{OOBB}}$
Squareness/Cubeness	$SQN = rac{ ho_{EAC}}{ ho_{PN}} = rac{4\sqrt{A_{PN}}}{ ho_{PN}}$	$CBN = \frac{A_{EVS}}{A_{MS}} = \frac{6\sqrt[3]{V_{MS}}^2}{A_{MS}}$
Cohesion	$nCl_2 = rac{0.9054 imes \sqrt{rac{A_{ ext{PN}}}{\pi}}}{rac{1}{n(n-1)} \sum_{i=1}^n \sum_{j=1}^n d_{ ext{lgp}_{ij}}}$	$nCl_3 = \frac{\frac{\frac{36}{35} \times \sqrt[3]{\frac{3^V_{\text{MS}}}{4 \pi}}}{\frac{1}{n(n-1)} \sum_{i=1}^n \sum_{j=1}^n d_{\text{igp}_{ij}}} d_{\text{igp}_{ij}}}$
Proximity	$nPxl_2 = rac{rac{2}{3} xr_EAC}{\mu_figp} = rac{rac{2}{3} x \sqrt{rac{A_PN}{\pi}}}{\mu_figp}$	$nPxI_3 = \frac{\frac{3}{4} \times r_{EVS}}{\mu_{r_{lgp}}} = \frac{\frac{3}{4} \times \sqrt[3]{\frac{3 V_{MS}}{4 \pi}}}{\mu_{r_{lgp}}}$
Exchange	$nEl_2 = \frac{A_{(PN \cap EAC)}}{A_1}$	$nEI_3 = \frac{V_{(MS \cap EVS)}}{V_{MS}}$
Spin	$nSI_2 = \frac{0.5 \times \frac{A_{PN}}{\pi}}{\mu_{r_{DD}}}$	$nSI_3 = \frac{\frac{3}{5} \times \sqrt[3]{\frac{3 \times V_{MS}}{4 \times \pi}}}{\mu_{r_2}}$
Perimeter/Circumference	$nPml_2 = rac{P_{EAC}}{P_{PN}} = rac{2\sqrt{\pi A_{PN}}}{P_{PN}}$	$ \text{nEI}_{3} = \frac{V_{\text{MS} \cap \text{EVS}}}{V_{\text{MS}}} $ $ \text{nSI}_{3} = \frac{\frac{3}{5} \times \sqrt[3]{3 \times V_{\text{MS}}^{2}}}{\mu_{r_{2}}} $ $ \text{nPmI}_{3} = \frac{4\pi \times \sqrt[3]{3 \times V_{\text{MS}}^{2}}}{A_{\text{MS}}} $
Depth	$nDpl_2 = rac{\mu_{PN_{d_{igp,b}}}}{\mu_{EAC_{d_{igp,b}}}} = rac{3\mu_{PN_{d_{igp,b}}}}{\sqrt{rac{\Lambda_{PN}}{\pi}}}$	$nDpl_3 = rac{4 imes \mu_{MS_{d_{idgp,b}}}}{\sqrt[3]{rac{3 imes V_{MS}}{4 imes \pi}}}$
Girth	$nGI_2 = \frac{r_{LIC}}{r_{EAC}} = \frac{r_{LIC}}{\sqrt{\frac{A_{PN}}{\pi}}}$	$nGI_3 = \frac{\mathit{r}_{LIS}}{\sqrt[3]{\frac{3 \times \mathit{V}_{MS}}{4 \times \pi}}}$
Dispersion	$nDsl_2 = 1 - rac{\mu_{r_{dev}}}{r_{ADC}} = 1 - rac{\mu_{r_{dev}}}{\mu_{r_{lbp}}}$	$ ext{nDsI}_3 = 1 - rac{\mu_{ ext{r}_{ ext{dev}}}}{r_{ ext{ADS}}} = 1 - rac{\mu_{ ext{r}_{ ext{dl}}}}{\mu_{ ext{r}_{ ext{lk}}}}$
Range	$nRl_2 = rac{r_EAC}{r_SCC} = rac{\sqrt{rac{eta_PN}{\pi}}}{r_SCC}$	$ nRI_3 = \frac{\sqrt[3]{\frac{3 \times V_{MS}}{4 \times \pi}}}{r_{SCS}} $ $ ECI = \sqrt[3]{\frac{V_{NOBB}}{V_{OOBB}}} \times \frac{A_{OOBB}}{A_{MS}} $
Equivalent rectangular/ cuboid index	$(1) \ k = \sqrt{\frac{A_{PN}}{A_{MABR}}} (k \le 1)$	$ECI = \sqrt[3]{\frac{V_{MS}}{V_{OOBB}}^2} \times \frac{A_{OOBB}}{A_{MS}}$
	$(2) P_{EAR} = k \times P_{MABR}$	
	(3) ERI $= rac{ ho_{EAR}}{ ho_{PN}} = \sqrt{rac{A_{PN}}{A_{MABR}}} imes rac{ ho_{MABR}}{ ho_{PN}}$	
Roughness index*	$RI_2 = \frac{\mu_{f_lbp}^2}{A_PN + P_PN^2} \times 42.62$	$RI_3 = \frac{\mu_{r_{\text{libp}}}^3}{V_{Mc} + \sqrt{A_{Mc}}^3} \times 48.735$
Elongation	$1-\frac{5}{L}$ (Computed for the three axes respectively)	- mu + V - mu
Form factor	-	$\frac{A}{V^{\frac{2}{3}}}$

How to calculate the volume of a (invalid) solid



Area of polygon

Vector primer Main geometric algorithms

Area of a simple polygon 1/2

Let P be a simple polygon (no boundary self-intersections) with vertex vectors

$$P = ((x_1, y_1), (x_2, y_2), ..., (x_n, y_n))$$

where $(x_1, y_1) = (x_n, y_n)$

Then the area of the polygon P is

area(P) =
$$\frac{1}{2} \sum_{i=1}^{n-1} x_i y_{i+1} - x_{i+1} y_i$$

In the case of a triangle pqr

area of 1 triangle



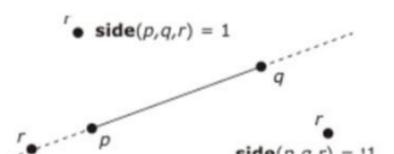
14

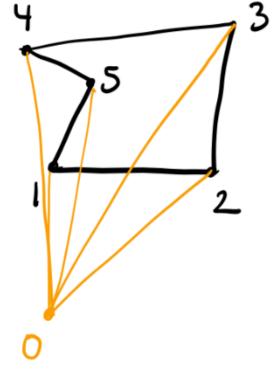
Area of polygon

Area of a simple polygon 2/2

- Note that the area may be positive or negative, in fact area(pqr) = -area(qpr)
- If p is to the left of qr then the area is positive, if p is to the right of qr then the area is negative

$$\mathbf{side}(p,q,r) = \left\{ \begin{array}{ll} 1 & \text{if } \mathbf{area}(pqr) > 0 & (p \text{ is left of } qr) \\ 0 & \text{if } \mathbf{area}(pqr) = 0 & (pqr \text{ are collinear}) \\ -1 & \text{if } \mathbf{area}(pqr) < 0 & (p \text{ is right of } qr) \end{array} \right.$$





13.1 Conversions for fields | 129

Inverse distance weighting (IDW). The generalisation of this method to three dimensions is straightforward: a searching *sphere* with a given radius is used. The same problems with the one-dimensionality of the method (the value for the search radius) will be even worse because the search must be performed in one more dimension. The method has too many problems to be considered has a viable solution for fields as found in geosciences: the interpolant is not guaranteed to be continuous, especially when the dataset has an anisotropic distribution, and the criterion has to be selected carefully by the user. Note that the implementation problems are also similar to the ones encountered with the previous method, and an auxiliary data structure must be used to avoid testing all the points in a dataset.

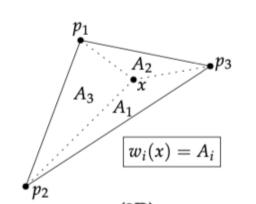
Linear interpolation in tetrahedra. This is the generalisation of the popular linear interpolation in TINs where the tetrahedra of the Delaup tetrahedralisation (DT) are used. The barycentric coordinates can be sed to linearly interpolate inside a tetrahedron, as shown in Figure 3.3 the volumes of 4 tetrahedra are used (instead of the area for the ** case.)

The volume of a *d*-simplex σ is easily computed:

$$vol(\sigma) = \frac{1}{d!} \left| \det \begin{pmatrix} v^0 & \cdots & v^d \\ 1 & \cdots & 1 \end{pmatrix} \right|$$
 (13.1)

where v^i is a d-dimensional vector representing the coordinates of a vertex and det() is the determinant of the matrix.

anisotropic distribution



Vector primer Main geometric algorithms

How to calculate the volume of a (invalid) solid

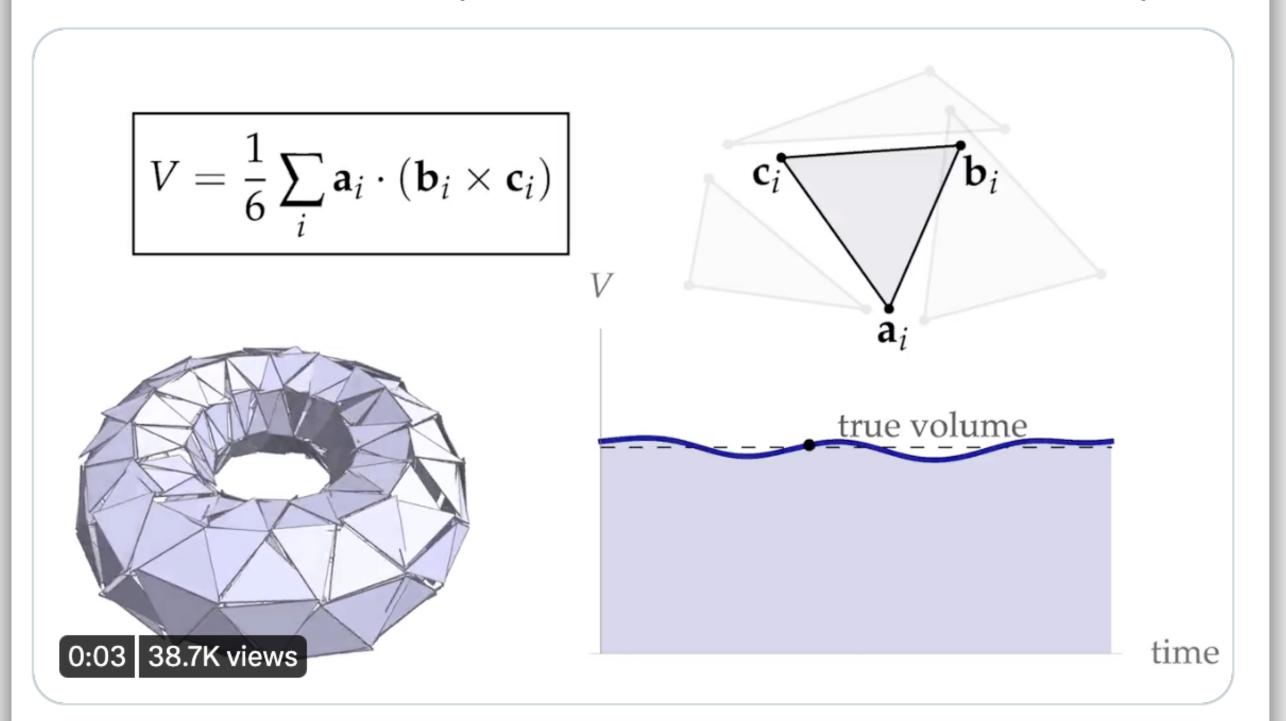


Need the volume of a broken triangle mesh?

Don't bother fixing it.

Just sum over all triangles (a_i, b_i, c_i) the dot product of one vertex with the cross product of the other two, and divide by 6.

[Caveat: all normals must point out. Works even for nonconvex shapes!]





Keenan Crane @keenanisalive · 22 Nov 2022

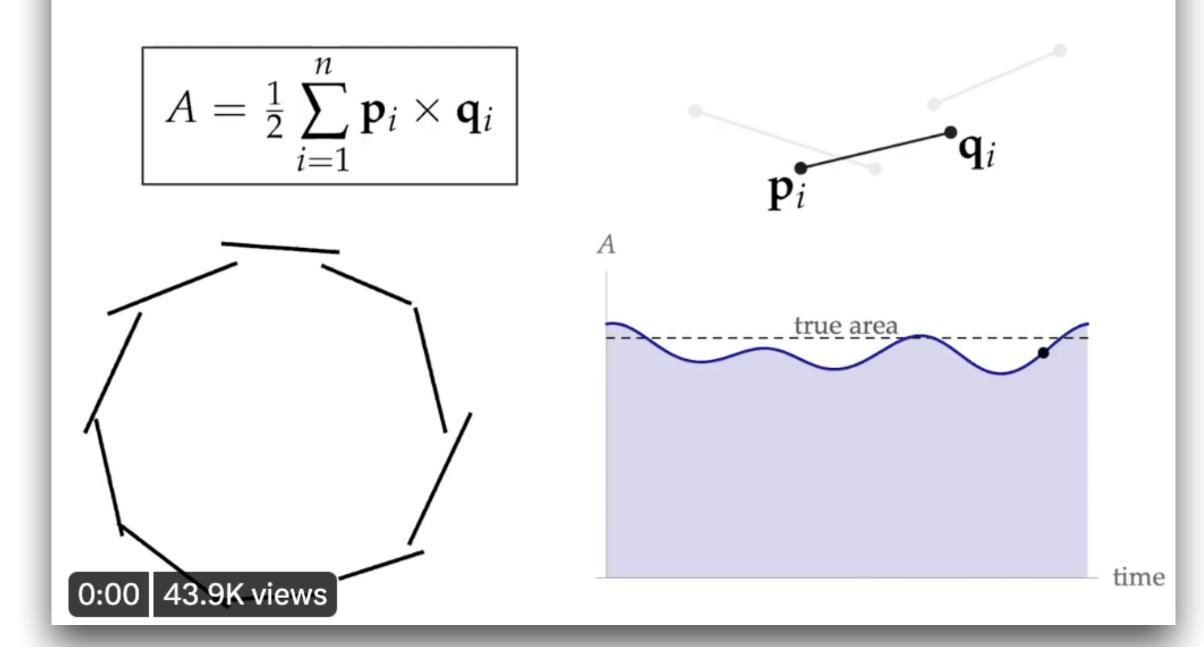
Need the area of a broken polygon?

Don't bother fixing it.

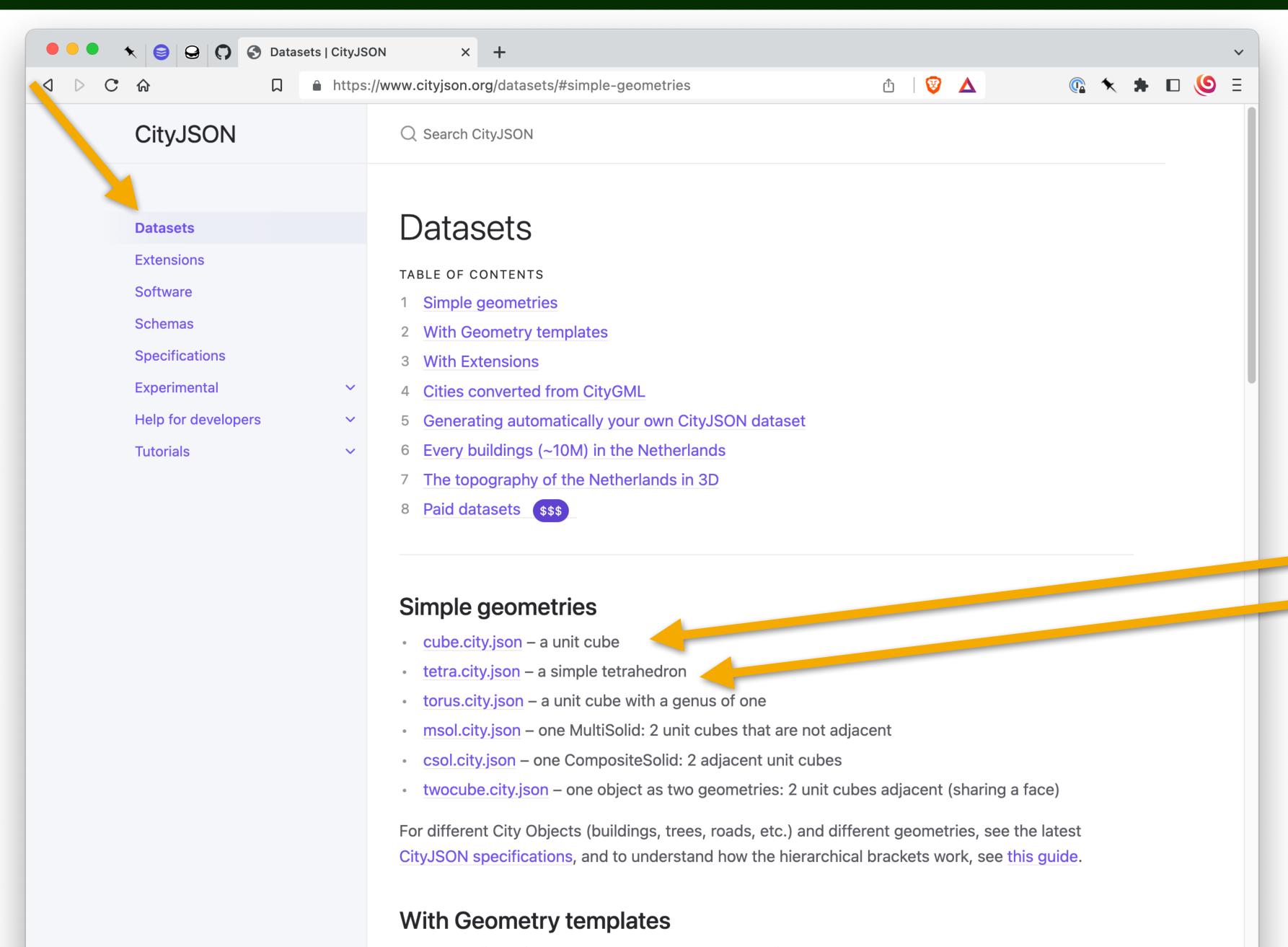
Just sum up the cross product of the two endpoints, and divide by two.

[Here $u \times v := u_1v_2 - u_2v_1$. Works even if the polygon is nonconvex. Caveat: all segments must point counter-clockwise, since $u \times v = -v \times v$ u!]

Show this thread



Tip: start with simple shapes, not BK-City...



Download and modify those